

# Planes in four space and four associated CM points

joint work with Menny Aka and Manfred Einsiedler

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# Discriminants

For any two-dimensional rational subspace  $L \subset \mathbb{R}^4$  we define the *discriminant* of  $L$  to be

$$\text{disc}(L) = \text{covol}(L \cap \mathbb{Z}^4)^2 \in \mathbb{Z}_{>0}$$

For any integer  $D > 0$  set

$$\mathcal{R}_D = \{L \subset \mathbb{R}^4 \text{ rational plane} : \text{disc}(L) = D\} \subset \text{Gr}_{2,4}(\mathbb{R}).$$

This is a finite set and non-empty if and only if  $D \not\equiv 0, 7, 12, 15 \pmod{16}$ . In this case, one can show that

$$|\mathcal{R}_D| = D^{1+o(1)}.$$

# The first two CM points

By rotating  $L$  to a fixed copy of  $\mathbb{R}^2$  in  $\mathbb{R}^4$  the lattice  $L \cap \mathbb{Z}^4 \subset L$  yields a lattice with complex multiplication in  $\mathbb{R}^2$ . It is well-defined up to (possibly not orientation preserving) isometries and so we obtain a point (the *shape* of  $L \cap \mathbb{Z}^4$ )

$$z_1(L) = [L \cap \mathbb{Z}^4] \in \mathrm{PGL}_2(\mathbb{Z}) \backslash \mathrm{PGL}_2(\mathbb{R}) / \mathrm{O}(2) =: \mathcal{X}_2$$

Similarly, one defines the shape  $z_2(L) = [L^\perp \cap \mathbb{Z}^4]$ .

# The Klein map

To define the second pair of CM points attached to  $L$  we make use of a quaternionic accident identifying  $\mathrm{Gr}_{2,4}(\mathbb{R})$  with  $\mathbb{S}^2 \times \mathbb{S}^2$  up to index two.

We identify  $\mathbb{R}^4$  with the algebra  $\mathbf{D}$  of Hamiltonian quaternions given by

$$i^2 = j^2 = k^2 = -1, \quad ij = -ji = k.$$

For  $x = x_0 + x_1i + x_2j + x_3k$  we denote

$$\begin{aligned}\bar{x} &= x_0 - x_1i - x_2j - x_3k, \\ \mathrm{Nr}(x) &= x\bar{x} = x_0^2 + x_1^2 + x_2^2 + x_3^2, \\ \mathrm{Tr}(x) &= x + \bar{x} = 2x_0.\end{aligned}$$

For  $L \in \mathcal{R}_D$  with integral basis  $v_1, v_2$  we set

$$\begin{aligned}a_1(L) &= v_1 \overline{v_2} - \frac{1}{2} \operatorname{Tr}(v_1 \overline{v_2}), \\a_2(L) &= \overline{v_2} v_1 - \frac{1}{2} \operatorname{Tr}(\overline{v_2} v_1).\end{aligned}$$

These are two integer vectors in  $\mathbb{Z}^3$  that are independent of the choice of basis up to changing the sign in both of them simultaneously. Also,

$$L = \{x \in \mathbf{D} : a_1(L)x = xa_2(L)\}.$$

Using these vectors we may define the shapes

$$z_3(L) = [a_1(L)^\perp \cap \mathbb{Z}^3], \quad z_4(L) = [a_2(L)^\perp \cap \mathbb{Z}^3] \in \mathcal{X}_2.$$

# Equidistribution theorem

## Theorem (Aka, Einsiedler, W. 2019)

Let  $p, q$  be two odd primes and consider the set  $\mathcal{J}_D$  of tuples

$$(L, z_1(L), z_2(L), z_3(L), z_4(L)) \in \text{Gr}_{2,4}(\mathbb{R}) \times \mathcal{X}_2^4$$

for  $L \in \mathcal{R}_D$ . When  $D \rightarrow \infty$  with  $|\mathcal{R}_D| \neq \emptyset$  and  $-D$  is a non-zero square modulo  $p$  as well as modulo  $q$ , the sets  $\mathcal{J}_D$  are equidistributed.

Note:

- Maass (50's) and Schmidt (90's) show equidistribution of the tuples  $(L, z_1(L))$  on average.
- Equidistribution of the individual factors follows from Duke's theorem and its refinements (here by Harcos and Michel).

Action of  $SU_2^2$ 

Note that  $SU_2^2 = \{x \in \mathbf{D} : \text{Nr}(x) = 1\}^2$  acts on  $\mathbf{D}$  via

$$(g_1, g_2).x = g_1 x g_2^{-1}$$

preserving the norm.

The map  $L \mapsto (a_1(L), a_2(L))$  is equivariant in the sense that

$$a_1((g_1, g_2).L) = g_1 a_1(L) g_1^{-1}, \quad a_2((g_1, g_2).L) = g_2 a_2(L) g_2^{-1}.$$

We consider the stabilizer subgroup

$$\mathbb{H}_L = \{(g_1, g_2) \in SU_2^2 : (g_1, g_2).L = L\}^\circ$$

One can naturally embed  $\mathbb{H}_L$  into

$$\mathbb{G} = \mathrm{SU}_2^2 \times \mathrm{SL}_2^4.$$

We deduce the main theorem from an equidistribution result for the orbits

$$\mathbb{G}(\mathbb{Q})\mathbb{H}_L(\mathbb{A}) \subset \mathbb{G}(\mathbb{Q}) \backslash \mathbb{G}(\mathbb{A}).$$

By a joinings classification of Einsiedler and Lindenstrauss, we essentially need to understand if  $\mathbb{H}_L$  is contained in any subgroup of  $\mathbb{G}$  (that projects onto each factor).



## Example of a stabilizer

We consider  $\mathbf{D} = \text{Mat}_2$  and the subspace

$$L = \left\{ \begin{pmatrix} * & 0 \\ 0 & * \end{pmatrix} \right\}.$$

Then

$$a_1(L) = a_2(L) = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}.$$

One checks

$$\mathbb{H}_L(\mathbb{R}) = \text{Stab}_{\text{SL}_2(\mathbb{R})}(a_1(L)) \times \text{Stab}_{\text{SL}_2(\mathbb{R})}(a_2(L)) = A \times A$$

where

$$A = \left\{ a_t = \begin{pmatrix} t & 0 \\ 0 & t^{-1} \end{pmatrix} : t \in \mathbb{R}^\times \right\}.$$

We would now like to understand the way in which  $A \times A$  acts on the subspaces  $L, L^\perp, a_1(L)^\perp, a_2(L)^\perp$ .

- In the basis  $E_{11}, E_{22}$ , the matrix  $a = (a_s, a_t) \in A \times A$  acts on  $L$  as  $a_{st^{-1}}$ .
- In the basis  $E_{12}, E_{21}$ , the matrix  $a$  acts on  $L^\perp$  as  $a_{st}$ .
- By equivariance,  $a$  acts on  $a_1(L)^\perp$  by conjugating with  $a_s$ . In the basis  $E_{12}, E_{21}$  this amounts to  $a_{s^2}$ .
- Similarly, for  $a_2(L)^\perp$  we get  $a_{t^2}$ .

$$\rightsquigarrow \{(a_s, a_t, a_{st^{-1}}, a_{st}, a_{s^2}, a_{t^2}) : s, t > 0\} \subset \mathrm{SL}_2(\mathbb{R})^6.$$

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Fixing any two factors, say the 4th and the 5th, one sees that there is no non-trivial subgroup  $M < \mathrm{SL}_2(\mathbb{R})^2$  that projects onto each component and that contains

$$\{(a_{st}, a_{s^2}) : s, t > 0\}.$$