Multivariate Extremes and Geometry

Guus Balkema Paul Embrechts* Natalia Nolde

*Department of Mathematics and RiskLab ETH Zurich, Switzerland

3

< ロ > < 同 > < 回 > < 回 > < 回 > <

Introduction

- Key tools:
 - sample clouds
 - 8 densities
- Limiting shape of sample clouds is at the heart of many results of the thesis



- # Global description of multivariate extremes
- * The shape of the sample clouds and of the level sets of densities is crucial in determining various probabilistic properties of light-tailed distributions

Sample clouds: Notation

- X_1, X_2, \ldots i.i.d. random vectors on \mathbb{R}^d
- $N_n = \{X_1/a_n, \dots, X_n/a_n\}$: *n*-point sample cloud with scaling constants $a_n > 0, a_n \to \infty$ as $n \to \infty$
- N_n(A) = ∑ⁿ_{i=1} 1_A(X_i/a_n) for any Borel set A ⊂ ℝ^d
 ↑
 number of points of N_n contained in set A

・ 何 ト ・ ヨ ト ・ ヨ ト … ヨ

Examples of sample clouds (n = 10, 000)



elliptic Cauchy with dispersion matrix $\Sigma = \begin{pmatrix} 5/4 & 3/4 \\ 3/4 & 5/4 \end{pmatrix}$

standard normal

meta-Cauchy with normal marginals

Sample clouds: Convergence onto a set

Definition

The sample clouds N_n converge onto a compact set E in \mathbb{R}^d if

- $\mathbb{P}{N_n(U^c) > 0} \rightarrow 0$ for open sets U containing E, and
- $\mathbb{P}{N_n(\mathbf{p} + \epsilon B) > m} \rightarrow 1, \ m \ge 1, \ \epsilon > 0, \ \mathbf{p} \in E$

where B denotes the unit Euclidean ball

The set E is called a limit set

(日)

Part I

Meta densities and the shape of their sample clouds

References:

- A.A. Balkema, P. Embrechts and N. Nolde (2010). Meta densities and the shape of their sample clouds. *J. Multivariate Analysis* 101: 1738-1754.
- A.A. Balkema, P. Embrechts and N. Nolde (2010). Sensitivity of the asymptotic behaviour of meta distributions. *Submitted*.

Why meta distributions?

Recent popularity in applications of multivariate probability theory, especially in finance

- Asymptotic independence of coordinatewise maxima as a shortcoming of the multivariate Gaussian model
- Go beyond normality by introducing stronger tail dependence while preserving normal marginals

伺下 イヨト イヨト

Why meta distributions?

Recent popularity in applications of multivariate probability theory, especially in finance

- Asymptotic independence of coordinatewise maxima as a shortcoming of the multivariate Gaussian model
- Go beyond normality by introducing stronger tail dependence while preserving normal marginals
- A typical example:
 - **Start with a multivariate** *t* distribution (tail dependence and heavy tails)
 - Transform each coordinate so that the new distribution has normal marginals (light tails)
 - * The new distribution is called a meta distribution with normal marginals based on the original t distribution (tail dependence and light tails)

3

・ 同 ト ・ ヨ ト ・ ヨ ト

Definition (Meta distribution)

- Random vector **Z** in \mathbb{R}^d with df **F** and continuous marginals F_i , i = 1, ..., d
- $\textit{G}_1, \ldots, \textit{G}_d$: continuous df's on $\mathbb{R},$ strictly increasing on $I_i = \{0 < G_i < 1\}$
- Define transformation:

 $K(x_1,...,x_d) = (K_1(x_1),...,K_d(x_d)), \quad K_i(s) = F_i^{-1}(G_i(s)), \quad i = 1,...,d$

Definition (Meta distribution)

- Random vector **Z** in \mathbb{R}^d with df *F* and continuous marginals F_i , i = 1, ..., d
- $\textit{G}_1, \ldots, \textit{G}_d$: continuous df's on $\mathbb{R},$ strictly increasing on $I_i = \{0 < G_i < 1\}$
- Define transformation:

 $K(x_1,...,x_d) = (K_1(x_1),...,K_d(x_d)), \quad K_i(s) = F_i^{-1}(G_i(s)), \quad i = 1,...,d$

- The df $G = F \circ K$ is the meta distribution (with marginals G_i) based on original df F
- The coordinatewise map $K = K_1 \otimes \cdots \otimes K_d$ which maps $\mathbf{x} = (x_1, \dots, x_d) \in I = I_1 \times \cdots \times I_d$ into the vector $\mathbf{z} = (K_1(x_1), \dots, K_d(x_d))$ is called the meta transformation

▲ロト ▲圖 ▶ ▲ 画 ▶ ▲ 画 ▶ ● の Q @

Definition (Standard set-up)

In the standard set-up, the meta density g is based on the original density f and has marginals which are all equal to g_0 , where

• $f \sim f_*(n_D(\mathbf{z}))$ with

s $f_* \in RV_{-(\lambda+d)}$ for some $\lambda > 0$, continuous and decreasing on $[0,\infty)$

 n_D : the gauge function of the set D

D: bounded, open, star-shaped set with a continuous boundary and containing the origin

• g_0 is continuous, positive, symmetric, and asymptotic to a von Mises function $e^{-\psi}$ with $\psi \in RV_{\theta}$ for $\theta > 0$

イロト 不得 とくまとう まし

Theorem

- Let f, g and $g_0 \sim e^{-\psi}$ satisfy the assumptions of the standard set-up
- Let $\psi(s_n) \sim \log n$

For the sequence of independent observations X_n from the meta density g, the sample clouds $N_n = \{X_1/s_n, \ldots, X_n/s_n\}$ converge onto the limit set $E_{\lambda,\theta}$ given by

$$E_{\lambda,\theta} := \{ \mathbf{u} \in \mathbb{R}^d \mid |u_1|^{\theta} + \dots + |u_d|^{\theta} + \lambda \ge (\lambda + d) \|\mathbf{u}\|_{\infty}^{\theta} \}$$

(日)

Examples of limit sets $E_{\lambda,\theta}$ in \mathbb{R}^2

$$\theta = 0.5$$
 $\theta = 1$ $\theta = 2$



Legend: $\lambda = 1$ (solid), $\lambda = 2$ (dashed), $\lambda = 4$ (dotted), $\lambda = 10$ (dotdash)

Examples of limit sets $E_{\lambda, heta}$ in \mathbb{R}^3 $(\lambda = 1)$





(日) (同) (三) (三)

- How stable is the shape of the limit set?
 - 8 How much the original distribution can be altered without affecting its marginal tail behaviour and the shape of the limit set?
 - 8 How sensitive is the shape of the limit set to perturbations of the original distribution?

- How stable is the shape of the limit set?
 - 8 How much the original distribution can be altered without affecting its marginal tail behaviour and the shape of the limit set?
 - How sensitive is the shape of the limit set to perturbations of the original distribution?
- We investigate above questions using two procedures:
 - Block partitions
 - mixtures

Assumption:

marginal dfs of F are all equal to F_0 with positive continuous symmetric density

 \Rightarrow meta transformation K has equal components:

$$K : \mathbf{x} \mapsto \mathbf{z} = (K_0(x_1), \dots, K_0(x_d))$$
$$K_0 = F_0^{-1} \circ G_0 \qquad K_0(-t) = -K_0(t)$$

Theorem 1

- Assume the standard set-up
- Let $\tilde{\rho}$ be an excess measure on $\mathbb{R}^d \setminus \{\mathbf{0}\}$ with marginal densities $\lambda/|t|^{\lambda+1}$, $\lambda>0$

One may choose \tilde{F} such that

- sample clouds converge to Poisson point process \tilde{N} with mean measure $\tilde{\rho}$
- marginals are tail asymptotic to those of F
- meta dfs $\tilde{G} = \tilde{F} \circ K$ and G have the same asymptotics:
 - **#** the sample clouds converge onto $E_{\lambda, heta}$ with the same scaling
 - the marginals are tail asymptotic

イロト 不得 トイヨト イヨト

Block partitions - Construction

- Partitions of ℝ^d into bounded Borel sets B_n, where B_n are coordinate blocks
- Start with an increasing sequence of cubes: $s_n C = [-s_n, s_n]^d$ with $0 < s_1 < s_2 < \cdots, s_n \to \infty$
- Subdivide ring $R_n = s_{n+1}C \setminus s_nC$ into blocks by a symmetric partition of interval $[-s_{n+1}, s_{n+1}]$ with division points $\pm s_{nj}$, $j = 1, ..., m_n$, with



$$-s_{n+1} < -s_n < \cdots < -s_{n1} < s_{n1} < \cdots < s_{nm_n} = s_n < s_{nm_n+1} = s_{n+1}$$

Regular block partitions

- If blocks are relatively small, the asymptotic behaviour of a distribution is not affected if the distribution is replaced by one which gives (asymptotically) the same mass to each block
 - # regular block partitions: a block partition is regular if and only if

 $s_{n+1} \sim s_n$ and $\Delta_n/s_n \to 0$

where $\Delta_n = \max\{s_{n1}, s_{n2} - s_{n1}, \dots, s_{nm_n} - s_{nm_n-1}\}$

イロト 不得下 イヨト イヨト 二日

Proof of Theorem 1 - sketch of construction

Notation:

 (A_n) : block partition in **x**-space with division points s_n (B_n) : block partition in **z**-space with division points $t_n = K_0(s_n)$

- Suppose (A_n) is regular $(\Rightarrow s_{n+1} \sim s_n)$ It is possible that $t_n << t_{n+1}$ $(\Rightarrow (B_n)$ is non-regular)
- Choose $s_{nm_n-1} = s_{n-1}$; define sets:

$$U = \bigcup_n [t_{n-1}, t_{n+1}]^d$$

- **Solution** Note: $U/t \to (0,\infty)^d$ for $t \to \infty$ if $t_n << t_{n+1}$
- **#** Let U_{δ} be the image of U in orthant Q_{δ} for $\delta \in \{-1,1\}^d$

< ロ > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

Sketch of construction (cont'd)

- Choose density \hat{f} such that sample clouds converge to \tilde{N} with mean measure $\tilde{\rho}$
- Let \tilde{f} agree with \hat{f} on sets U_{δ} and with f elsewhere $\Rightarrow \tilde{f}$ and \hat{f} differ only on asymptotically negligible set
- Alter *f* on a bounded set to make it a probability density
- \Rightarrow sample clouds from $ilde{F}$ converge to $ilde{N}$
 - In corr. partition (A_n) on x-space, the measure is changed only on "tiny" blocks [s_{n-1}, s_{n+1}]^d (with s_{n-1} ~ s_{n+1}) and their reflections
- \Rightarrow sample clouds from $\tilde{G} = \tilde{F} \circ K$ converge onto $E_{\lambda,\theta}$





Theorem 2

- Assume the standard set-up
- A ⊂ [-1, 1]^d: a star-shaped closed set with continuous boundary and containing the origin as interior point
- $E_{00} = \{r\delta \mid 0 \le r \le 1, \ \delta \in \{-1,1\}^d\}$: the diagonal cross

There exists a df \tilde{F} such that

• \tilde{F} and F have the same asymptotics:

the sample clouds converge to the same point process

- the marginals are tail asymptotic
- the sample clouds from the meta distribution \tilde{G} converge onto the set $E = A \cup E_{00}$

イロト 不得下 イヨト イヨト 二日

Idea behind a proof of Theorem 2

 Replace dF by a probability measure dF̃ which agrees outside a bounded set with d(F + F°), where F° has lighter marginals than F:

$$F_j^o(-t) << F_0(-t), \quad 1-F_j^o(t) << 1-F_0(t), \quad t \to \infty \ (j=1,\ldots,d)$$

- $\Rightarrow \tilde{F}$ and F have the same asymptotics
- dfs \tilde{G} and G may have different asymptotics:

% the scaling constants $a_n^o \sim a_n$ even though G^o has lighter tails than G% suppose sample clouds from G^o converge onto a compact set E^o then: sample clouds from \tilde{G} converge onto $E_{\lambda,\theta} \cup E^o$

- 本語 医 本語 医 一語

Some concluding remarks

- Distributions with the same asymptotics in one space (x- or z-space) may give rise to different asymptotic behaviour in the other space
 - Sensitivity of the limit shape may be radical due to even slight perturbations of the original distribution, perturbations which do not affect the asymptotics of the coordinatewise extremes or the marginals
- It is possible to manipulate the shape of the limit set without affecting the distribution of coordinatewise extremes

Part II

Asymptotic independence for unimodal densities

References:

- A.A. Balkema and N. Nolde (2010). Asymptotic independence for unimodal densities. *Advances in Applied Probability*: 42(2), in press.
- N. Lysenko, P. Roy and R. Waeber (2009). Multivariate extremes of generalized skew-normal distributions. *Statist. Probab. Let.* 79:525-533.

< 回 > < 三 > < 三 >

Early work goes back to 1960's...



Masaaki Sibuya

Balkema, Embrechts, Nolde

(日) (同) (三) (三)

For bivariate data, asymptotic independence means:

large values in one coordinate are unlikely to be accompanied by large values in the other coordinate

Definition (Sibuya's condition)

Let X and Y have continuous dfs F_1 and F_2 , resp.

Define a function P on $[0,1]^2$ via

$$P(F_1(x),F_2(y)) = \mathbb{P}\{X > x, Y > y\}$$

X and Y are asymptotically independent if and only if

P(1-s,1-s)=o(s) $s
ightarrow0^+$ [Sibuya (1960)]

・ロト ・ 母 ト ・ ヨ ト ・ ヨ ト … ヨ

Motivation (1/2): Relevance for applications

• The concept of asymptotic independence has been used in many applications

se.g. modelling of environmental, financial, and traffic network data

• Model risk: not being aware of the properties of a model with respect to extremal dependence may potentially lead to risk underestimation

8 e.g. the Gaussian copula model and the recent financial crisis

(4 回) (4 \Pi) (4 \Pi)

Motivation (2/2): Densities vs. distribution functions (dfs)

- "Simple" to check asymptotic independence using dfs as the standard criteria are given in terms of dfs
- However, explicit expressions for dfs are not always available
- Typically we are given a density in analytic form
- For a light-tailed density, the shape of sample clouds may give a good geometric image of the asymptotic shape of its level sets

(1日) (日) (日) (日)

Motivation (2/2): Densities vs. distribution functions (dfs)

- "Simple" to check asymptotic independence using dfs as the standard criteria are given in terms of dfs
- However, explicit expressions for dfs are not always available
- Typically we are given a density in analytic form
- For a light-tailed density, the shape of sample clouds may give a good geometric image of the asymptotic shape of its level sets

Objective:

Give sufficient conditions for asymptotic independence in terms of the (asymptotic) shape of the level sets of the density or of suitably scaled sample clouds

< ロ > < 同 > < 回 > < 回 > < 回 > <

The class $\mathcal{A}(D)$

- \mathcal{D}_d : the class of all bounded open star-shaped sets $D \subset \mathbb{R}^d$ for which
 - **#** the cone $D_{\infty} = \bigcup_{n>0} nD$ is convex
 - **\$** the gauge function n_D is continuous on D_∞
- A positive density g on \mathbb{R}^d belongs to the class $\mathcal{A}(D)$ if
 - $\mathcal{B} \quad D \in \mathcal{D}_d$
 - ***** there exist sequences $c_n > 0$ and $r_n \to \infty$ with $c_{n+1}/c_n \to 0$ and $r_{n+1} \sim r_n$ such that for any $\epsilon > 0$ eventually

$$e^{-\epsilon}r_nD \subset \{g > c_n\} \subset e^{\epsilon}r_nD \qquad (\star)$$

- **#** Write $\{g > c_n\}/r_n \to D$
- A continuous positive function g̃ is shape equivalent to g if its level sets satisfy (*)

イロト 不得下 イヨト イヨト 三日

The class $\mathcal{A}(D)$: Shape-equivalent densities

• How large is the class $\mathcal{A}(D)$?

Proposition:

Suppose $f_* = e^{-\varphi}$, where φ is continuous, strictly increasing and varies regularly at ∞ with exponent $\theta > 0$

Then $g = e^{-\gamma} \in \mathcal{A}(D)$ is shape equivalent to $f = f_*(n_D)$ if and only if $\gamma(\mathbf{x}_n) \sim \varphi(n_D(\mathbf{x}_n))$ whenever $||\mathbf{x}_n|| \to \infty$

|山田 | 小田 | (田)

The class $\mathcal{A}(D)$: Shape-equivalent densities (cont'd)

• The behaviour of the quotient of two shape equivalent functions may be quite erratic

Examples: $\tilde{f} = qf$ is shape equivalent to standard normal density f on \mathbb{R}^2 for the following choices of q:



ヘロト 人間 とくほ とくほ とう

Criteria for asymptotic independence - I

Definition

The set $D \in D_2$ is blunt if the coordinatewise supremum of the points in D does not lie in the closure of D

.

Criteria for asymptotic independence - I

Definition

The set $D \in D_2$ is blunt if the coordinatewise supremum of the points in D does not lie in the closure of D

Theorem 1

• Suppose $X = (X_1, \dots, X_d)$ has density $f \in \mathcal{A}(D)$

If the bivariate projection D_{12} of the set D on x_1, x_2 -plane is blunt, then X_1 and X_2 are asymptotically independent

Criteria for asymptotic independence - II

Theorem 2

- X_1, X_2, \ldots i.i.d. observations from a continuous df F on \mathbb{R}^2
- Suppose there exist scaling constants s_n such that the sample clouds $N_n = \{\mathbf{X}_1/s_n, \dots, \mathbf{X}_n/s_n\}$ converge onto the closure of $D \in \mathcal{D}_2$

If D is blunt then the two coordinates of the vector \boldsymbol{X}_1 are asymptotically independent

Proof of Theorem 2 - outline

• Let
$$\mathbf{b} = (b_1, b_2) := \sup D$$

 D blunt $\Rightarrow \exists \delta > 0: (e^{-\delta}\mathbf{b}, \infty) \cap e^{\delta}D = \emptyset$

• Let $n\pi_n$ denote the mean measure of N_n

$$n\pi_n(e^{-\delta}\mathbf{b},\infty) \le n\pi_n(e^{\delta}D)^c \to 0$$

$$n\pi_n(D \cap \{u > e^{-\delta}b_1\}) \to \infty$$

$$n\pi_n(D \cap \{v > e^{-\delta}b_2\}) \to \infty$$



since N_n converges onto D

• Let $\mathbf{W}_n = (U_n, V_n)$ denote the componentwise maximum of N_n $\mathbb{P}\{\mathbf{W}_n \in N_n\} \leq \mathbb{P}\{N_n((e^{-\delta}\mathbf{b}, \infty)) > 0\}$ $+ \mathbb{P}\{N_n(\{u > e^{-\delta}b_1\}) = 0\} + \mathbb{P}\{N_n(\{v > e^{-\delta}b_2\}) = 0\} \rightarrow 0$

[criterion due to Gnedin (1994)]

Example

• A *d*-dimensional skew-normal distribution with positive-definite scale matrix $\Omega \in \mathbb{R}^{d \times d}$ and shape parameter $\alpha \in \mathbb{R}^d$ has a density of the form

$$g(\mathbf{x}) = 2\phi_d(\mathbf{x}; \mathbf{0}, \Omega) \Phi(\boldsymbol{\alpha}^T \mathbf{x}) \qquad \mathbf{x} \in \mathbb{R}^d$$

where $\phi_d(\cdot; \mu, \Sigma)$ and $\Phi(\cdot)$ denote the *d*-dimensional normal density with mean μ and covariance matrix Σ , and the univariate standard normal df, resp.

• It can be shown that $g \in \mathcal{A}(D)$ with $D = \{\mathbf{u} \in \mathbb{R}^d \mid n_D(\mathbf{u}) < 1\}$, where

$$n_D(\mathbf{u}) = \begin{cases} \mathbf{u}^T \Omega^{-1} \mathbf{u}, & \boldsymbol{\alpha}^T \mathbf{u} \ge \mathbf{0}, \\ \mathbf{u}^T \Omega^{-1} \mathbf{u} + (\boldsymbol{\alpha}^T \mathbf{u})^2, & \boldsymbol{\alpha}^T \mathbf{u} < \mathbf{0} \end{cases}$$

- *D* has blunt bivariate projections (in fact, convex with *C*¹ boundary) and hence the skew-normal distribution is asymptotically independent
 - **%** cf. [Lysenko, Roy, Waeber (2009)]

・ロト ・ 四ト ・ ヨト

Future work:

- A more delicate question is the relation between the shape and asymptotic independence when the bivariate projections are not blunt
- Criteria for asymptotic dependence for light-tailed densities

Additional references

- Balkema, G., and Embrechts, P. (2007). *High Risk Scenarios and Extremes. A geometric approach.* European Mathematical Society.
- Gnedin, A.V. (1994). On the best choice problem with dependent criteria. *J. Appl. Probab.* 31:221-234.
- Sibuya, M. (1960). Bivariate extreme statistics. *Ann. Inst. Stat. Math.* 11:195-210.

Thank you!

3

・ロト ・聞ト ・ヨト ・ヨト