

ETH Lecture 401-0674-00L Numerical Methods for Partial Differential Equations

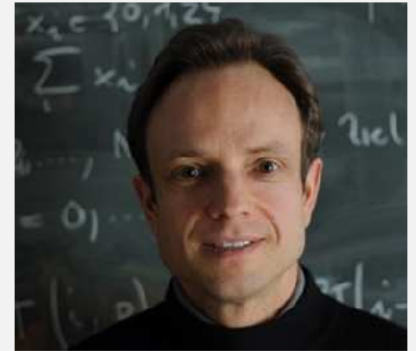
Course Video

Section 13.2.1: Cochain Calculus

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(C) Seminar für Angewandte Mathematik, ETH Zürich



Prerequisites.

- Elementary linear algebra, matrix calculus

Dependencies. [Lecture → Section 2.5.1], [Lecture → Section 2.7.2.2], [Lecture → Section 13.1.2], [Lecture → Section 13.1.4]

Duration: minutes



Video and accompanying tablet notes may not match completely!

[Corrections and updates may have been made in tablet notes.]

XIII Finite - Element Exterior Calculus (FEEC)

13.2 Discrete Differential Forms

Goal: FE subspaces of $H^1(d, \Omega)$, $0 \leq l \leq d$

13.2.1. Cochain Calculus

→ discrete integral forms

13.2.1.1. Meshes and Cochain

$$\begin{array}{l} |F : \\ (\text{Def 13.1.2.7}) \end{array} \quad \underline{\omega} : S_\ell(\Omega) \longrightarrow \mathbb{R}$$



Introduce **discrete integral ℓ -forms** as mappings from a **finite** subset of $S_\ell(\Omega)$ into $\mathbb{R}$.

suitable: meaningful $\mathcal{I}$

▷ Use FE mesh (Def 2.5.1.1.)

Definition 13.2.1.1. Generalized oriented meshes

A **generalized oriented mesh** $\mathcal{M}$ of a domain $\Omega \subset \mathbb{R}^d$ is a collection of sets of **ℓ -facets**,

$$\mathcal{M} := (\mathcal{F}_\ell(\mathcal{M}))_{\ell=0}^d$$

such that

- (i) $\mathcal{F}_\ell(\mathcal{M}) \subset \mathcal{S}_\ell(\Omega)$: every ℓ -facet $f \in \mathcal{F}_\ell(\mathcal{M})$ is an oriented (*), relatively **open**, bounded, ℓ -dimensional, **non-degenerate**^a C^1_{pw} -surface $\subset \mathbb{R}^d$,
- (ii) the facets form a **partition** of $\overline{\Omega}$:

$$\overline{\Omega} = \bigcup_{\ell=0}^d \bigcup_{F \in \mathcal{F}_\ell(\mathcal{M})} F, \quad f \cap f' = \emptyset \quad \forall f \in \mathcal{F}_j(\mathcal{M}), f' \in \mathcal{F}_k(\mathcal{M}), k, j \in \{0, \dots, d\},$$

- (iii) for every $F \in \mathcal{F}_\ell(\mathcal{M})$, $0 < \ell \leq d$, its boundary ∂F is the union of the closures of finitely many $\ell - 1$ -facets:

$$\forall F \in \mathcal{F}_\ell(\mathcal{M}): \exists \{f_1, \dots, f_m\} \subset \mathcal{F}_{\ell-1}(\mathcal{M}) \quad \text{such that} \quad \partial F = \overline{f_1} \cup \dots \cup \overline{f_m},$$

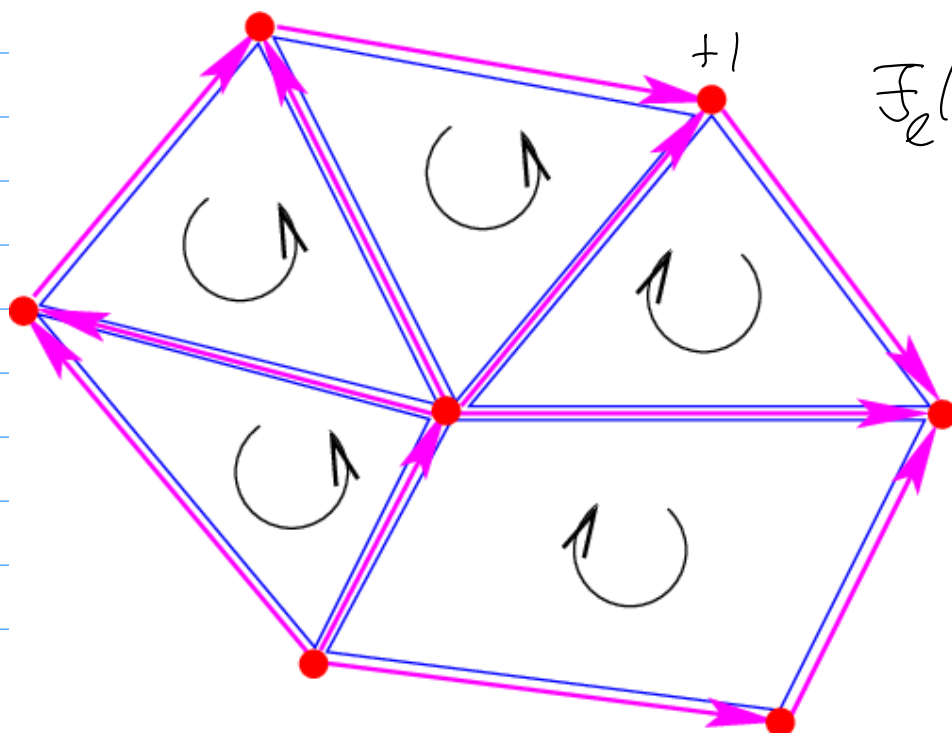
- (iv) the intersection of the closures of any two ℓ -facets is an $\ell - 1$ -facet,

$$\forall \ell \in \{1, \dots, d\}, \quad \forall f, f' \in \mathcal{F}_\ell(\mathcal{M}): \quad \overline{f} \cap \overline{f'} \in \mathcal{F}_{\ell-1}(\mathcal{M}),$$

- (v) for every $f \in \mathcal{F}_\ell(\mathcal{M})$, $0 \leq \ell < d$, there is a $F \in \mathcal{F}_{\ell+1}(\mathcal{M})$ such that $f \subset \partial F$.

^aAn ℓ -dimensional sub-manifold $\subset \mathbb{R}^d$ is called non-degenerate, if it has non-zero ℓ -dimensional volume.

Ex : $d = 2$



$$\mathcal{F}_\ell(\mathcal{M}) = \begin{cases} \text{cells, } \ell=2 \\ \text{edge, } \ell=1 \\ \text{node, } \ell=0 \end{cases}$$

Special case : simplicial meshes*

$d=2$: triangular , $d=3$ tetrahedral

* All ℓ -facets are ℓ -simplices = convex hull of $\ell+1$ nodes.

$$\sum [x_0, \dots, x_{\ell+1}]$$

↑ ordering determines orientation

Definition 13.2.1.7. Cochains

Given a generalized oriented mesh $\mathcal{M} = (\mathcal{F}_\ell)_{\ell=0}^d$ of a domain $\Omega \subset \mathbb{R}^d$ an ℓ -cochain $\vec{\omega}$ is a mapping $\vec{\omega} : \mathcal{F}_\ell(\mathcal{M}) \rightarrow \mathbb{R}$.

Notation : $C^\ell(\mathcal{M}) \stackrel{\text{def}}{=} \text{vector space}$
 $\langle \vec{\omega}, f \rangle := \vec{\omega}(f), \quad \vec{\omega} \in C^\ell(\mathcal{M}), f \in \mathcal{F}_\ell(\mathcal{M})$

$$\mathcal{F}_\ell(\mathcal{M}) = \{f_1, \dots, f_{N_\ell}\}, \quad N_\ell = \#\mathcal{F}_\ell(\mathcal{M})$$

$$\rightarrow C^\ell(\mathcal{M}) \cong \mathbb{R}^{N_\ell} \quad \text{by} \quad (\vec{\omega})_i := \langle \vec{\omega}, f_i \rangle$$

13.2.1.2. Discrete exterior Derivative

$$\text{IF: } \langle \underline{d}_\ell \underline{\omega}, T \rangle = \langle \underline{\omega}, \underset{\substack{\uparrow \\ \text{w/ induced orientation}}}{\mathcal{T}T} \rangle, \quad T \in \mathcal{F}_{\ell+1}(\mathcal{M})$$

$$CC: \quad \vec{\omega} \in C^k(\mathcal{M})$$

additive

$$\langle \vec{\omega}, F \rangle = \langle \vec{\omega}, \partial F \rangle = \sum_{i=1}^m \pm \langle \vec{\omega}, f_i \rangle$$

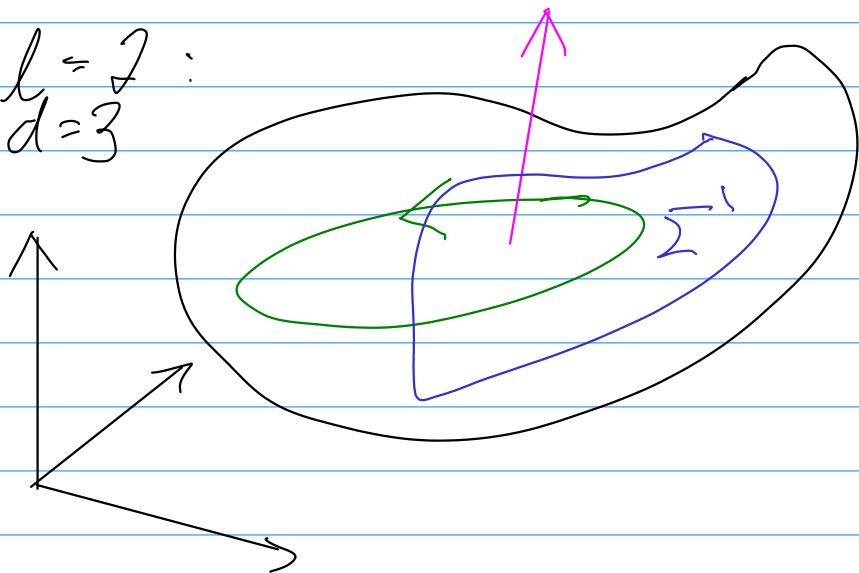
$$\forall F \in \mathcal{F}_{e+1}(\mathcal{M})$$

$$\text{Def. } \mathcal{M} \Rightarrow \partial F = \overline{f_1} \cup \dots \cup \overline{f_m}, f_i \in \mathcal{F}_0(\mathcal{M})$$

§ 13.2.1.8 Induced orientation of mesh facets

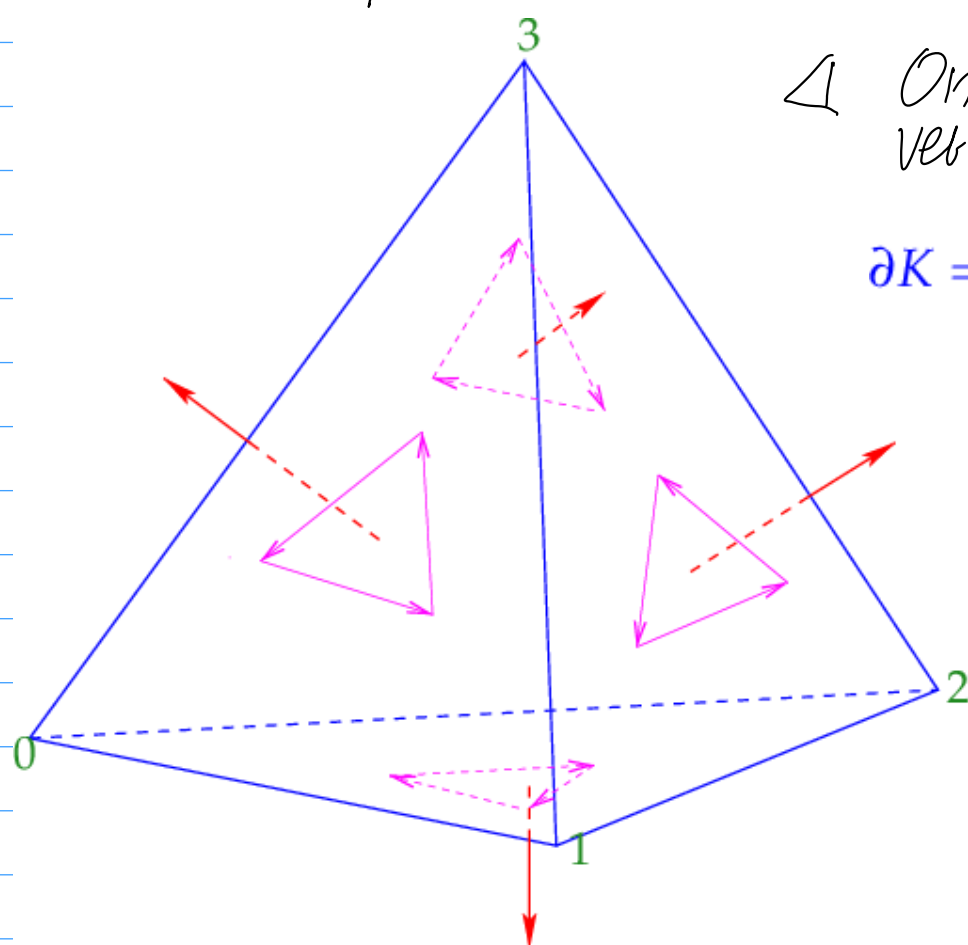
$$\Sigma, \Sigma' \in S_e(\Omega) : \Sigma' \subset \Sigma \Rightarrow \Sigma' \text{ inherits orientation}$$

$$l=2 : \\ d=3$$



$$F \in \mathcal{F}_{e+1}(\mathcal{M}) \subset S_{e+1}(\mathcal{M}) \Rightarrow f_i \subset \partial F \text{ inherits orientation from } \partial F \\ \text{[induced orientation]}$$

Ex: Simplex in 3D



△ Oriented by numbering vertices

$$\partial K = \Sigma[1,2,3] \cup \Sigma[0,3,2] \cup \Sigma[0,1,3] \cup \Sigma[0,2,1],$$

↑
w/ correct induced orientation

General combinatorial formula for simplex

$$\partial \Sigma[x_0, \dots, x_\ell] = \bigcup_{k=0}^{\ell} (-1)^k \Sigma[x_0, \dots, \cancel{x_k}, \dots, x_\ell], \quad (13.2.1.11)$$

face-simplex w/ induced orientation

§ 13.2.1.10 Relative orientation



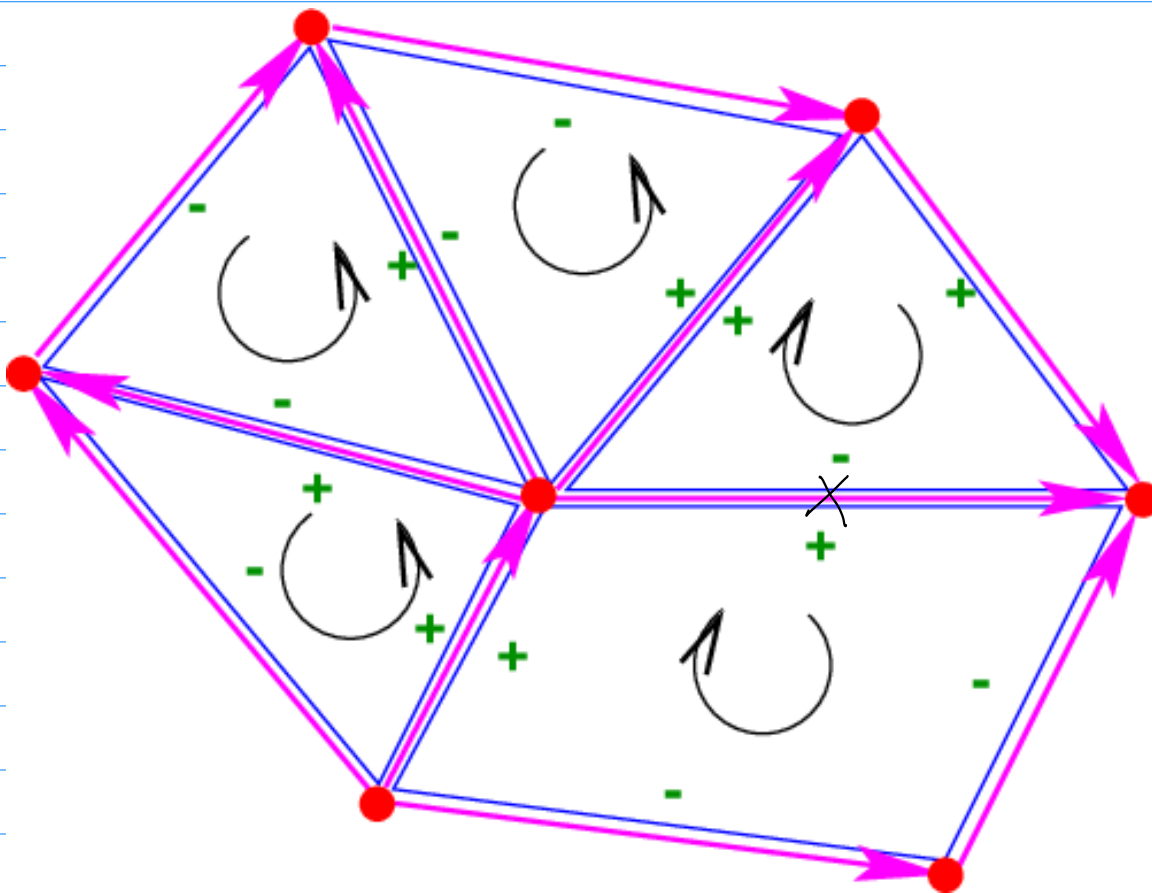
mismatch: intrinsic or. $\Leftrightarrow$ induced or.

Definition 13.2.1.13. Relative orientation of mesh facets

Given $F \in \mathcal{F}_\ell(\mathcal{M})$, $0 < \ell \leq d$, and $f \in \mathcal{F}_{\ell-1}(\mathcal{M})$, we define their **relative orientation** as

$$o_r(f, F) := \begin{cases} 1 & , \text{ if } f \subset F \text{ and the orientations of } f \text{ and } \partial F \text{ agree,} \\ -1 & , \text{ if } f \subset F \text{ and the orientations of } f \text{ and } \partial F \text{ are opposite,} \\ 0 & , \text{ if } f \not\subset \partial F. \end{cases}$$

2D example :



Definition 13.2.1.16. Exterior derivative for cochains

Given a generalized oriented mesh $\mathcal{M}$ of $\Omega \subset \mathbb{R}^d$ and $\ell \in \{0, \dots, d-1\}$, the **exterior derivative** $\vec{d}_\ell : \mathcal{C}^\ell(\mathcal{M}) \rightarrow \mathcal{C}^{\ell+1}(\mathcal{M})$ is defined by

$$\langle \vec{d}_\ell \vec{\omega}, F \rangle = \sum_{f \in \mathcal{F}_\ell(\mathcal{M})} o_r(f, F) \langle \vec{\omega}, f \rangle \quad \forall F \in \mathcal{F}_{\ell+1}(\mathcal{M}). \quad (13.2.1.17)$$

→ linear operator

$$C^e(\mathcal{M}) \cong \mathbb{R}^{N_e}, \quad N_e = \# \mathcal{F}_e(\mathcal{M})$$

Matrix representation $\mathbf{D}_e$ of $\vec{d}_e$:

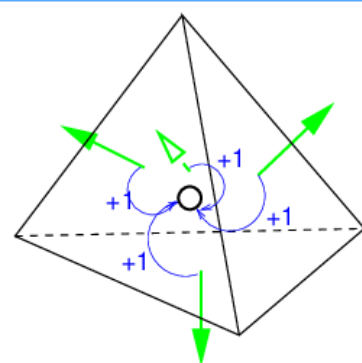
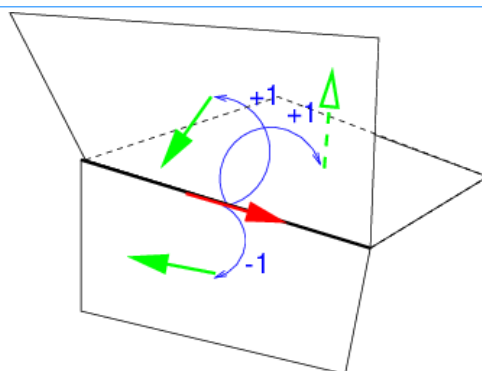
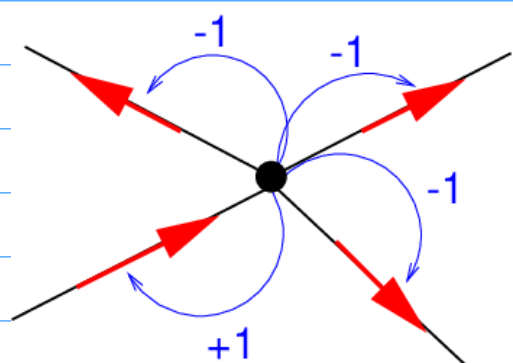
$$(\vec{d}_e \vec{\omega} = \mathbf{D}_e \vec{\omega})_i = \langle \vec{d}_e \vec{\omega}, F_i \rangle \stackrel{\text{def}}{=} \sum_{f \in \mathcal{F}_e(\mathcal{M})} o_r(f, F_i) \langle \vec{\omega}, f \rangle = \sum_{j=1}^{N_e} o_r(f_j, F_i) (\vec{\omega})_j. \quad \mathcal{M} \times V\text{-prod.}$$

$$\blacktriangleright \quad \mathbf{D}_e = [o_r(f_j, F_i)]_{\substack{i=1, \dots, N_{\ell+1} \\ j=1, \dots, N_e}} \in \{-1, 0, 1\}^{N_{\ell+1}, N_e} \quad \mathcal{F}_\ell(\mathcal{M}) = \{f_1, \dots, f_{N_e}\}, \quad \mathcal{F}_{\ell+1}(\mathcal{M}) = \{F_1, \dots, F_{N_{\ell+1}}\}. \quad (13.2.1.18)$$

$\Rightarrow \mathbf{D}_e$ sparse

$\mathbf{D}_e$: (signed) incidence matrices of $\mathcal{M}$

Stencil view:



$\mathbf{D}_0$: node-edge incidence matrix

$\mathbf{D}_1$: edge-face incidence matrix

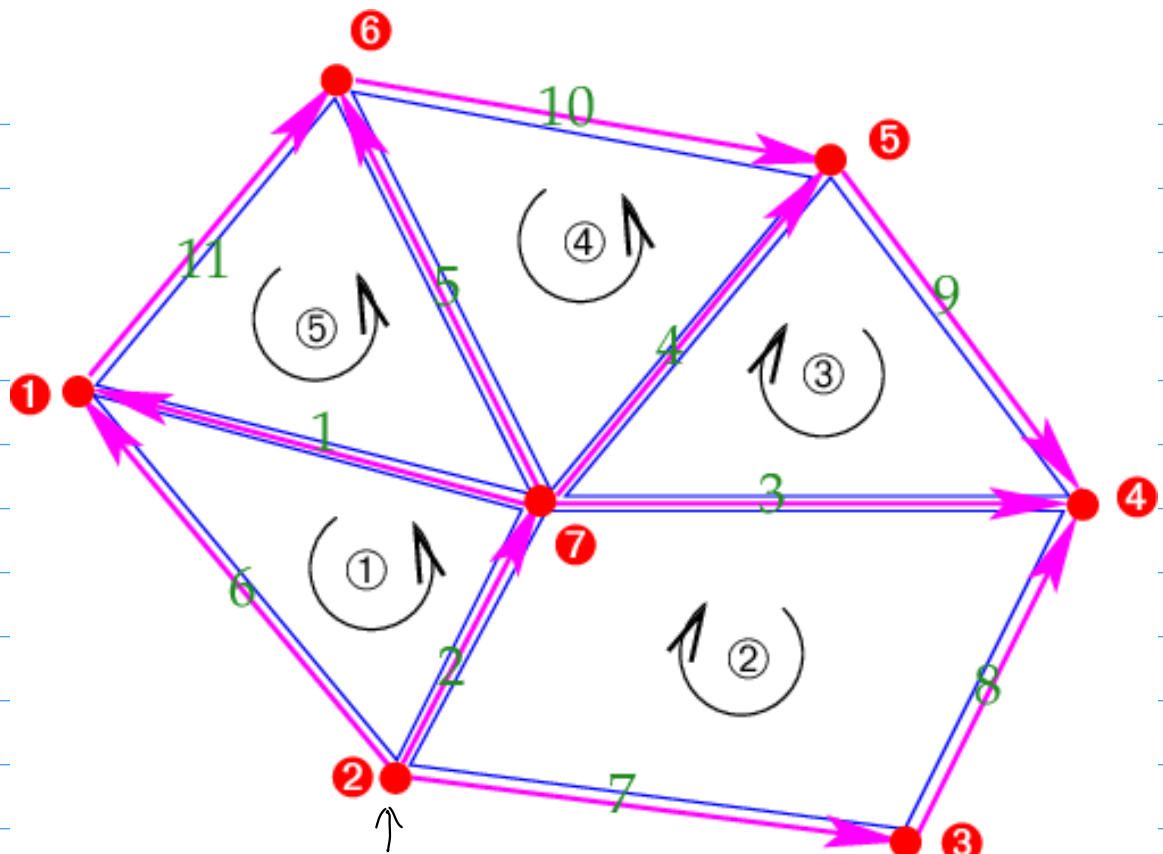
$\mathbf{D}_2$: face-cell incidence matrix

[discrete grad]

[discrete curl]

[discrete div]

9

 Ex: $d=2$


"node-edge":

$$\mathbf{D}_0 = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & -1 \\ 0 & -1 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 & 1 & 0 & -1 \\ 0 & 0 & 0 & 0 & 0 & 1 & -1 \\ 1 & -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 \\ -1 & 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix} \sim \text{edges}$$

~ nodes

"edge-cell":

$$\mathbf{D}_1 = \begin{bmatrix} 1 & 1 & 0 & 0 & 0 & -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & -1 & -1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & -1 & 0 & 0 & 0 & 0 & -1 & 0 \\ -1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & -1 \end{bmatrix} \sim \text{cells}$$

~ edges

Properties of $\vec{d}_\ell$

Theorem 13.2.1.21. $\vec{d} \circ \vec{d} = 0$

For any generalized mesh $\mathcal{M}$ of a domain $\Omega \subset \mathbb{R}^d$ and $\ell \in \{0, \dots, d-2\}$ holds true

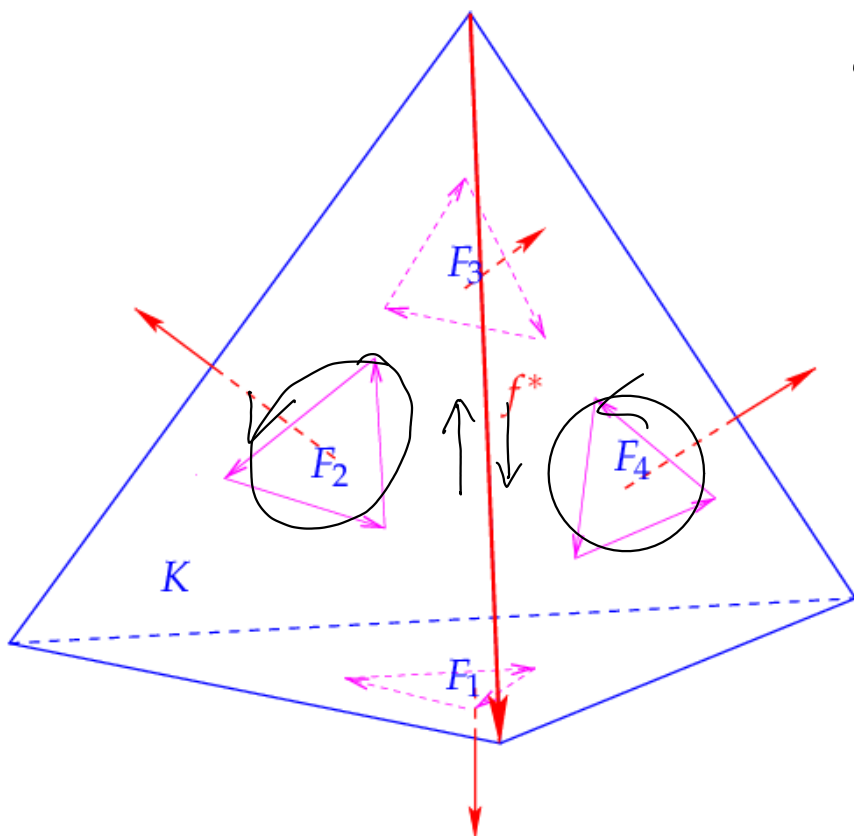
$$\vec{d}_{\ell+1} \circ \vec{d}_\ell = 0 \Leftrightarrow \mathbf{D}_{\ell+1} \mathbf{D}_\ell = \mathbf{0} \Leftrightarrow \mathcal{R}(\mathbf{D}_\ell) \subset \mathcal{N}(\mathbf{D}_{\ell+1}).$$

Idea of proof ($d=3, \ell=1$)

$$f^* \in \mathcal{F}_1(\mathcal{M}), \quad K \in \mathcal{F}_3(\mathcal{M}), \quad f^* \subset \partial K$$

$$\text{Compute } (\mathbf{D}_2 \mathbf{D}_1)_{K, f^*} = 0$$

↑
cancellation of
rel. ori.!



$$\ell = 1$$

Theorem 13.1.4.81. Existence of potentials

Let $\Omega \subset \mathbb{R}^d$ be a domain and $1 \leq \ell \leq d$. If

[every oriented, compact and closed ℓ -dimensional sub-manifold of $\in \mathcal{S}_\ell(\Omega)$ is the boundary of an $\ell + 1$ -dimensional sub-manifold $\in \mathcal{S}_{\ell+1}(\Omega)$,
then

$$\omega \in C^1 \Lambda^\ell(\Omega), \quad d_\ell \omega = 0 \Rightarrow \exists \eta \in C^1 \Lambda^{\ell-1}(\Omega) \text{ such that } d_{\ell-1} \eta = \omega. \quad (13.1.4.82)$$

→ topological assumption

Theorem 13.2.1.22. Existence of cochain potentials

Let the domain $\Omega \subset \mathbb{R}^d$ satisfy the assumptions of Thm. 13.1.4.81. Then for **any** generalized oriented mesh $\mathcal{M}$ of Ω and for any $1 \leq \ell \leq d$ we have

$$\begin{aligned} \vec{\omega} \in \mathcal{C}^\ell(\mathcal{M}): \quad \vec{d}_\ell \vec{\omega} = 0 &\Rightarrow \exists \vec{\eta} \in \mathcal{C}^{\ell-1}(\mathcal{M}) \text{ such that } \vec{d}_{\ell-1} \vec{\eta} = \vec{\omega} \\ \Leftrightarrow \mathcal{R}(\vec{d}_{\ell-1}) = \mathcal{N}(\vec{d}_\ell) &\Leftrightarrow \mathcal{R}(\mathbf{D}_{\ell-1}) = \mathcal{N}(\mathbf{D}_\ell). \end{aligned} \quad (13.2.1.23)$$

13.2.1.3. Semi-discrete Maxwell's Equations

ME in IF :

$$\underline{d}_1 \underline{e}(t) = -\frac{d}{dt} \underline{b}(t) \quad , \quad \underline{d}_1 \underline{h}(t) = \frac{d}{dt} \underline{d}(t) + \underline{j}(t) \quad , \quad (13.1.4.30)$$

$$\vec{d}_1 \vec{e}(t) = -\frac{d}{dt} \vec{b}(t) \quad , \quad \vec{d}_1 \vec{h}(t) = \frac{d}{dt} \vec{d}(t) + \vec{j}(t) \quad , \quad (13.2.1.29)$$

$$\mathbf{D}_1 \vec{e}(t) = -\frac{d}{dt} \vec{b}(t) \quad , \quad \mathbf{D}_1 \vec{h}(t) = \frac{d}{dt} \vec{d}(t) + \vec{j}(t) \quad . \quad (13.2.1.30)$$

↑
FL

↑
AL

↑
source current
= given data

} discrete ME

A remarkable property :

IF $\longrightarrow$ CC : sampling/measurement

$$S_\ell : \begin{cases} \mathcal{I}^\ell(\Omega) & \rightarrow \mathcal{C}^\ell(\mathcal{M}) \\ \underline{\omega} & \mapsto (\langle \underline{\omega}, f \rangle)_{f \in \mathcal{F}_\ell(\mathcal{M})} \end{cases} \quad , \quad \ell \in \{0, 1, 2, 3\} . \quad (13.2.1.32)$$

$\Rightarrow$ Sampled fields

$$\vec{e} := S_1 \underline{e} \quad , \quad \vec{h} := S_1 \underline{h} \quad ,$$

$$\vec{e}, \vec{h} \in \mathbb{R}^{N_1} \quad , \quad N_1 := \#\mathcal{F}_1(\mathcal{M}) \quad ,$$

$$\vec{b} := S_2 \underline{b} \quad , \quad \vec{d} := S_2 \underline{d} \quad , \quad \vec{j} := S_2 \underline{j} \quad ,$$

$$\vec{b}, \vec{d}, \vec{j} \in \mathbb{R}^{N_2} \quad , \quad N_2 := \#\mathcal{F}_2(\mathcal{M}) \quad .$$

These vectors will be exact solution of the algebraic Maxwell's equations ~~??~~ (30)

Well in (30) :

$$\# \text{ unknowns} = 2 \cdot \# \mathcal{F}_1(M) + 2 \cdot \# \mathcal{F}_2(M)$$

$$\# \text{ eqs.} = 2 \cdot \# \mathcal{F}_2$$

(30) is strongly under-determined





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