

C++ code 5.2.53: Implementation of `brachistochrone()` → [GitLab](#)

```
2 template <typename RECORDER = std::function<
3     void(const Eigen::Matrix<double, 2, Eigen::Dynamic> &>>
4 Eigen::Matrix<double, 2, Eigen::Dynamic> brachistochrone(
5     unsigned int M, Eigen::Vector2d a, Eigen::Vector2d b, double atol,
6     double rtol, unsigned int itmax,
7     RECORDER &&rec = [] (const Eigen::Matrix<double, 2, Eigen::Dynamic> &)
8     -> void { return; }) {
9     // Initialize knots
10    Eigen::Matrix<double, 2, Eigen::Dynamic> knots(2, M + 1);
11    // Linear interpolant as initial guess
12    for (int i = 0; i <= M; ++i) {
13        double s = static_cast<double>(i) / M;
14        knots.col(i) = (1.0 - s) * a + s * b;
15    }
16    Eigen::Matrix<double, 2, Eigen::Dynamic> knots_prev = knots;
17    // Record the initial conditions of the knots
18    rec(knots);
19    // Perform the fixed point-iteration
20    unsigned int q = 0;
21    do {
22        // Store the previous knots data for comparison later
23        knots_prev = knots;
24
25        // Compute R-matrix and RHS
26        Eigen::SparseMatrix<double> R = matR(knots);
27        Eigen::VectorXd rhs = compute_rhs(knots, a, b);
28        // Initialize the LU solver
29        Eigen::SparseLU<Eigen::SparseMatrix<double>> solver;
30        // Do LU decomposition once
31        solver.compute(R);
32        if (solver.info() != Eigen::Success) {
33            std::cerr << "Cannot factorize R!" << std::endl;
34            return knots;
35        }
36        // Solve the first system
37        Eigen::VectorXd uh = solver.solve(rhs.segment(0, M - 1));
38        for (int i = 0; i < M - 1; ++i) knots(0, i + 1) = uh(i);
39        // Solve the second system
40        Eigen::VectorXd uh2 = solver.solve(rhs.segment(M - 1, M - 1));
41        for (int i = 0; i < M - 1; ++i) knots(1, i + 1) = uh2(i);
42        // Update and record
43        rec(knots);
44        // Abort when max iterations is reached or error is small enough.
45    } while ((++q < itmax) &&
46            (Brachistochrone::L2norm(knots - knots_prev) >
47             std::min<double>(atol, rtol * Brachistochrone::L2norm(knots))));
48
49    // Output a warning if fixed-point iteration was aborted because max
50    // iterations was reached.
51    if (q == itmax)
52        std::cout << "M = " << M
53                  << " : Max iterations reached. Truncated with L2 error: "
54                  << L2norm(knots - knots_prev) << "\n";
55    return knots;
56 };
```