

C++ code 2.14.24: Sub-problem (2-14.u): Implementation of `solveCRNeumannBVP()`,
→ [GitLab](#)

```
2 template <typename GAMMA_COEFF, typename F_FUNCTOR>
3 Eigen::VectorXd solveCRNeumannBVP(std::shared_ptr<CRFeSpace> fe_space,
4                                   GAMMA_COEFF &&gamma, F_FUNCTOR &&f) {
5     Eigen::VectorXd sol;
6     // TODO: task 2-14.u)
7     // Obtain local to global index mapping for shape functions
8     const If::assemble::DofHandler &dof_handler{fe_space->LocGlobMap()};
9     const size_type num_dofs = dof_handler.NumDofs();
10    // Prepare coefficient and source functions as MeshFunction
11    If::mesh::utils::MeshFunctionGlobal mf_one{
12        [](Eigen::Vector2d x) -> double { return 1.; }};
13    If::mesh::utils::MeshFunctionGlobal mf_gamma{gamma};
14    If::mesh::utils::MeshFunctionGlobal mf_f{f};
15    // Sparse Galerkin matrix in triplet format
16    If::assemble::COOMatrix<double> A(num_dofs, num_dofs);
17    // Initialize ELEMENT_MATRIX_PROVIDER object
18    If::uscalfe::ReactionDiffusionElementMatrixProvider<double, decltype(mf_one),
19                                                         decltype(mf_gamma)>
20        element_matrix_builder(fe_space, mf_one, mf_gamma);
21    // Fill Galerkin matrix (create array of triplets)
22    If::assemble::AssembleMatrixLocally(0, dof_handler, dof_handler,
23                                         element_matrix_builder, A);
24    // Right-hand-side vector; do not forget to set to zero!
25    Eigen::Matrix<double, Eigen::Dynamic, 1> phi(num_dofs);
26    phi.setZero();
27    // Initialize ELEMENT_VECTOR_PROVIDER object
28    If::uscalfe::ScalarLoadElementVectorProvider<double, decltype(mf_f)>
29        load_vector_builder(fe_space, mf_f);
30    // Fill right-hand-side vector (cell oriented assembly)
31    If::assemble::AssembleVectorLocally(0, dof_handler, load_vector_builder, phi);
32    // Set up Galerkin matrix in CRS format
33    Eigen::SparseMatrix<double> A_crs = A.makeSparse();
34    // ... and solve the linear system of equations by Gaussian elimination
35    Eigen::SparseLU<Eigen::SparseMatrix<double>> solver;
36    solver.compute(A_crs);
37    sol = solver.solve(phi);
38    return sol;
39 }
```