IV. Group Lasso (... continued after material from visualizer) Parameterization of model matrix

4 levels, p = 2 variables

main effects only

```
> xx1
[1] 0 1 2 3 3 2 1 0
Levels: 0 1 2 3
> xx2
[1] 3 3 2 2 1 1 0 0
Levels: 0 1 2 3
> model.matrix(~xx1+xx2,
contrasts=list(xx1="contr.sum",xx2="contr.sum"))
  (Intercept) xx11 xx12 xx13 xx21 xx22 xx23
            1 0 1 0 -1 -1 -1
1 0 0 1 0 -1 -1 -1
1 0 0 1 0 0 1
1 -1 -1 -1 0 0 1
1 -1 -1 -1 0 1 0
1 0 0 1 0 1 0 0
1 1 0 0 1 0 0
1 1 0 0 1 0 0
attr(, "assign")
[1] 0 1 1 1 2 2 2
attr(, "contrasts")
attr(, "contrasts") $xx1
[1] "contr.sum"
attr(, "contrasts") $xx2
[1] "contr.sum"
```

with interaction terms

```
> model.matrix(~xx1*xx2.
contrasts=list(xx1="contr.sum",xx2="contr.sum"))
  (Intercept) xx11 xx12 xx13 xx21 xx22 xx23 xx11:xx21 xx12:xx21 xx13:xx21
                                                               0
                                        0
attr(,"assign")
[1] 0 1 1 1 2 2 2 3 3 3 3 3 3 3 3 3 3
attr(,"contrasts")
attr(,"contrasts")$xx1
[1] "contr.sum"
attr(, "contrasts") $xx2
[1] "contr.sum"
```

Prediction of DNA splice sites (Ch. 4.3.1 in Bühlmann and van de Geer (2011))

want to predict donor splice site where coding and non-coding regions in DNA start/end

seven positions around "GT"

training data:

$$Y_i \in \{0, 1\}$$
 true donor site or not $X_i \in \{A, C, G, T\}^7$ positions $i = 1, \dots, n \approx 188'000$

unbalanced: $Y_i = 1$: 8415; $Y_i = 0$: 179'438

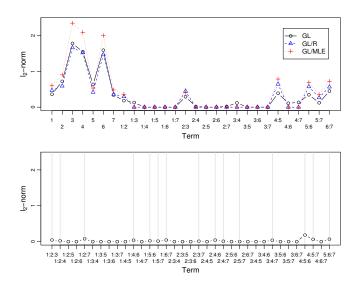
model: logistic linear regression model with intercept, main effects and interactions up to order 2 (3 variables interact)

 \rightarrow dimension = 1155



methods:

- ► Group Lasso
- ▶ MLE on $\hat{S} = \{j; \ \hat{\beta}_{\mathcal{G}_i} \neq 0\}$
- ightharpoonup as above but with Ridge regularized MLE on \hat{S}



mainly main effects (quite debated in computational biology...)

Theoretical guarantees for Group Lasso

follows "similarly" but with more complicated arguments as for the Lasso (e.g. requiring group compatibility condition)

Algorithm for Group Lasso

consider the KKT conditions for the objective function

$$Q_{\lambda}(\beta) = \underbrace{n^{-1} \sum_{i=1}^{n} \rho_{\beta}(X_i, Y_i)}_{\text{e.g. } \|Y - X\beta\|_2^2/n} + \lambda \sum_{j=1}^{q} m_j \|\beta_{\mathcal{G}_j}\|_2$$

Lemma (Lemma 4.3 in Bühlmann and van de Geer (2011)) Assume $\rho_{\beta} = n^{-1} \sum_{i=1}^{n} \rho_{\beta}(X_i, Y_i)$ is differentiable and convex (in β). Then, a necessary and sufficient condition for $\hat{\beta}$ to be a solution is

$$\nabla \rho(\hat{\beta})_{\mathcal{G}_{j}} = -\lambda m_{j} \frac{\hat{\beta}_{\mathcal{G}_{j}}}{\|\hat{\beta}_{\mathcal{G}_{j}}\|_{2}} \quad \text{if } \hat{\beta}_{\mathcal{G}_{j}} \not\equiv 0,$$
$$\|\nabla \rho(\hat{\beta})_{\mathcal{G}_{j}}\|_{2} \leq \lambda m_{j} \quad \text{if } \hat{\beta}_{\mathcal{G}_{j}} \equiv 0$$

block coordinate descent

Algorithm 1 Block Coordinate Descent Algorithm

- i. Let $\beta^{[0]} \in \mathbb{R}^p$ be an initial parameter vector. Set m = 0.
- 2: repeat
- 3: Increase m by one: $m \leftarrow m + 1$.
 - Denote by $\mathscr{S}^{[m]}$ the index cycling through the block coordinates $\{1, \ldots, q\}$:
 - $\mathscr{S}^{[m]} = \mathscr{S}^{[m-1]} + 1 \mod q$. Abbreviate by $j = \mathscr{S}^{[m]}$ the value of $\mathscr{S}^{[m]}$.
- $\begin{array}{ll} \text{4:} & \text{if } \|(-\nabla\rho(\beta_{\mathscr{G}_{j}}^{[m-1]})_{\mathscr{G}_{j}}\|_{2} \leq \lambda m_{j} \colon \operatorname{set} \beta_{\mathscr{G}_{j}}^{[m]} = 0, \\ & \text{otherwise: } \beta_{\mathscr{G}_{j}}^{[m]} = \arg\min_{\beta_{\mathscr{G}_{i}}} Q_{\lambda}(\beta_{+\mathscr{G}_{j}}^{[m-1]}), \end{array}$
 - where $\beta_{-\mathcal{G}_j}^{[m-1]}$ is defined in (4.14) and $\beta_{+\mathcal{G}_j}^{[m-1]}$ is the parameter vector which equals $\beta^{[m-1]}$ except for the components corresponding to group \mathcal{G}_j whose entries are equal to $\beta_{\mathcal{G}_j}$ (i.e. the argument we minimize over).
- 5: until numerical convergence

block-updates where the blocks correspond to the groups

The generalized Group Lasso penalty

Chapter 4.5 in Bühlmann and van de Geer (2011)

$$pen(\beta) = \lambda \sum_{j=1}^{q} m_j \sqrt{\beta_{\mathcal{G}_j}^T A_j \beta_{\mathcal{G}_j}},$$
A positive definite

 A_j positive definite

can do the computation with standard group Lasso by transformation:

$$\tilde{\beta}_{\mathcal{G}_j} = A_j^{1/2} \beta_{\mathcal{G}_j} \rightsquigarrow \text{pen}(\tilde{\beta}) = \lambda \sum_{j=1}^q m_j \|\tilde{\beta}_{\mathcal{G}_j}\|_2$$

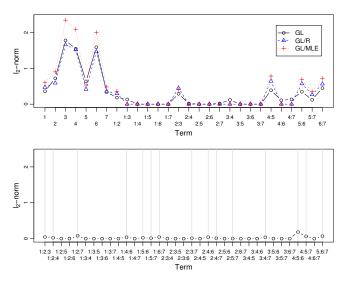
$$X\beta = \sum_{j=1}^q \tilde{X}_{\mathcal{G}_j} \tilde{\beta}_{\mathcal{G}_j} =: \tilde{X}\tilde{\beta}, \ \tilde{X}_{\mathcal{G}_j} = X_{\mathcal{G}_j} A_j^{1/2}$$

can simply solve the "tilde" problem: $\leadsto \hat{\tilde{\beta}} \leadsto \hat{\beta}_{\mathcal{G}_j} = A_j^{-1/2} \hat{\tilde{\beta}}_{\mathcal{G}_j}$

special but important case: groupwise prediction penalty

$$\begin{split} \text{pen}(\beta) &= \sum_{j=1}^q m_j \|X_{\mathcal{G}_j}\beta_{\mathcal{G}_j}\|_2 = \lambda \sum_{j=1}^q m_j \sqrt{\beta_{\mathcal{G}_j}^T X_{\mathcal{G}_j}^T X_{\mathcal{G}_j}\beta_{\mathcal{G}_j}} \\ X_{\mathcal{G}_i}^T X_{\mathcal{G}_j} \text{typically positive definite for } |\mathcal{G}_j| < n \end{split}$$

- ▶ penalty is invariant under arbitrary reparameterizations within every group G_i : important!
- when using an orthogonal parameterization such that $X_{\mathcal{G}_j}^T X_{\mathcal{G}_j} = I$: it is the standard Group Lasso with categorical variables: this is in fact what one has in mind (can use groupwise orthogonalized design) or one should use the groupwise prediction penalty



is with groupwise orthogonalized design matrices

High-dimensional additive models

the special case with natural cubic splines

(Ch. 5.3.2 in Bühlmann and van de Geer (2011))

consider the estimation problem wit the SPS penalty:

$$\hat{f}_1, \dots, \hat{f}_p = \operatorname{argmin}_{f_1, \dots, f_p \in \mathcal{F}} (\|Y - \sum_{j=1}^p f_j\|_n^2 + \lambda_1 \|f_j\|_n + \lambda_2 I(f_j))$$

where \mathcal{F} = Sobolev space of functions on [a,b] that are continuously differentiable with square integrable second derivatives

Proposition 5.1 in Bühlmann and van de Geer (2011) Let $a,b\in\mathbb{R}$ such that $a<\min_{i,j}(X_i^{(j)})$ and $b>\max_{i,j}(X_i^{(j)})$. Let \mathcal{F} be as above. Then, the \hat{f}_j 's are natural cubic splines with knots at $X_i^{(j)}$, $i=1,\ldots,n$.

implication: the optimization over functions is exactly representable as a parametric problem with dim $\approx 3np$



the optimization over functions is exactly representable as a parametric problem with

therefore:

$$f_j = H_j \beta_j$$
, H_j from natural cubic spline basis
$$||f_j||_n = ||H_j \beta_j||_2 / \sqrt{n} = \sqrt{\beta_j^T H_j^T H_j \beta_j} / \sqrt{n}$$

$$I(f_j) = \sqrt{\int ((H_j \beta_j)'')^2} = \sqrt{\beta_j^T \underbrace{(H_j'')^T H_j''}_{=:W_j} \beta} = \sqrt{\beta_j^T W_j \beta_j}$$

→ convex problem

$$\hat{\beta} = \operatorname{argmin}_{\beta} \left(\|Y - H\beta\|_2^2 / n + \lambda_1 \sum_{j=1}^p \sqrt{\beta_j^T H_j^T H_j \beta_j} / n + \lambda_2 \sum_{j=1}^p \sqrt{\beta_j^T W_j \beta_j} \right)$$

SPS penalty of group Lasso type

for easier computation: instead of

$$\mathsf{SPS} \; \mathsf{penalty} = \lambda_1 \sum_j \|f_j\|_n + \lambda_2 \sum_j \textit{I(fj)}$$

one can also use as an alternative:

SPS Group Lasso penalty =
$$\lambda_1 \sum_j \sqrt{\|f_j\|_n^2 + \lambda_2 I^2(f_j)}$$

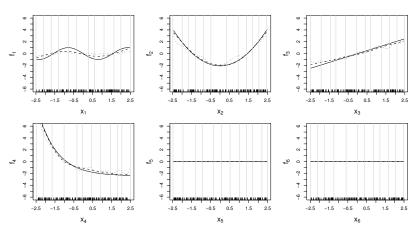
in parameterized form, the latter becomes:

$$\lambda_{1} \sum_{j=1}^{p} \sqrt{\|H_{j}\beta_{j}\|_{2}^{2}/n + \lambda_{2}^{2}\beta_{j}^{T}W_{j}\beta_{j}} = \lambda_{1} \sum_{j=1}^{p} \sqrt{\beta_{j}^{T}(H_{j}^{T}H_{j}/n + \lambda_{2}^{2}W_{j})\beta_{j}}$$

 \rightarrow for every λ_2 : a generalized Group Lasso penalty



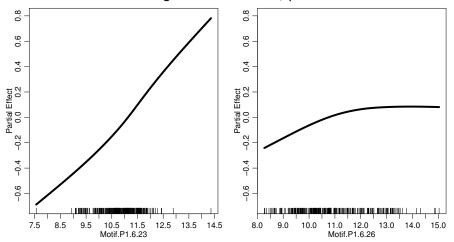
simulated example: n = 150, p = 200 and 4 active variables



dotted line: $\lambda_2 = 0$

 $\sim \lambda_2$ seems not so important: just consider a few candidate values (solid and dashed line)

motif regression: n = 287, p = 195



→ a linear model would be "fine as well"

Conclusions

if the problem is sparse and smooth: only a few $X^{(j)}$'s influence Y (only a few non-zero f_j^0) and the non-zero f_j^0 are smooth

 \sim one can often afford to model and fit additive functions in high dimensions

reason:

- ▶ dimensionality is of order $\dim = O(pn)$ $\log(\dim)/n = O((\log(p) + \log(n))/n)$ which is still small
- ightharpoonup sparsity and smoothness then lead to: if each f_j^0 is twice continuously differentiable

$$\|\hat{f} - f^0\|_2^2/n = O_P(\underbrace{\text{sparsity}}_{\text{no. of non-zero } f_i^0} \sqrt{\log(p)} n^{-4/5})$$

(cf. Ch. 8.4 in Bühlmann & van de Geer (2011))

