The de-sparsified or de-biased Lasso

Recap: if p < n and rank(X) = p, then:

$$\begin{split} \hat{\beta}_{\text{OLS},j} &= Y^{T} Z^{(j)} / (X^{(j)})^{T} Z^{(j)} \\ Z^{(j)} &= X^{(j)} - X^{(-j)} \hat{\gamma}^{(j)} \\ &= \text{OLS residuals from } X^{(j)} \text{ vs. } X^{(-j)} = \{ X^{(k)}; \ k \neq j \} \\ \hat{\gamma}^{(j)} &= \arg\min_{\gamma} \| X^{(j)} - X^{(-j)} \gamma \|_{2}^{2} \end{split}$$

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idea for high-dimensional setting: use the Lasso for the residuals $Z^{(j)}$

The de-sparsified Lasso

consider

$$Z^{(j)} = X^{(j)} - X^{(-j)} \hat{\gamma}^{(j)}$$

= Lasso residuals from $X^{(j)}$ vs. $X^{(-j)} = \{X^{(k)}; k \neq j\}$
 $\hat{\gamma}^{(j)} = \operatorname{argmin}_{\gamma} \|X^{(j)} - X^{(-j)}\gamma\|_{2}^{2} + \lambda_{j} \|\gamma\|_{1}$

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build projection of Y onto $Z^{(j)}$:

$$\frac{Y^{T}Z^{(j)}}{(X^{(j)})^{T}Z^{(j)}} \underset{Y=X\beta^{0}+\varepsilon}{\overset{=}{\underset{k\neq j}{\overset{\beta^{0}}{=}}}} \beta^{0}_{j} + \underbrace{\sum_{\substack{k\neq j}} \frac{(X^{(k)})^{T}Z^{(j)}}{(X^{(j)})^{T}Z^{(j)}} \beta^{0}_{k}}_{\text{bias}} + \frac{\varepsilon^{T}Z^{(j)}}{(X^{(j)})^{T}Z^{(j)}}$$

estimate bias and subtract it:

$$\widehat{\text{bias}} = \sum_{k \neq j} \frac{(X^{(k)})^T X^{(j)}}{(X^{(j)})^T Z^{(j)}} \underbrace{\hat{\beta}_k}_{\text{standard Lasso}}$$

 \sim de-sparsified Lasso estimator

$$\hat{b}_{j} = \frac{Y^{T} Z^{(j)}}{(X^{(j)})^{T} Z^{(j)}} - \sum_{k \neq j} \frac{(X^{(k)})^{T} Z^{(j)}}{(X^{(j)})^{T} Z^{(j)}} \hat{\beta}_{k} \ (j = 1, \dots, p)$$

not sparse! Never equal to zero for all $j = 1, \ldots, p$

can also be represented as

$$\hat{b}_{j} = \underbrace{\hat{\beta}_{j}}_{\text{standard Lasso}} + \frac{(Y - X\hat{\beta})^{T} Z^{(j)}}{(X^{(j)})^{T} Z^{(j)}} \quad \text{``de-biased Lasso''}$$

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using that

$$\frac{Y^{T}Z^{(j)}}{(X^{(j)})^{T}Z^{(j)}} = \beta_{j}^{0} + \sum_{k \neq j} \frac{(X^{(k)})^{T}Z^{(j)}}{(X^{(j)})^{T}Z^{(j)}} \beta_{k}^{0} + \frac{\varepsilon^{T}Z^{(j)}}{(X^{(j)})^{T}Z^{(j)}}$$

we obtain

$$\sqrt{n}(\hat{b}_{j} - \beta_{j}^{0}) = \underbrace{\sqrt{n} \sum_{k \neq j} \frac{(X^{(k)})^{T} Z^{(j)}}{(X^{(j)})^{T} Z^{(j)}} (\beta_{k}^{0} - \hat{\beta}_{k})}_{\sqrt{n} \cdot \text{ (bias term of de-biased Lasso)}} + \underbrace{\sqrt{n} \frac{\varepsilon^{T} Z^{(j)}}{(X^{(j)})^{T} Z^{(j)}}}_{\text{fluctuation term}}$$

so far, this holds for any $Z^{(j)}$

assume fixed design X, e.g. condition on X Gaussian error $\varepsilon \sim N_n(0, \sigma^2 I)$

fluctuation term:

$$\sqrt{n} \frac{\varepsilon^T Z^{(j)}}{(X^{(j)})^T Z^{(j)}} = \frac{n^{-1/2} \varepsilon^T Z^{(j)}}{(X^{(j)})^T Z^{(j)}/n} \sim \mathcal{N}(0, \frac{\sigma^2 \|Z^{(j)}\|_2^2/n}{|(X^{(j)})^T Z^{(j)}/n|^2})$$

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bias term of de-biased Lasso: we exploit two things

$$||\hat{\beta} - \beta^0||_1 = O_P(s_0\sqrt{\log(p)/n})$$

► KKT condition for Lasso (on $X^{(j)}$ versus $X^{(-j)}$): $|(X^{(k)})^T Z^{(j)}/n| \le \lambda_j/2$

therefore:

$$\begin{split} &\sqrt{n} \sum_{k \neq j} \frac{(X^{(k)})^T Z^{(j)}}{(X^{(j)})^T Z^{(j)}} (\beta_k^0 - \hat{\beta}_k) \\ &= \sqrt{n} \sum_{k \neq j} \frac{(X^{(k)})^T Z^{(j)} / n}{(X^{(j)})^T Z^{(j)} / n} (\beta_k^0 - \hat{\beta}_k) \\ &\leq \sqrt{n} \max_{k \neq j} |\frac{(X^{(k)})^T Z^{(j)} / n}{(X^{(j)})^T Z^{(j)} / n} |\| \hat{\beta} - \beta^0 \|_1 \\ &\leq \sqrt{n} \frac{\lambda_j / 2}{(X^{(j)})^T Z^{(j)} / n} O_P(s_0 \sqrt{\log(p) / n}) \end{split}$$

$$= O_P(s_0 \log(p)/\sqrt{n}) = o_P(1) \text{ if } s_0 \ll \frac{\sqrt{n}}{\log(p)}$$

if $\lambda_j \simeq \sqrt{\log(p)/n}$ and $(X^{(j)})^T Z^{(j)}/n \simeq O(1)$

summarizing \sim *Theorem 10.1 in the notes* assume:

•
$$\varepsilon \sim \mathcal{N}(0, \sigma^2 I)$$

• $\lambda_j = C_j \sqrt{\log(p)/n}$ and $||Z^{(j)}||_2^2/n \ge L > 0$
• $s_0 = o(\sqrt{n}/\log(p))$ (a bit more sparse than "usual")
• $||\hat{\beta} - \beta^0||_1 = O_P(s_0 \sqrt{\log(p)/n})$
(i.e., compatibility constant ϕ_o^2 bounded away from zero)
Then:

$$\sigma^{-1}\sqrt{n}\frac{(\boldsymbol{X}^{(j)})^{T}\boldsymbol{Z}^{(j)}/n}{\|\boldsymbol{Z}^{(j)}\|_{2}/\sqrt{n}}(\hat{b}_{j}-\beta_{j}^{0})\Longrightarrow\mathcal{N}(0,1) \ (j=1,\ldots,p)$$

more precisely:

$$\sigma^{-1} \sqrt{n} \frac{(X^{(j)})^T Z^{(j)}/n}{\|Z^{(j)}\|_2/\sqrt{n}} (\hat{b}_j - \beta_j^0) = W_j + \Delta_j$$

$$(W_1, \dots, W_p)^T \sim \mathcal{N}_p(0, \Omega), \ \Omega_{jj} \equiv 1 \ \forall j, \ \max_{j=1,\dots,p} |\Delta_j| = o_P(1)$$

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confidence intervals for β_i^0 :

$$\hat{b}_{j} \pm \hat{\sigma} n^{-1/2} rac{\|Z^{(j)}\|_{2}/\sqrt{n}}{|(X^{(j)})^{T}Z^{(j)}/n} \Phi^{-1}(1-lpha/2)$$

 $\hat{\sigma}^2 = \|Y - X\hat{\beta}\|_2^2/n \text{ or } \hat{\sigma}^2 = \|Y - X\hat{\beta}\|_2^2/(n - \|\hat{\beta}\|_0^0)$

can also test

$$H_{0,j}: \ \beta_j^0 = 0 \text{ versus } H_{A,j}: \ \beta_j^0 \neq 0$$

can also test group hypothesis: for $G \subseteq \{1, \ldots, p\}$

$$egin{aligned} &\mathcal{H}_{0,G}:\ eta_j^0\equiv 0 \forall j\in G\ &\mathcal{H}_{A,G}:\exists j\in G ext{ such that }eta_j^0
eq 0 \end{aligned}$$

under $H_{0,G}$:

$$\max_{j \in G} \sigma^{-1} \sqrt{n} \frac{|(X^{(j)})^T Z^{(j)}/n|}{\|Z^{(j)}\|_2/\sqrt{n}} |\hat{b}_j| = \max_{j \in G} |W_j + \Delta_j| \asymp \underbrace{\max_{j \in G} |W_j|}_{\text{distr. simulated}}$$

and plug-in $\hat{\sigma}$ for σ

Choice of tuning parameters

as usual: $\hat{\beta} = \hat{\beta}(\hat{\lambda}_{CV})$; what is the role of λ_j ?

variance =
$$\sigma^2 n^{-1} \frac{\|Z^{(j)}\|_2^2/n}{|(X^{(j)})^T Z^{(j)}/n|^2} \simeq \sigma^2 / \|Z^{(j)}\|_2^2$$

if $\lambda_j \searrow$ then $\|Z^{(j)}\|_2^2 \searrow$, i.e. large variance

error due to bias estimation is bounded by:

$$|\ldots| \leq \sqrt{n} \frac{\lambda_j/2}{|(X^{(j)})^T Z^{(j)}/n|} \|\hat{\beta} - \beta^0\|_1 \propto \lambda_j$$

assuming λ_j is not too small if $\lambda_j \searrow$ (but not too small) then bias estimation error \searrow

 \sim inflate the variance a bit to have low error due to bias estimation: control type I error at the price of slightly decreasing power

How good is the de-biased Lasso?

asymptotic efficiency:

for the de-biased Lasso to "work" we require

- ► sparsity: $s_0 = o(\sqrt{n}/\log(p))$ this cannot be beaten in a minimax sense
- compatibility condition for X

for optimality in terms of the lowest possible asymptotic variance achieving the "Cramer-Rao" lower bound:

require in addition that X^(j) versus X^(−j) is sparse: s_j ≪ n/log(p)

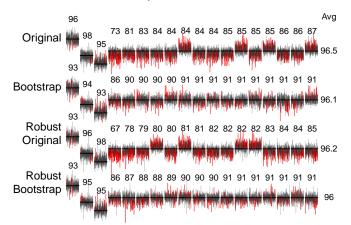
then... skipping details, the de-biased Lasso achieves (see Theorem 10.2):

$$\sqrt{n}(\hat{b}_j - \beta_j^0) \Longrightarrow \mathcal{N}(0, \underbrace{\sigma^2 \Theta_{jj}}_{\text{Cramer-Rao lower bound}})$$

$$\Theta = \Sigma_X^{-1} = \operatorname{Cov}(X)^{-1} \rightsquigarrow \text{ as for OLS in low dimensions!}$$

Empirical results

R-software hdi



de-sparsified Lasso

black: confidence interval covered the true coefficient red: confidence interval failed to cover

Stability Selection (Ch. 10 in Bühlmann and van de Geer (2011))





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Stability selection

Nicolai Meinshausen University of Oxford, UK and Peter Bühlmann Eidgenössiche Technische Hochschule Zürich, Switzerland

[Read before The Royal Statistical Society at a meeting organized by the Research Section on Wednesday, February 3rd, 2010, Professor D. M. Titterington in the Chair]

has been developed before one knew about the de-biased/de-sparsified Lasso

even with new tools such as the de-biased/de-sparsified Lasso estimation of discrete structures ("relevant" variables in a generalized linear model; edges in a graphical model) is notoriously difficult

e.g. choice of tuning parameters ...?

i.i.d. data Z_1, \ldots, Z_n

main example: $Z_i = (X_i, Y_i)$ from regression or classification

 \hat{S}_{λ} is a "feature selection" method/algorithm among $\{1, \dots, p\}$ features

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can we assign "relevance" to the selected features in \hat{S}_{λ} ?

a "natural" approach: resampling! here: use subsampling:

- ▶ l^* random sub-sample of size $\lfloor n/2 \rfloor$ of $\{1, \ldots, n\}$
- compute $\hat{S}_{\lambda}(I^*)$
- repeat *B* times to obtain $\hat{S}_{\lambda}(I^{*1}), \dots, \hat{S}_{\lambda}(I^{*B})$

• consider the "overlap" among $\hat{S}_{\lambda}(I^{*1}), \dots, \hat{S}_{\lambda}(I^{*B})$ regarding the latter, for example:

$$\hat{\Pi}_{\mathcal{K}}(\lambda) = \mathbb{P}^*[\mathcal{K} \subseteq \hat{S}_{\lambda}(I^*)] \approx B^{-1} \sum_{b=1}^{B} I(\mathcal{K} \subseteq \hat{S}_{\lambda}(I^{*b}))$$

e.g. $\hat{\Pi}_j(\lambda) \ (j \in \{1, \dots, p\})$

the probability \mathbb{P}^* is with respect to subsampling: a sum over $\binom{n}{m}$ terms, $m = \lfloor n/2 \rfloor$, i.e., all possible subsampling combinations

 \sim it is approximated by *B* (\approx 100) times random subsampling

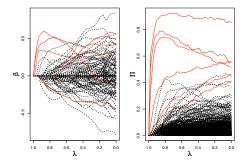
The stability regularization path

Riboflavin data: n = 115, p = 4088

Y: log-production rat of riboflavin by bacillus subtilis

X: gene expressions of bacillus subtilis

all X-variables permuted except 6 "a-priori relevant" genes



left: Lasso regularization path (red: the 6 non-permuted "relevant" genes) right: Stability path with $\hat{\Pi}_j$ on y-axis (red: the 6 non-permuted "relevant" variables stick out much more clearly from the noise covariates)

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What is a good truncation value (for Î)?

aim: choose π_{thr} such that

$$\hat{\mathcal{S}}_{ ext{stable}} = \{j; \max_{\lambda \in \Lambda} \hat{\Pi}_j(\lambda) \geq \pi_{ ext{thr}} \}$$

has not too many false positives Λ can be a singleton or a range of values

as a measure for type I error control (against false positives):

$$V =$$
 number of false positives $= |\hat{S}_{\text{stable}} \cap S_0^c|$

where S_0 is the set of the true relevant features, e.g.:

- active variables in regression
- true edges in a graphical model

"the miracle":

a simple formula connecting π_{thr} with $\mathbb{E}[V]$

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consider a setting with *p* possible features $\hat{S}(\lambda)$ is a feature selection algorithm $\hat{S}_{\Lambda} = \bigcup_{\lambda \in \Lambda} \hat{S}(\lambda)$ $q_{\Lambda} = \mathbb{E}[\hat{S}_{\Lambda}(\underbrace{I}_{\text{random subsample}})]$

Theorem 10.1 Assume:

- exchangeability condition: $\{l(j \in \hat{S}(\lambda)\}), j \in S_0^c\}$ is exchangeable for all $\lambda \in \Lambda$
- \hat{S} is not worse than random guessing

$$\frac{\mathbb{E}|S_0 \cap \hat{S}_{\Lambda}|)}{\mathbb{E}(|S_0^c \cap \hat{S}_{\Lambda}|)} \geq \frac{|S_0|}{|S_0^c|}.$$

Then, for $\pi_{\text{thr}} \in (1/2, 1)$:

$$\mathbb{E}[V] \quad \leq \quad rac{1}{2\pi_{ ext{thr}}-1} \; rac{q_{\Lambda}^2}{
ho}$$

suppose we know q_{Λ} (see later) strategy: specify $\mathbb{E}[V] = v_0$ (e.g. = 5) \sim for $\pi_{\text{thr}} := \frac{1}{2} + \frac{q_{\Lambda}^2}{2\rho v_0}$: $\mathbb{E}[V] \le v_0$ example: regression model with p = 1000 variables

 \hat{S}_{λ} = the top 10 variables from Lasso (e.g. the different λ from Lasso by CV and choose the top 10 variables with the largest absolute values of the corresponding estimated coefficients; if less than 10 variables are selected, take the selected variables) the value λ corresponds to the "top 10"; Λ is a singleton

we then know that $q_{\Lambda} = \mathbb{E}[|\hat{S}_{\lambda}(I)|] \leq 10$

For $\mathbb{E}[V] = v_0 := 5$ we then obtain

$$\pi_{\rm thr} = \frac{1}{2} + \frac{q_{\Lambda}^2}{2\rho v_0} = 0.5 + \frac{10^2}{2*1000*5} = 0.51$$

there is room to play around recommendation: take $|\hat{S}(\lambda)|$ rather large and stability selection will reduce again to reasonable size

when taking the "top 30", the threshold becomes

$$\pi_{\rm thr} = \frac{1}{2} + \frac{q_{\Lambda}^2}{2\rho v_0} = 0.5 + \frac{30^2}{2*1000*5} = 0.59$$

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adding noise... can always add (e.g. independent $\mathcal{N}(0, 1)$) noise covariates enlarged dimension p_{enlarged}

error control becomes better (for the same threshold)

$$\mathbb{E}[V] \leq \frac{1}{2\pi_{\rm thr}-1} \frac{q_{\Lambda}^2}{p_{\rm enlarged}}$$

this sometimes helps indeed in practice – at the cost of loss in power

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The assumptions for mathematical guarantees

not worse than random guessing

$$rac{\mathbb{E}|S_0 \cap \hat{S}_{\Lambda}|)}{\mathbb{E}(|S_0^c \cap \hat{S}_{\Lambda}|)} \ \geq \ rac{|S_0|}{|S_0^c|}$$

perhaps hard to check but very reasonable...

for Lasso in linear models it holds assuming the variable screening property asymptotically: if beta-min and compatibility condition hold

exchangeability condition $\{l(j \in \hat{S}(\lambda)\}), j \in S_0^c\}$ is exchangeable for all $\lambda \in \Lambda$

a restrictive assumption but the theorem is very general, for any algorithm \hat{S}

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a very special case where exchangeability condition holds: random equi-correlation design linear model

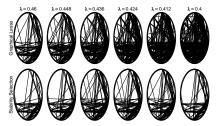
$$Y = X\beta^0 + \varepsilon$$
, $\operatorname{Cov}(X)_{i,j} \equiv \rho \ (i \neq j)$, $\operatorname{Var}(X_j) \equiv 1 \forall j$

distributions of $(Y, X^{(S_0)}, \{X^{(j)}; j \in S_0^c\})$ and of $(Y, X^{(S_0)}, \{X^{(\pi(j))}; j \in S_0^c\})$ are the same for any permutation $\pi : S_0^c \to S_0^c$

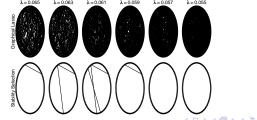
- distribution of X^(S₀), {X^{(π(j))}; j ∈ S₀^c} is the same for all π (because of equi-correlation)
- ► distribution of Y|X^(S₀), {X^{(π(j))}; j ∈ S^c₀} is the same for all π (because it depends only on X^(S₀))
- therefore: distribution of Y, X^(S₀), {X^{(π(j))}; j ∈ S₀^c} is the same for all π and hence exchangeability condition holds for any (measurable) function Ŝ(λ)

An illustration for graphical modeling

p = 160 gene expressions, n = 115GLasso estimator, selecting among the $\binom{p}{2} = 12'720$ features stability selection with $\mathbb{E}[V] \le v_0 = 30$



with permutation (empty graph is correct)



Stability Selection is extremely easy to use and super-generic

the sufficient assumptions (far from necessary) for mathematical guarantees are restrictive but the method seems to work very well in practice

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