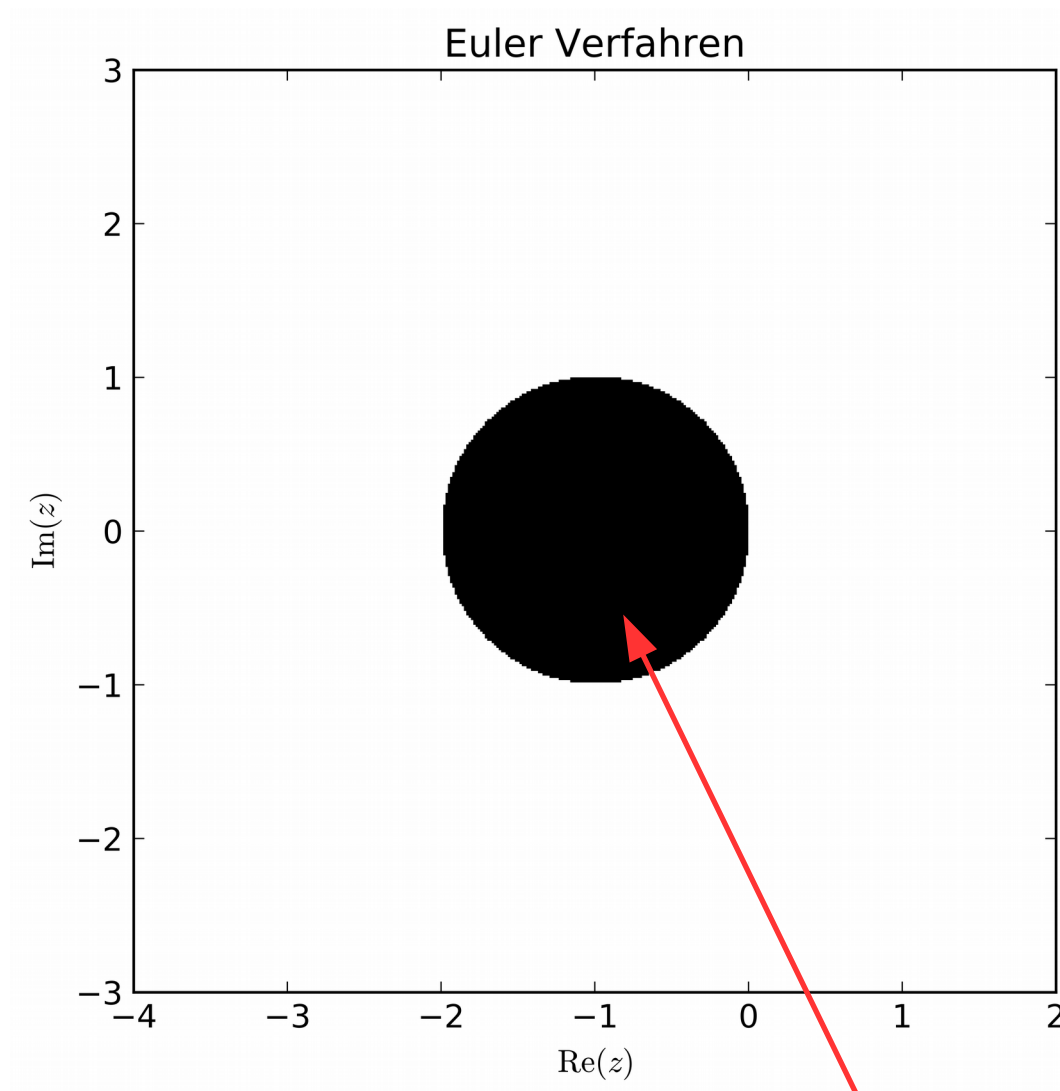
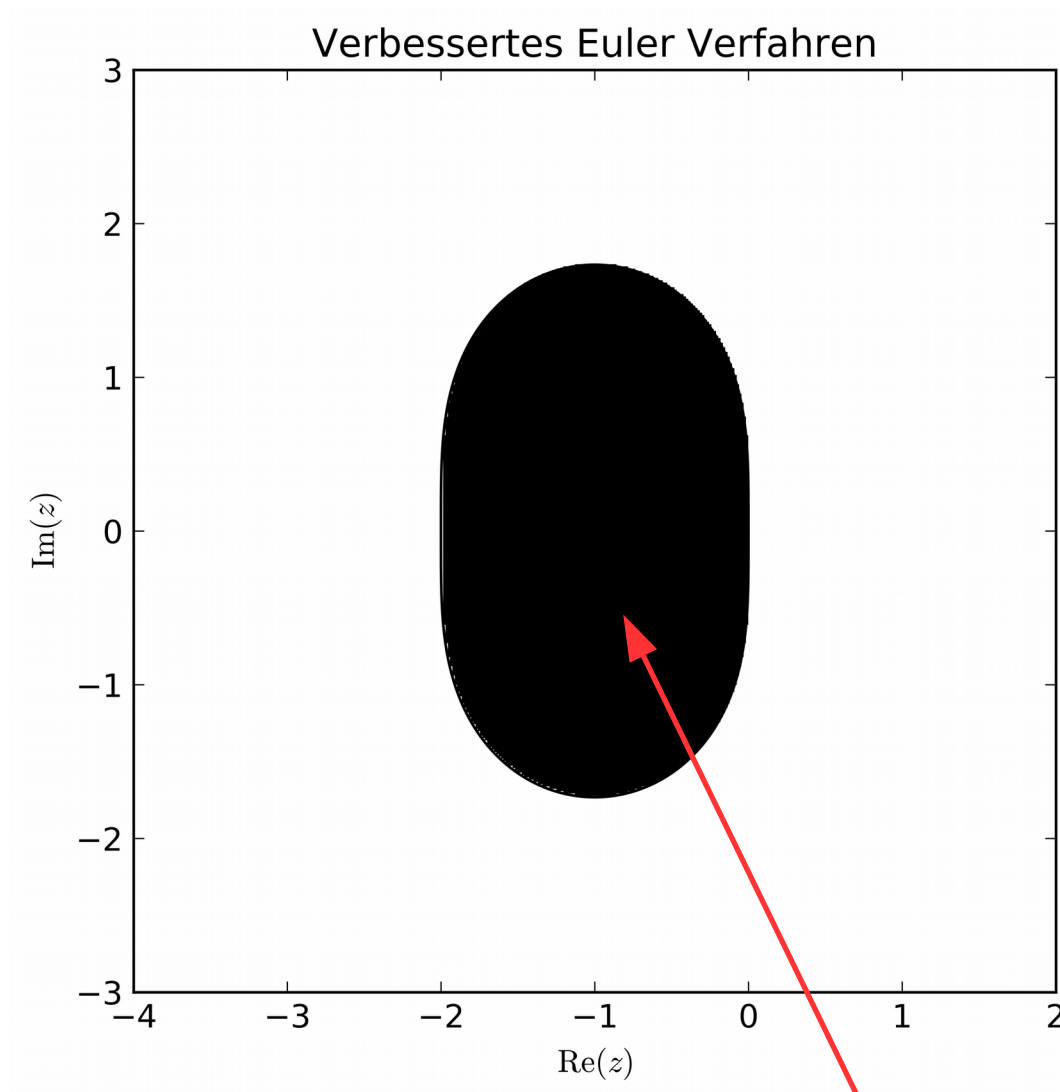


# Stabilitätsgebiete



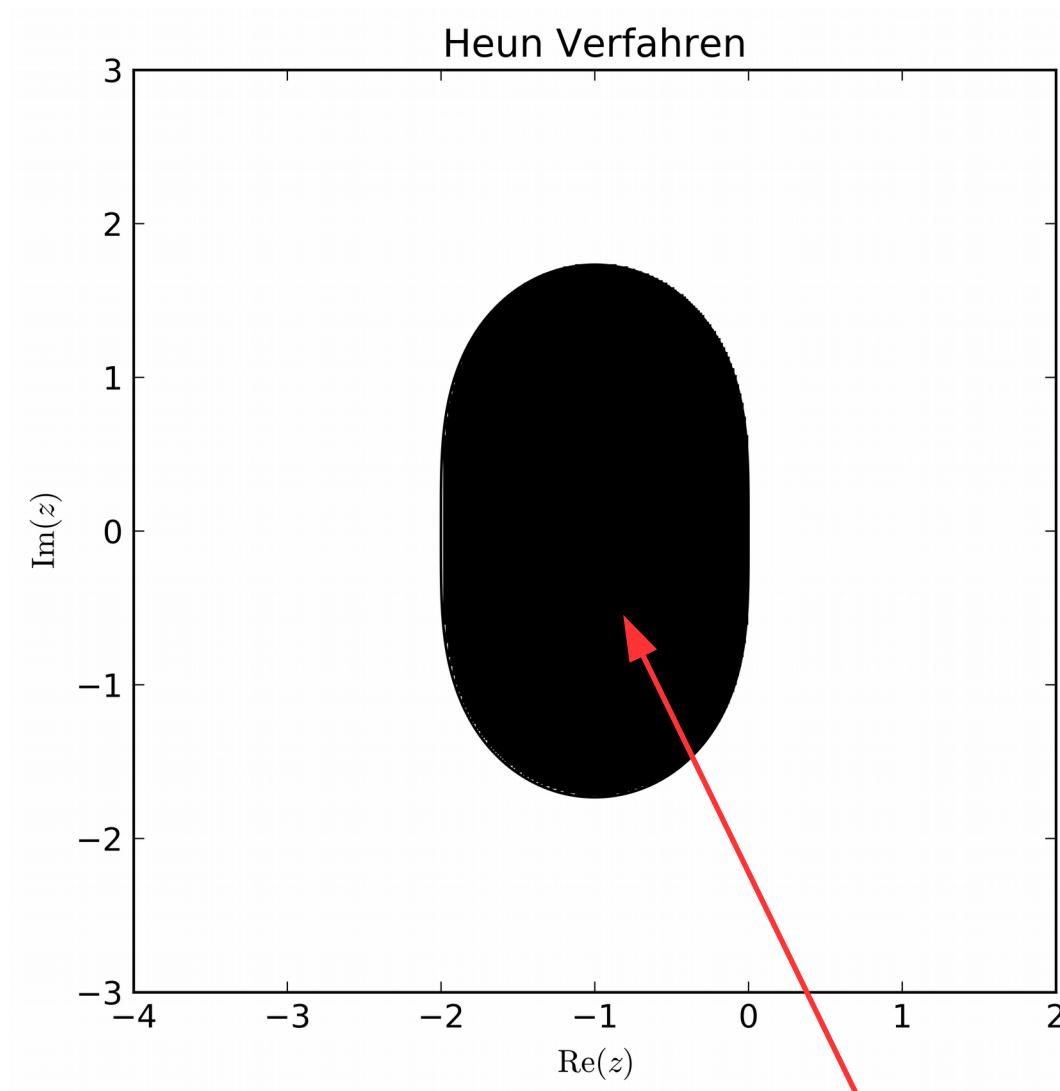
**Stabilitätsgebiet**

# Stabilitätsgebiete



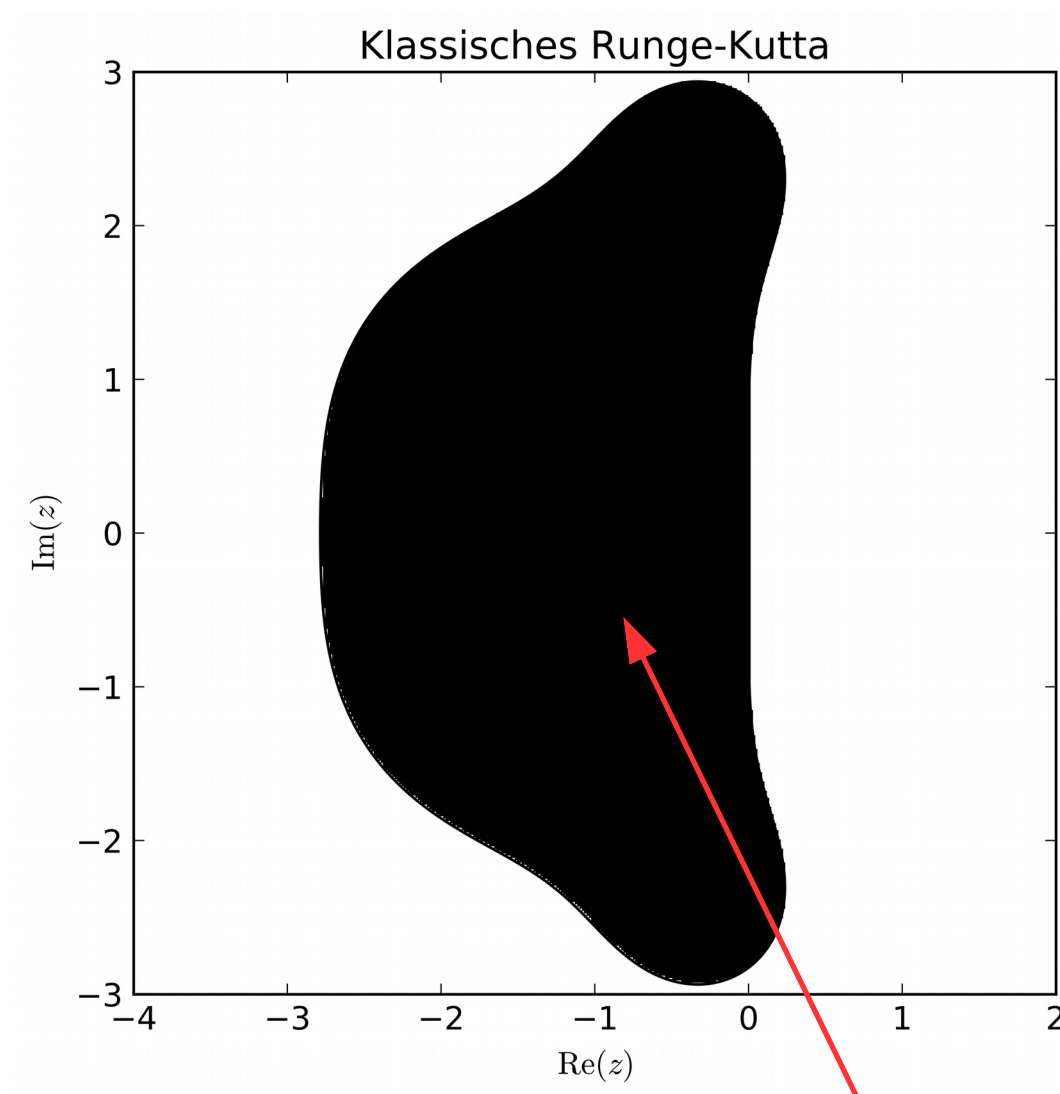
**Stabilitätsgebiet**

# Stabilitätsgebiete



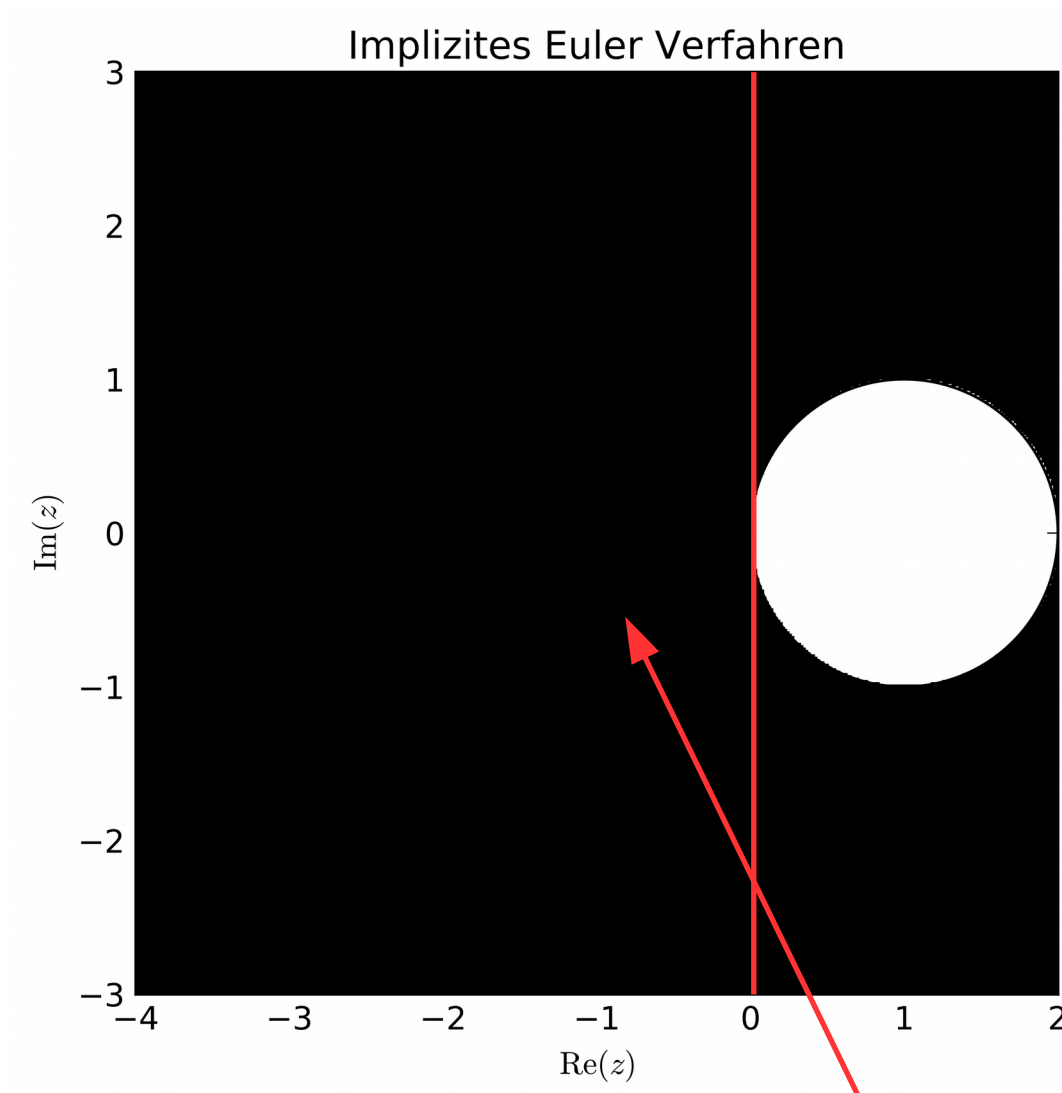
**Stabilitätsgebiet**

# Stabilitätsgebiete



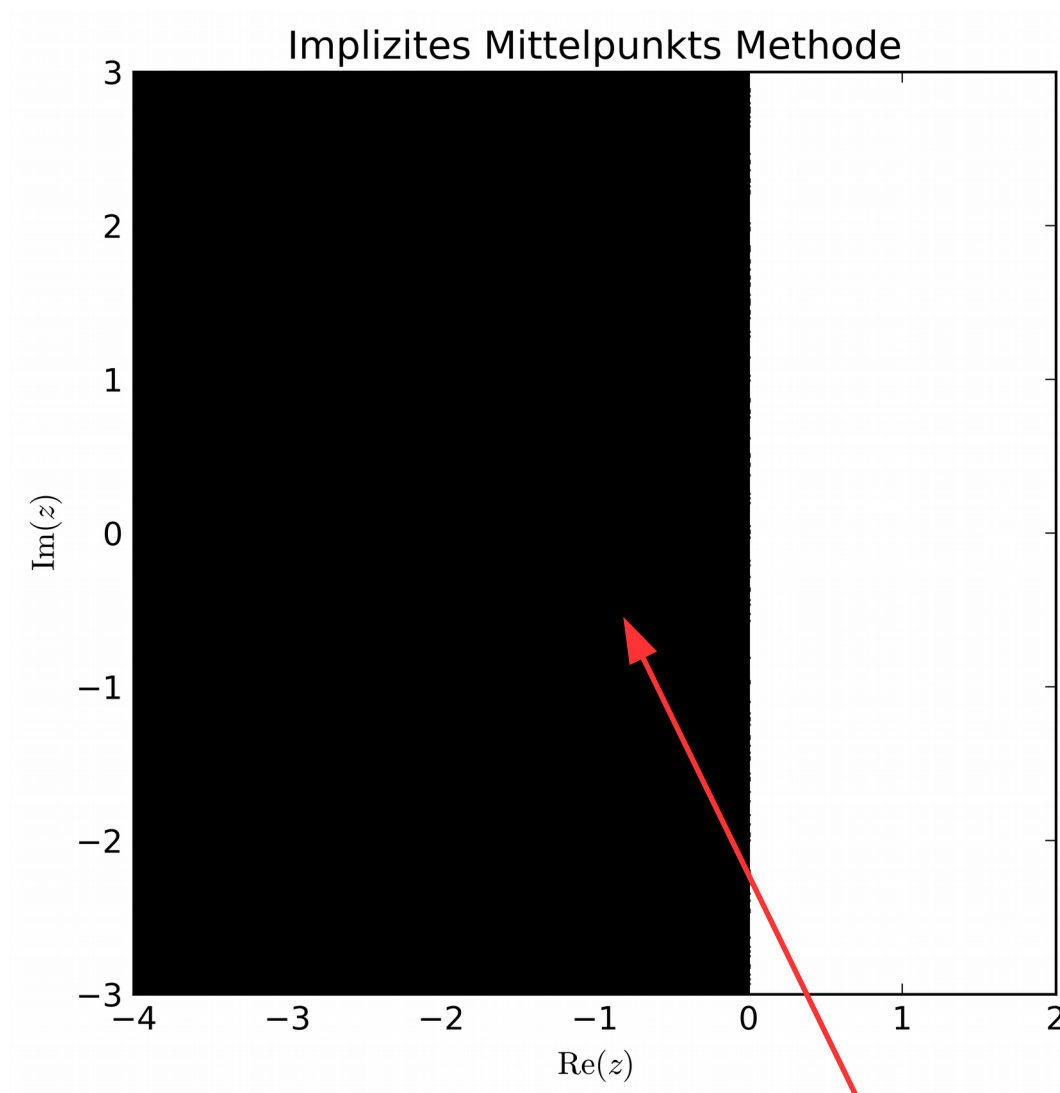
**Stabilitätsgebiet**

# Stabilitätsgebiete



**Stabilitätsgebiet**

# Stabilitätsgebiete



**Stabilitätsgebiet**

# Steifes lineares AWP

$$\dot{\mathbf{y}}(t) = A\mathbf{y}(t)$$

$$\mathbf{y} = \begin{pmatrix} y_1(t) \\ y_2(t) \\ y_3(t) \end{pmatrix} \quad A = \begin{pmatrix} -\frac{1}{2} & -\frac{869}{10} & \frac{1521}{5} \\ 0 & -\frac{227}{2} & \frac{591}{2} \\ 0 & \frac{591}{2} & -\frac{1803}{2} \end{pmatrix}$$

$$\mathbf{y}_0 = \begin{pmatrix} 1 \\ 6 \\ 2 \end{pmatrix} \quad 0 \leq t \leq 2$$

# Steifes lineares AWP

$$\begin{aligned}\dot{\mathbf{y}}(t) &= A\mathbf{y}(t) \\ &= PDP^{-1}\mathbf{y}(t)\end{aligned}$$

↑  
Diagonal!

D.h. „von Links“

×  $P^{-1}$  →

$$P^{-1}\dot{\mathbf{y}}(t) = D \underbrace{P^{-1}\mathbf{y}(t)}_{\mathbf{z}(t)}$$

$$\dot{\mathbf{z}}(t) = D\mathbf{z}(t) \quad \text{ENTKOPPELT!!!}$$



# Steifes lineares AWP

Durch rechnen (z.B. mit einem CAS!):

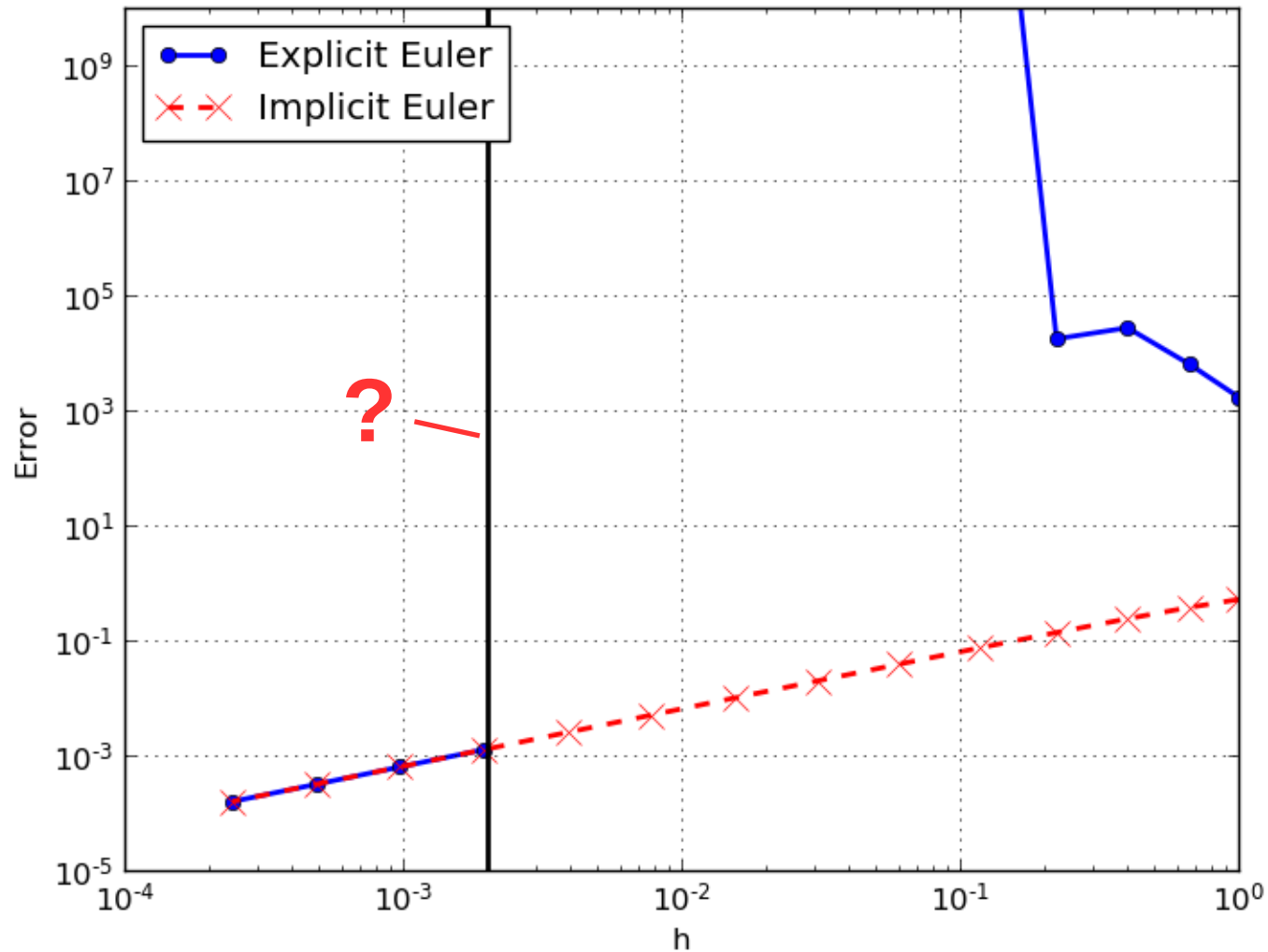
$$D = \begin{pmatrix} -\frac{1}{2} & 0 & 0 \\ 0 & -15 & 0 \\ 0 & 0 & -1000 \end{pmatrix}$$

$$P = \begin{pmatrix} 15 & -12 & 1 \\ 0 & 12 & 1 \\ 0 & 4 & -3 \end{pmatrix} \quad P^{-1} = \begin{pmatrix} \frac{1}{15} & \frac{4}{75} & \frac{1}{25} \\ 0 & \frac{3}{40} & \frac{1}{40} \\ 0 & \frac{1}{10} & -\frac{3}{10} \end{pmatrix}$$

Durch einsetzen der AW:

$$\mathbf{y}(t) = \begin{pmatrix} 7e^{-\frac{1}{2}t} - 6e^{-15t} \\ 6e^{-15t} \\ 2e^{-15t} \end{pmatrix}$$

# Steifes lineares AWP



# Steifes nichtlineares AWP

$$\dot{y}_A = -0.1y_A + 100y_B y_C$$

$$\dot{y}_B = +0.1y_A - 100y_B y_C - 500y_B^2$$

$$\dot{y}_C = +500y_B^2 - 0.5y_C$$

$$y_A(0) = 0.5 \quad y_B(0) = 0.5 \quad y_C(0) = 0.5$$

$$0 \leq t \leq 1$$

# Steifes nichtlineares AWP

$$\dot{y}_A = -0.1y_A + 100y_B y_C$$

$$\dot{y}_B = +0.1y_A - 100y_B y_C - 500y_B^2$$

$$\dot{y}_C = +500y_B^2 - 0.5y_C$$

NICHTLINEAR!!!

$$\mathbf{y} = \begin{pmatrix} y_A \\ y_B \\ y_C \end{pmatrix} \quad \mathbf{f}(x, \mathbf{y}) = \begin{pmatrix} -0.1y_A + 100y_B y_C \\ +0.1y_A - 100y_B y_C - 500y_B^2 \\ +500y_B^2 - 0.5y_C \end{pmatrix}$$

$$y_A(0) = 0.5 \quad y_B(0) = 0.5 \quad y_C(0) = 0.5 \quad \mathbf{y}_0 = \begin{pmatrix} 0.5 \\ 0.5 \\ 0.5 \end{pmatrix}$$

# Steifes nichtlineares AWP

## Steif?

Linearisieren wir die rechte Seite der DGL:

$$\mathbf{f}(t, \mathbf{y}) = \begin{pmatrix} -0.1y_A + 100y_B y_C \\ +0.1y_A - 100y_B y_C - 500y_B^2 \\ +500y_B^2 - 0.5y_C \end{pmatrix}$$

$$\mathbf{f}(t, \mathbf{y}) \approx \mathbf{f}(t_1, \mathbf{y}_1) + \underbrace{\frac{\partial \mathbf{f}}{\partial t}(t_1, \mathbf{y}_1)}_0 + \underbrace{\frac{\partial \mathbf{f}}{\partial \mathbf{y}}(t_1, \mathbf{y}_1)}_{/}$$

$$J(t, \mathbf{y}) = \frac{\partial \mathbf{f}}{\partial \mathbf{y}}(t, \mathbf{y}) = \begin{pmatrix} -0.1 & 100y_C & 100y_B \\ +0.1 & -1000y_B - 100y_C & -100y_B \\ 0 & 1000y_B & -0.5 \end{pmatrix}$$

# Steifes nichtlineares AWP

## Lokal Steif?

Linearisieren wir um den AW:  $t_0 = 0$   $\mathbf{y}_0 = \begin{pmatrix} 0.5 \\ 0.5 \\ 0.5 \end{pmatrix}$

$$J(t_0, \mathbf{y}_0) = \frac{\partial \mathbf{f}}{\partial \mathbf{y}}(t_0, \mathbf{y}_0) = \begin{pmatrix} -0.1 & 50 & 50 \\ +0.1 & -550 & -50 \\ 0 & 500 & -0.5 \end{pmatrix}$$

MATLAB: eig  $\longrightarrow$

$$\lambda_1 \approx -5.00 \times 10^2$$
$$\lambda_2 \approx -9.87 \times 10^{-4}$$
$$\lambda_3 \approx -5.07 \times 10^1$$

$$S = \frac{\max_j |\operatorname{Re}(\lambda_j)|}{\min_j |\operatorname{Re}(\lambda_j)|} \approx 5.06 \times 10^5 \quad \mathbf{JA!!!}$$