

## Question 1

The correct answers are:

(a) (2)

(b) (3)

(c) (1)

(d) (2)

(e) (3)

(f) (2)

(g) (3)

(h) (1)

## Question 2

- (a) Any probability measure  $Q \approx P$  can be specified by four parameters  $q_{\uparrow\uparrow}, q_{\downarrow\uparrow}, q_{\uparrow\downarrow}, q_{\downarrow\downarrow}$  (with the obvious interpretation), which must all be strictly between 0 and 1. Moreover, for this probability measure to be an EMM for  $S^1$  and  $S^2$  the following conditions must be satisfied

$$\begin{aligned} q_{\uparrow\uparrow} + q_{\downarrow\uparrow} + q_{\uparrow\downarrow} + q_{\downarrow\downarrow} &= 1, \\ (1 + u_1)q_{\uparrow*} + (1 + d_1)q_{\downarrow*} &= 1 + r, \\ (1 + u_2)q_{* \uparrow} + (1 + d_2)q_{* \downarrow} &= 1 + r, \end{aligned}$$

where  $q_{\uparrow*} = q_{\uparrow\uparrow} + q_{\uparrow\downarrow}$ ,  $q_{\downarrow*} = q_{\downarrow\uparrow} + q_{\downarrow\downarrow}$ ,  $q_{* \uparrow} = q_{\uparrow\uparrow} + q_{\downarrow\uparrow}$  and  $q_{* \downarrow} = q_{\uparrow\downarrow} + q_{\downarrow\downarrow}$ . The first and the second equation let us solve explicitly

$$q_{\uparrow*} = \frac{r - d_1}{u_1 - d_1}, \quad q_{\downarrow*} = \frac{u_1 - r}{u_1 - d_1}$$

and similarly the first with the third give

$$q_{* \uparrow} = \frac{r - d_2}{u_2 - d_2}, \quad q_{* \downarrow} = \frac{u_2 - r}{u_2 - d_2}.$$

For these to be positive we already require  $u_1 > r > d_1, u_2 > r > d_2$ . Using a parameter  $q_{\uparrow\uparrow} =: a$ , we get

$$q_{\downarrow\uparrow} = \frac{r - d_2}{u_2 - d_2} - a, \quad q_{\uparrow\downarrow} = \frac{r - d_1}{u_1 - d_1} - a \quad \text{and} \quad q_{\downarrow\downarrow} = 1 - \frac{r - d_2}{u_2 - d_2} - \frac{r - d_1}{u_1 - d_1} + a.$$

Given the conditions we already have, it is clear that this leads to a well-defined equivalent measure only if

$$a \in \left( \max \left( 0, \frac{r - d_2}{u_2 - d_2} + \frac{r - d_1}{u_1 - d_1} - 1 \right), \min \left( \frac{r - d_1}{u_1 - d_1}, \frac{r - d_2}{u_2 - d_2} \right) \right).$$

So we have established that for no arbitrage to occur,  $u_1 > r > d_1, u_2 > r > d_2$  must hold and  $a$  must belong to the given interval, and moreover the entire measure is then specified by the formulas above. Conversely, we can check that any such  $a$  generates an EMM. This interval thus describes all EMMs for  $S^1$  and  $S^2$ . Moreover, the interval is non-empty if and only if the four inequalities hold

$$\begin{aligned} \frac{r - d_2}{u_2 - d_2} &> 0, & \frac{r - d_1}{u_1 - d_1} &> 0 \\ \frac{r - d_2}{u_2 - d_2} &> \frac{r - d_2}{u_2 - d_2} + \frac{r - d_1}{u_1 - d_1} - 1 \\ \frac{r - d_1}{u_1 - d_1} &> \frac{r - d_2}{u_2 - d_2} + \frac{r - d_1}{u_1 - d_1} - 1 \end{aligned}$$

These are all true as long as  $0 < \frac{r - d_i}{u_i - d_i} < 1$ , which in turn is implied by  $d_i < r < u_i$ . Therefore these conditions are also sufficient for absence of arbitrage.

- (b) Since the market is arbitrage-free by assumption, there exists an EMM for  $(S^0, S^1, S^2)$  by the fundamental theorem of asset pricing. The same EMM is therefore an EMM for both  $(S^0, S^1)$  and  $(S^0, S^2)$ , which means again by the fundamental theorem of asset pricing that both of these markets are arbitrage-free. But both of these markets are simple binomial markets so they are also complete. We can thus hedge  $f(\tilde{S}_1^1)$  by trading only in  $\tilde{S}^1$ . We do this by finding an initial value  $c_1$  and a trading strategy  $\theta_1$  such that

$$c_1 + \theta_1(\tilde{S}_1^1 - \tilde{S}_0^1) = f(\tilde{S}_1^1) \quad P\text{-a.s.},$$

since we assume  $r = 0$ . This gives equations

$$\begin{aligned} c_1 + \theta_1 u_1 &= f(1 + u_1), \\ c_1 + \theta_1 d_1 &= f(1 + d_1), \end{aligned}$$

which can indeed be solved with

$$\theta_1 = \frac{f(1+u_1) - f(1+d_1)}{u_1 - d_1},$$

$$c_1 = \frac{u_1 f(1+d_1) - d_1 f(1+u_1)}{u_1 - d_1}.$$

Analogously, we can hedge  $g(\tilde{S}_1^2)$  by trading in  $\tilde{S}^2$  only, and then add up the hedging strategies. In the specific case given, we have that

$$\theta_1 = \frac{f(1+u_1) - f(1+d_1)}{u_1 - d_1} = \frac{1.2^2 - 0.8^2}{0.4} = 2,$$

$$\theta_2 = \frac{g(1+u_2) - g(1+d_2)}{u_2 - d_2} = \frac{0 - (-0.3)}{0.9} = \frac{1}{3},$$

$$c_1 + c_2 = V_0(\tilde{H}) = \frac{u_1 f(1+d_1) - d_1 f(1+u_1)}{u_1 - d_1} + \frac{u_2 g(1+d_2) - d_2 g(1+u_2)}{u_2 - d_2}$$

$$= \frac{0.2 \times 1.2^2 + 0.2 \times 0.8^2}{0.4} + \frac{0.6 \times (-0.3) + 0.3 \times 0}{0.9} = 1.04 - 0.2 = 0.84.$$

(c) Using that  $r = 0$ , we obtain

$$E_Q[\tilde{H}] = q_{*\uparrow}(1.6) + q_{\uparrow\downarrow}(1.2) + q_{\downarrow\downarrow}(0.8)$$

$$= \frac{0.3}{0.9} \times 1.6 + \left( \frac{0.2}{0.4} - a \right) \times 1.2 + \left( 1 - \frac{0.3}{0.9} - \frac{0.2}{0.4} + a \right) \times 0.8$$

$$= \frac{19}{15} - \frac{2}{5}a.$$

One can see that the interval for  $a$  in this setting is given by  $(0, \frac{1}{3})$  and so the expectations under EMMs form the set

$$\Pi(\tilde{H}) = \left( \frac{17}{15}, \frac{19}{15} \right).$$

In particular, this set is not a singleton, so according to Theorem 1.2 on page 49 in the lecture notes,  $\tilde{H}$  is not attainable.

### Question 3

- (a) Since  $Q \approx P$ , we know that  $Z > 0$   $P$ -a.s. by Radon–Nikodým theorem. Therefore also  $\frac{1}{Z} > 0$   $P$ -a.s. As a continuous transformation of an adapted process  $Z$ ,  $\frac{1}{Z}$  is adapted. We also have by Lemma 3.1 in chapter 3 of the lecture notes and the adaptedness of  $\frac{1}{Z}$  that

$$E_Q \left[ \left[ \frac{1}{Z_k} \right] \right] = E_Q \left[ \frac{1}{Z_k} \right] = E_P \left[ Z_k \frac{1}{Z_k} \right] = 1$$

for all  $k \in \{0, 1, \dots, T\}$ . This gives the  $Q$ -integrability of  $\frac{1}{Z}$  as well as the fact that

$$E_Q \left[ \frac{1}{Z_0} \right] = 1.$$

Additionally, we have by the Bayes formula from Lemma 3.1 in chapter 3 of the lecture notes and again by the adaptedness of  $\frac{1}{Z}$  that

$$E_Q \left[ \frac{1}{Z_k} \middle| \mathcal{F}_{k-1} \right] = E_P \left[ \frac{Z_k}{Z_{k-1}} \frac{1}{Z_k} \middle| \mathcal{F}_{k-1} \right] = E_P \left[ \frac{1}{Z_{k-1}} \middle| \mathcal{F}_{k-1} \right] = \frac{1}{Z_{k-1}}$$

for all  $k \in \{0, 1, \dots, T\}$ . So  $\frac{1}{Z}$  is a strictly positive  $Q$ -martingale with  $E_Q \left[ \frac{1}{Z_0} \right] = 1$ . Since  $A \in \mathcal{F}_k$  and because  $\frac{1}{Z}$  is adapted, the random variable  $\frac{1}{Z_k} \mathbf{1}_A$  is  $\mathcal{F}_k$ -measurable and we have again by the Lemma 3.1 in chapter 3 of the lecture notes

$$E_Q \left[ \frac{1}{Z_k} \mathbf{1}_A \right] = E_P \left[ Z_k \frac{1}{Z_k} \mathbf{1}_A \right] = E_P [\mathbf{1}_A] = P[A].$$

- (b) Let  $\eta := \tau \wedge \sigma = \min\{\tau, \sigma\}$ . Then we have for all  $k \in \{0, 1, \dots, T\}$

$$\begin{aligned} \{\eta \leq k\} &= \{\min\{\tau, \sigma\} \leq k\} = \{\omega \in \Omega \text{ such that } \tau(\omega) \leq k \text{ or } \sigma(\omega) \leq k\} \\ &= \{\tau \leq k\} \cup \{\sigma \leq k\} \in \mathcal{F}_k, \end{aligned}$$

since  $\tau$  and  $\sigma$  are  $\mathbb{F}$ -stopping times by assumption and  $\sigma$ -algebras are closed under countable unions.

- (c) We know from (b) that if  $\sigma_n$  is an  $\mathbb{F}$ -stopping time for all  $n \in \mathbb{N}$  then  $\tau_n \wedge \sigma_n$  is an  $\mathbb{F}$ -stopping time as well. Since  $\tau_n \uparrow T$   $P$ -a.s. by assumption, it is first enough to show that  $\sigma_n$  is an  $\mathbb{F}$ -stopping time for all  $n \in \mathbb{N}$  and that  $\sigma_n \uparrow T$   $P$ -a.s. The latter is clear from the very definition of  $\sigma_n$ . In order to show that  $\sigma_n$  is an  $\mathbb{F}$ -stopping time, we have

$$\begin{aligned} \{\sigma_n \leq k\} &= \{\omega \in \Omega \text{ such that } |\vartheta_l| > n \text{ for some } l \in \{0, 1, \dots, k+1\}\} \\ &= \bigcup_{l=1}^{k+1} \{|\vartheta_l| > n\} \in \mathcal{F}_k \end{aligned}$$

by the fact that  $\vartheta$  is  $\mathbb{F}$ -predictable and that  $\sigma$ -algebras are closed under countable unions.

In order to show that  $X^{\tau_n \wedge \sigma_n}$  is a  $(P, \mathbb{F})$ -martingale for all  $n \in \mathbb{N}$  we use the fact that a stopped martingale is a martingale (which has been proved in one of the exercise sheets) and that  $X^{\tau_n}$  is a  $(P, \mathbb{F})$ -martingale since  $(\tau_n)_{n \in \mathbb{N}}$  is a localizing sequence for  $X$ . Denoting  $Y = X^{\tau_n}$  we indeed we have for  $k \in \{0, 1, \dots, T\}$  that

$$X_k^{\tau_n \wedge \sigma_n} = X_{\tau_n \wedge \sigma_n \wedge k} = X_{\sigma_n \wedge k}^{\tau_n} = Y_{\sigma_n \wedge k} = Y_k^{\sigma_n}.$$

- (d) Let us denote  $\rho_n := \tau_n \wedge \sigma_n$ . Then we have for all  $n \in \mathbb{N}$  and  $k \in \{0, 1, \dots, T\}$  that

$$(\vartheta \cdot X)_{\rho_n \wedge k} = \sum_{j=1}^{\rho_n \wedge k} \vartheta_j (X_j - X_{j-1}) = \sum_{j=1}^k \vartheta_j (X_{\rho_n \wedge j} - X_{\rho_n \wedge (j-1)}) = (\vartheta \cdot X^{\rho_n})_k.$$

But  $X^{\rho_n}$  is a  $(P, \mathbb{F})$ -martingale for all  $n \in \mathbb{N}$  and  $|\vartheta_j| \leq n$  for all  $j \leq \rho_n$  and

$$X_{\rho_n \wedge j} - X_{\rho_n \wedge (j-1)} = 0 \text{ for all } j > \rho_n,$$

so we have for all  $k \in \{0, 1, \dots, T\}$  that

$$\begin{aligned} E [ |(\vartheta \cdot X)_{\rho_n \wedge k}| ] &= E \left[ \left| \sum_{j=1}^k \vartheta_j (X_{\rho_n \wedge j} - X_{\rho_n \wedge (j-1)}) \right| \right] \leq \sum_{j=1}^k E [ |\vartheta_j| |X_{\rho_n \wedge j} - X_{\rho_n \wedge (j-1)}| ] \\ &= \sum_{j=1}^k E [ |\vartheta_j| |X_{\rho_n \wedge j} - X_{\rho_n \wedge (j-1)}| \mathbf{1}_{\{j \leq \rho_n\}} ] \\ &\leq \sum_{j=1}^k n E [ |X_{\rho_n \wedge j} - X_{\rho_n \wedge (j-1)}| \mathbf{1}_{\{j \leq \rho_n\}} ] \leq \sum_{j=1}^k n E [ |X_{\rho_n \wedge j} - X_{\rho_n \wedge (j-1)}| ] \\ &\leq \sum_{j=1}^k n (E [ |X_{\rho_n \wedge j}| ] + E [ |X_{\rho_n \wedge (j-1)}| ]) < \infty, \end{aligned}$$

which is the integrability of  $(\vartheta \cdot X)^{\rho_n}$ . We also have for all  $n \in \mathbb{N}$  and  $k \in \{1, \dots, T\}$  that

$$\begin{aligned} E [ (\vartheta \cdot X)_{\rho_n \wedge k} - (\vartheta \cdot X)_{\rho_n \wedge (k-1)} \mid \mathcal{F}_{k-1} ] &= E [ \vartheta_{k-1} (X_{\rho_n \wedge k} - X_{\rho_n \wedge (k-1)}) \mid \mathcal{F}_{k-1} ] \\ &= E [ \vartheta_{k-1} (X_{\rho_n \wedge k} - X_{\rho_n \wedge (k-1)}) \mathbf{1}_{\{k \leq \rho_n\}} \mid \mathcal{F}_{k-1} ] \\ &= \mathbf{1}_{\{k \leq \rho_n\}} \vartheta_{k-1} E [ X_{\rho_n \wedge k} - X_{\rho_n \wedge (k-1)} \mid \mathcal{F}_{k-1} ] = 0, \end{aligned}$$

where the third equality follows from the fact that  $|\vartheta_k \mathbf{1}_{\{k \leq \rho_n\}}| \leq n$  is bounded and

$$\{\rho_n \geq k\} = \{\rho_n > k-1\} = \{\rho_n \leq k-1\}^C \in \mathcal{F}_{k-1}.$$

Adaptedness is clear since  $(\vartheta \cdot X)_k^{\rho_n}$  is a sum of products of  $\mathcal{F}_k$ -measurable random variables so we conclude that  $(\vartheta \cdot X)^{\rho_n}$  is a  $(P, \mathbb{F})$ -martingale for all  $n \in \mathbb{N}$ , which shows that  $(\rho_n)_{n \in \mathbb{N}}$  is a localizing sequence for  $(\vartheta \cdot X)$ .

#### Question 4

- (a)  $BW$  is adapted since  $B$  and  $W$  are. By independence,  $E[|B_t W_t|] = E[|B_t|]E[|W_t|] < \infty$  since  $B, W$  are integrable. Finally,

$$\begin{aligned} E[B_t W_t | \mathcal{F}_s] &= E[(B_t - B_s + B_s)(W_t - W_s + W_s) | \mathcal{F}_s] \\ &= E[(B_t - B_s)(W_t - W_s)] + B_s W_s \\ &= B_s W_s, \end{aligned}$$

where the last equality follows from the independence of the increments of  $W$  and  $B$ . Thus  $BW$  is a  $(P, \mathbb{F})$ -martingale. Alternatively, this can also be shown using the product rule and arguing that the stochastic integrals that show up are indeed martingales.

- (b)  $\mathcal{M}_0^2$  is the space of martingales  $M$  null at 0 with  $\sup_{t \geq 0} E[M_t^2] < \infty$ .

Note that we clearly have for all  $t \geq 0$  that

$$X_t^T = \left( \int_0^t s dW_s \right)^T + B_t^T$$

Since every deterministic time is also an  $\mathbb{F}$ -stopping time, we can apply the *behavior under stopping* property of stochastic integrals from page 89 in the lecture notes to obtain that

$$X_t^T = \int_0^t s dW_s^T + B_t^T$$

For each  $T > 0$ ,  $B^T \in \mathcal{M}_0^2$  since  $E[(B_t^T)^2] = t \wedge T \leq T < \infty$ . On the other hand, by the properties of stochastic integrals  $(\int_0^\cdot s dW_s^T) \in \mathcal{M}_0^2$  since the process  $H = (H_s)_{s \geq 0}$  defined by  $H_s := s$  is in  $L^2(W^T)$ , because it is clearly predictable since it is  $\mathbb{F}$ -adapted and continuous and

$$E \left[ \int_0^\infty s^2 d[W^T]_s \right] = E \left[ \int_0^\infty s^2 d(s \wedge T) \right] = E \left[ \int_0^T s^2 ds \right] = \frac{T^3}{3} < \infty.$$

Clearly, both summands are null at 0, thus  $X^T \in \mathcal{M}_0^2$ . Finally, applying Itô's formula to the  $C^2$ -function  $f(x) = x^2$  with  $f'(x) = 2x$ ,  $f''(x) = 2$  and the  $(P, \mathbb{F})$ -semimartingale  $X$ , together with the fact that

$$\begin{aligned} \langle X \rangle_t &= \left\langle \int_0^\cdot s dW_s + B \right\rangle_t = \left\langle \int_0^\cdot s dW_s \right\rangle_t + 2 \left\langle \int_0^\cdot s dW_s, B \right\rangle_t + \langle B \rangle_t \\ &= \int_0^t s^2 d\langle W \rangle_s + 2 \int_0^t s d\langle W, B \rangle_s + \langle B \rangle_t = \frac{t^3}{3} + t \end{aligned}$$

since  $\langle W \rangle_t = \langle B \rangle_t = t$ ,  $\langle W, B \rangle_t = 0$  (by the independence of  $W$  and  $B$ ), gives that

$$X_t^2 = 2 \int_0^t X_s dX_s + \langle X \rangle_t = 2 \int_0^t s X_s dW_s + 2 \int_0^t X_s dB_s + \frac{t^3}{3} + t.$$

- (c) Since  $X^T \in \mathcal{M}_0^2$ ,  $(X^T)^2 - [X]^T$  is a  $(P, \mathbb{F})$ -martingale. Since  $X$  is continuous, we have that  $[X]_t = \langle X \rangle_t$  so by (b) we get that

$$\begin{aligned} E[(X_T)^2 | \mathcal{F}_t] &= X_t^2 + E[[X]_T - [X]_t | \mathcal{F}_t] = X_t^2 + \frac{T^3 - t^3}{3} + (T - t) \\ &= T + \frac{T^3}{3} + 2 \int_0^t s X_s dW_s + 2 \int_0^t X_s dB_s. \end{aligned}$$

- (d) The measure  $Q$  with  $\frac{dQ}{dP} = Z_T$  is a probability measure equivalent to  $P$  on  $\mathcal{F}_T$  since

$$\frac{dQ}{dP} = \mathcal{E}(\alpha B + \beta W)_T = \exp \left( \alpha B_T + \beta W_T - \frac{\alpha^2 + \beta^2}{2} T \right)$$

is finite and strictly positive  $P$ -a.s., and  $E_P[Z_T] = E_P[Z_0] = 1$  since  $Z$  is a  $(P, \mathbb{F})$ -martingale. By Girsanov's theorem, since  $W$  and  $B$  are two independent  $(P, \mathbb{F})$ -Brownian motions and noting that

$$\begin{aligned} [B, \alpha B + \beta W]_t &= \alpha[B, B]_t + [B, W]_t = \alpha[B]_t = \alpha t, \\ [W, \alpha B + \beta W]_t &= [W, B]_t + \beta[W, W]_t = \beta[W]_t = \beta t, \end{aligned}$$

we get that  $\tilde{B}$  and  $\tilde{W}$  are  $(Q, \mathbb{F})$ -Brownian motions.

Finally, we can rewrite  $X^2$  as

$$\begin{aligned} X_t^2 &= 2 \int_0^t s X_s dW_s + 2 \int_0^t X_s dB_s + \frac{t^3}{3} + t \\ &= 2 \int_0^t s X_s d\tilde{W}_s + 2 \int_0^t X_s d\tilde{B}_s + 2 \int_0^t (\beta s + \alpha) X_s ds + \frac{t^3}{3} + t. \end{aligned}$$

- (e) No. Notice that  $X_0^2 = 0$   $P$ -a.s., while  $X_t^2 \geq 0$   $P$ -a.s. and  $P[X_t^2 > 0] > 0$  for all  $t > 0$ . These conditions must hold under any equivalent measure  $Q^*$ , and if we additionally want  $X^2$  to be a  $(Q^*, \mathbb{F})$ -martingale, then we also need to have that  $E_{Q^*}[X_t^2] = E_{Q^*}[X_0^2] = 0$ . These two conditions are, however, not compatible, since if  $E_{Q^*}[X_t^2] = 0$ , then  $X_t^2 = 0$   $Q^*$ -a.s.

## Question 5

(a) By Fubini's theorem,

$$E \left[ \int_0^t W_s ds \right] = \int_0^t E[W_s] ds = 0$$

and

$$\begin{aligned} E \left[ \left( \int_0^t W_s ds \right)^2 \right] &= E \left[ \left( \int_0^t W_s ds \right) \left( \int_0^t W_u du \right) \right] = E \left[ \int_0^t \int_0^t W_s W_u ds du \right] \\ &= \int_0^t \int_0^t E[W_s W_u] ds du = \int_0^t \int_0^t (s \wedge u) ds du \\ &= \int_0^t \left( \frac{u^2}{2} + (t-u)u \right) du = \int_0^t \left( -\frac{u^2}{2} + tu \right) du = -\frac{t^3}{6} + \frac{t^3}{2} = \frac{t^3}{3}, \end{aligned}$$

where the fourth equality follows from the fact that for  $s \geq u$ , we have

$$\begin{aligned} E[W_s W_u] &= E[(W_s - W_u + W_u)W_u] = E[(W_s - W_u)W_u] + E[W_u^2] \\ &= E[W_s - W_u] E[W_u] + u = u \end{aligned}$$

and similarly for  $s < u$ ,  $E[W_s W_u] = s$ .

For the conditional distribution we can rewrite

$$\int_0^T W_s ds = \int_0^t W_s ds + (T-t)W_t + \int_t^T (W_s - W_t) ds.$$

The first two summands are  $\mathcal{F}_t$ -measurable, while  $(W_s - W_t)_{s \in [0, T]}$  is by the Markov property a new  $(P, \mathbb{F})$ -Brownian motion independent of  $\mathcal{F}_t$ . Therefore we can use the earlier calculations to compute the distribution as

$$\int_0^T W_s ds \sim \mathcal{N} \left( \int_0^t W_s ds + (T-t)W_t, \frac{(T-t)^3}{3} \right)$$

conditionally on  $\mathcal{F}_t$ .

(b) We compute

$$\begin{aligned} V_t &= E[H \mid \mathcal{F}_t] = P[A_t > K \mid \mathcal{F}_t] \\ &= P \left[ T \log(x) + \int_0^T \left( \sigma W_s - \frac{\sigma^2}{2} s \right) ds > T \log(K) \mid \mathcal{F}_t \right] \\ &= P \left[ \int_0^T W_s ds > \frac{T \log(K/x)}{\sigma} + \frac{T^2 \sigma}{4} \mid \mathcal{F}_t \right]. \end{aligned}$$

By (a) we know the conditional distribution of  $\int_0^T W_s ds$ , and we can write

$$\int_0^T W_s ds \stackrel{(d)}{=} \int_0^t W_s ds + (T-t)W_t + \frac{(T-t)^{\frac{3}{2}}}{\sqrt{3}} Z,$$

for  $Z \sim \mathcal{N}(0, 1)$  and independent of  $\mathcal{F}_t$ . Therefore we can write the above as

$$\begin{aligned} P \left[ \int_0^T W_s ds > \frac{T \log(K/x)}{\sigma} + \frac{T^2 \sigma}{4} \mid \mathcal{F}_t \right] &= \\ &= P \left[ \int_0^t W_s ds + (T-t)W_t + \frac{(T-t)^{\frac{3}{2}}}{\sqrt{3}} Z > \frac{T \log(K/x)}{\sigma} + \frac{T^2 \sigma}{4} \mid \mathcal{F}_t \right] \\ &= P \left[ Z > \frac{\sqrt{3}}{(T-t)^{\frac{3}{2}}} \left( \frac{T \log(K/x)}{\sigma} + \frac{T^2 \sigma}{4} - \int_0^t W_s ds - (T-t)W_t \right) \mid \mathcal{F}_t \right] \\ &= 1 - \Phi(X_t), \end{aligned}$$



as we wanted, using the aforementioned independence.

If instead we use that the conditional distribution of  $\int_0^T W_s ds$  given  $\mathcal{F}_t$  is  $\mathcal{N}(m_t, v_t^2)$  we still get  $V_t = 1 - \Phi(X_t)$  with  $X$  given in the generic form by

$$X_t = \frac{1}{v_t} \left( \frac{T \log(K/x)}{\sigma} + \frac{T^2 \sigma}{4} - m_t \right).$$

- (c) We can find the dynamics of  $\Phi(X)$  using Itô's formula. Note that  $X_t$  is a smooth function of  $t$ ,  $\int_0^t W_s ds$  and  $W_t$ . We know that  $V_t$  must be a  $(P, \mathbb{F})$ -martingale (by the tower law), and because all the terms are continuous, any continuous finite variation part must vanish. Note that  $t$  and  $\int_0^t W_s ds$  are finite variation processes, and so we only need to think about the derivative with respect to  $W_t$  (i.e., we know a priori that all the other terms must cancel out). Therefore that simply yields

$$\begin{aligned} V_t &= V_0 + \int_0^t dV_s = V_0 + \int_0^t -\Phi'(X_s) \left( -\frac{\sqrt{3}}{(T-s)^{\frac{1}{2}}} \right) dW_s \\ &= V_0 + \int_0^t \left( \frac{\sqrt{3} e^{-\frac{X_s^2}{2}}}{\sigma S_s \sqrt{2\pi(T-s)}} \right) dS_s \end{aligned}$$

giving

$$\theta_t = \left( \frac{\sqrt{3} e^{-\frac{X_t^2}{2}}}{\sigma S_t \sqrt{2\pi(T-t)}} \right)$$

and

$$V_0 = 1 - \Phi(X_0) = 1 - \Phi \left( \sqrt{3} \left( \frac{\log(K/x)}{\sigma \sqrt{T}} + \frac{\sqrt{T} \sigma}{4} \right) \right).$$