

ETH Lecture 401-0674-00L Numerical Methods for Partial Differential Equations

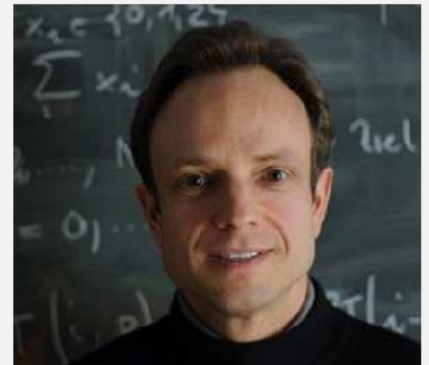
Course Video

Section 13.3.2.1: Electromagnetic Wave Equations

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(C) Seminar für Angewandte Mathematik, ETH Zürich



Prerequisites.

- Calculus and ODEs

Dependencies. [Lecture $\rightarrow$ Section 13.1.4], [Lecture $\rightarrow$ Section 13.1.5], [Lecture $\rightarrow$ Section 13.3.1.2]

Duration: minutes



Video and accompanying tablet notes may not match completely!

[Corrections and updates may have been made in tablet notes.]

XIII Finite - Element Exterior Calculus (FEEC)

13.3. Whitney FEM for Computational Electromagnetism

13.3.2. Electrodynamic Evolution Problems

IBVP for EM fields

$$ME : \quad d_1 \mathbf{e}(t) = -\frac{d}{dt} \mathbf{b}(t) \quad \text{in } L^2 \Lambda^2(\Omega) \quad , \quad d_1 \mathbf{h}(t) = \frac{d}{dt} \mathbf{d}(t) + \mathbf{j}(t) \quad \text{in } L^2 \Lambda^2(\Omega) \quad , \quad (13.3.1.1)$$

$$ML : \quad \int_{\Omega} \mathbf{d}(t) \wedge \mathbf{e}' = m_{\epsilon}(\mathbf{e}(t), \mathbf{e}') \quad \forall \mathbf{e}' \in L^2 \Lambda^1(\Omega) \quad , \quad (13.3.1.22)$$

$$\int_{\Omega} \mathbf{b}(t) \wedge \mathbf{h}' = m_{\mu}(\mathbf{h}(t), \mathbf{h}') \quad \forall \mathbf{h}' \in L^2 \Lambda^1(\Omega) \quad . \quad (13.3.1.23)$$

b.c. : (artificial / idealization)

$$\text{In v.p. : } \check{\mathbf{e}}(t) \times \mathbf{n} = 0 \quad [\text{PEC, (13.1.3.43)}] \quad \text{or} \quad \check{\mathbf{h}}(t) \times \mathbf{n} = 0 \quad [\text{PMC, (13.1.3.44)}] \quad \text{on } \partial\Omega \quad . \quad (13.3.2.1)$$

$\hat{=}$ zero tangential b.c. for 1-forms

13.3.2.1. Electromagnetic Wave Equations

Goal: spatial variational formulation, PEC b.c.

$\frac{d}{dt}$ on M :

$$m_\epsilon(\dot{e}(t), e') = \int_\Omega \dot{d}(t) \wedge e' \stackrel{ME}{=} \int_\Omega (d_1 h(t) - j) \wedge e' \quad (I)$$

$$= \int_\Omega h(t) \wedge d_1 e' - j(t) \wedge e' + \int_{\partial\Omega} h(t) \wedge e' \quad (=0)$$

[because of zero tangential b.c. on both $e(t)$ and e']

$$m_\mu(\dot{h}(t), h') = \int \dot{b}(t) \wedge h' = \int -d_1 e(t) \wedge h' \quad (II)$$

for $e, h : [0, T] \rightarrow H^1(d, \Omega)$ $\forall e', h' \in L^2 \Lambda^1(\Omega)$

mismatch of test/trial spaces



Apply integration by parts (13.1.4.124) (for $\ell = k = 1$) to **one** equation of (I), (II).

PEC b.c. are essential b.c.

Seek $e : [0, T] \rightarrow H_0 \Lambda^1(d, \Omega)$ and $h : [0, T] \rightarrow L^2 \Lambda^1(\Omega)$ such that

$$\begin{aligned} m_\epsilon\left(\frac{de}{dt}(t), e'\right) - \int_\Omega h(t) \wedge d_1 e' &= - \int_\Omega j(t) \wedge e' \quad \forall e' \in H_0 \Lambda^1(d, \Omega), \\ m_\mu\left(\frac{dh}{dt}(t), h'\right) + \int_\Omega d_1 e(t) \wedge h' &= 0 \quad \forall h' \in L^2 \Lambda^1(\Omega). \end{aligned} \quad (13.3.2.6)$$

$\stackrel{\wedge}{=}$ 1st-order "ODE in function space"

$\Rightarrow$ Requires initial conditions

$$e(0) = e_0 \in H_0 \Lambda^1(d, \Omega), \quad h(0) = h_0 \in L^2 \Lambda^1(\Omega)$$

§ 13.3.2.13 Conservation of energy

$$\begin{aligned} m_\epsilon \left(\frac{d\mathbf{e}}{dt}(t), \mathbf{e}' \right) - \int_{\Omega} \mathbf{h}(t) \wedge d_1 \mathbf{e}' &= - \int_{\Omega} \mathbf{j}(t) \wedge \mathbf{e}' \quad \forall \mathbf{e}' \in H_0 \Lambda^1(d, \Omega), \\ + m_\mu \left(\frac{d\mathbf{h}}{dt}(t), \mathbf{h}' \right) + \int_{\Omega} d_1 \mathbf{e}(t) \wedge \mathbf{h}' &= 0 \quad \forall \mathbf{h}' \in L^2 \Lambda^1(\Omega), \end{aligned} \quad (13.3.2.6)$$

set $\mathbf{e}' \leftarrow \mathbf{e}(t)$, $\mathbf{h}' \leftarrow \mathbf{h}(t)$ & add equ.

$$m_\epsilon \left(\frac{d\mathbf{e}}{dt}(t), \mathbf{e}(t) \right) + m_\mu \left(\frac{d\mathbf{h}}{dt}(t), \mathbf{h}(t) \right) = - \int_{\Omega} \mathbf{j}(t) \wedge \mathbf{e}(t). \quad (13.3.2.14)$$

$$E_{\text{tot}}(t) = E_{\text{el}}(\mathbf{e}(t)) + E_{\text{mag}}(\mathbf{h}(t)) = \frac{1}{2} m_\epsilon (\mathbf{e}(t), \mathbf{e}(t)) + \frac{1}{2} m_\mu (\mathbf{h}(t), \mathbf{h}(t)).$$

$$(14) \Rightarrow \frac{d}{dt} E_{\text{tot}}(t) = - \underbrace{\int_{\Omega} \mathbf{j}(t) \wedge \mathbf{e}(t)}_{\text{power injected by source current}}$$

$\Leftrightarrow$ Poynting's thm.

§ 13.3.2.19

Constraint propagation

Seek $\mathbf{e} : [0, T] \rightarrow H_0 \Lambda^1(\mathbf{d}, \Omega)$ and $\mathbf{h} : [0, T] \rightarrow L^2 \Lambda^1(\Omega)$ such that

$$\begin{aligned} m_\epsilon \left(\frac{d\mathbf{e}}{dt}(t), \mathbf{e}' \right) - \int_\Omega \mathbf{h}(t) \wedge d_1 \mathbf{e}' &= - \int_\Omega \mathbf{j}(t) \wedge \mathbf{e}' \quad \forall \mathbf{e}' \in H_0 \Lambda^1(\mathbf{d}, \Omega), \\ m_\mu \left(\frac{d\mathbf{h}}{dt}(t), \mathbf{h}' \right) + \int_\Omega d_1 \mathbf{e}(t) \wedge \mathbf{h}' &= 0 \quad \forall \mathbf{h}' \in L^2 \Lambda^1(\Omega). \end{aligned} \quad (13.3.2.6)$$

Use $\frac{d}{dt} ML : \int_\Omega \dot{b}(t) \wedge h' = m_\mu(\dot{h}(t), h')$

$\rightarrow \int_\Omega \dot{b}(t) \wedge h' + \int_\Omega d_1 e(t) \wedge h' = 0 \quad \forall h'$

test $h' := d_0 v, v \in H \Lambda^0(\mathbf{d}, \Omega)$

$$\int_\Omega \dot{b}(t) \wedge d_0 v + \underbrace{\int_\Omega d_1 e(t) \wedge d_0 v}_{=0 \text{ by i.b.p \& } e(t)|_{\partial\Omega} = 0} = 0$$

$= 0$ by i.b.p & $e(t)|_{\partial\Omega} = 0$

$$- \int_\Omega d_2 \dot{b}(t) \wedge v + \int_{\partial\Omega} b(t) \wedge v = 0 \quad \forall v$$



$$\frac{d}{dt} d_2 b(t) = 0 \text{ in } \Omega, \quad b|_{\partial\Omega} = 0 \text{ on } \partial\Omega$$

[tangential b.c.]

V.P. $\frac{d}{dt} \operatorname{div} \check{b}(t) = 0$

$\check{b}(t) \cdot n = 0$ on $\partial\Omega$

Seek $\mathbf{e} : [0, T] \rightarrow H_0 \Lambda^1(d, \Omega)$ and $\mathbf{h} : [0, T] \rightarrow L^2 \Lambda^1(\Omega)$ such that

$$\begin{aligned} m_\epsilon \left(\frac{d\mathbf{e}}{dt}(t), \mathbf{e}' \right) - \int_{\Omega} \mathbf{h}(t) \wedge d_1 \mathbf{e}' &= - \int_{\Omega} \mathbf{j}(t) \wedge \mathbf{e}' \quad \forall \mathbf{e}' \in H_0 \Lambda^1(d, \Omega), \\ m_\mu \left(\frac{d\mathbf{h}}{dt}(t), \mathbf{h}' \right) + \int_{\Omega} d_1 \mathbf{e}(t) \wedge \mathbf{h}' &= 0 \quad \forall \mathbf{h}' \in L^2 \Lambda^1(\Omega). \end{aligned} \quad (13.3.2.6)$$

Use $\frac{d}{dt} ML : \int_{\Omega} \dot{d}(t) \wedge e' = m_\epsilon(\dot{e}(t), e')$

$$\Rightarrow \int_{\Omega} \dot{d}(t) \wedge e' - \int_{\Omega} h(t) \wedge d_1 e' = - \int_{\Omega} j(t) \wedge e' \quad \forall e'$$

Use: $e' := dv', \quad v' \in H_0 \Lambda^0(d, \Omega)$

$$\Rightarrow \int_{\Omega} \dot{d}(t) \wedge dv' = - \int_{\Omega} j(t) \wedge dv'$$

$$\Rightarrow - \int_{\Omega} d_2 \dot{d}(t) \wedge v' = \int_{\Omega} d_2 j(t) \wedge v'$$

$$\Rightarrow \text{PDE} \quad - \frac{d}{dt} \underbrace{d_2 d(t)}_{=: q \hat{=} \text{charge density 3-form}} = d_2 j(t)$$

$$\Rightarrow \text{Continuity equation}$$

$$- \frac{d}{dt} q(t) = d_2 j(t)$$

$$\text{v.p.:} \quad \frac{\partial \check{q}}{\partial t}(x, t) = - \operatorname{div} \check{j}(x, t)$$

§ 13.3.2.31 EMWE in 2nd-order form

(for local linear ML, v.p. notation)

$$\check{e} :]0, T[\rightarrow H_0(\text{curl}, \Omega), \check{h} :]0, T[\rightarrow (L^2(\Omega))^3$$

$$\int_{\Omega} (\epsilon(x) \frac{\partial \check{e}}{\partial t}(x, t)) \cdot \check{e}'(x) dx - \int_{\Omega} \check{h}(x, t) \cdot \text{curl} \check{e}'(x) dx = - \int_{\Omega} \check{j}(x, t) \cdot \check{e}'(x) dx, \quad (13.3.2.7)$$

$$\int_{\Omega} (\mu(x) \frac{\partial \check{h}}{\partial t}(x, t)) \cdot \check{h}'(x) dx + \int_{\Omega} \text{curl} \check{e}(x, t) \cdot \check{h}'(x) dx = 0$$

for all $\forall \check{e}' \in H_0(\text{curl}, \Omega), \check{h}' \in (L^2(\Omega))^3$.

In 2nd equ.: $h' \leftarrow \mu^{-1} b'$

$$\frac{d}{dt} \left| \int_{\Omega} (\epsilon(x) \frac{\partial \check{e}}{\partial t}(x, t)) \cdot \check{e}'(x) dx - \int_{\Omega} \check{h}(x, t) \cdot \text{curl} \check{e}'(x) dx = - \int_{\Omega} \check{j}(x, t) \cdot \check{e}'(x) dx, \right.$$

$$\int_{\Omega} \frac{\partial \check{h}}{\partial t}(x, t) \cdot \check{b}'(x) dx + \int_{\Omega} (\mu^{-1}(x) \text{curl} \check{e}(x, t)) \cdot \check{b}'(x) dx = 0$$

for all $\forall \check{e}' \in H_0(\text{curl}, \Omega), \check{h}' \in (L^2(\Omega))^3$.

$$\check{b}' := \text{curl} \check{e}'$$

$$\int_{\Omega} (\epsilon(x) \frac{\partial^2 \check{e}}{\partial t^2}(x, t)) \cdot \check{e}'(x) dx - \int_{\Omega} \frac{\partial \check{h}}{\partial t}(x, t) \cdot \text{curl} \check{e}'(x) dx = - \int_{\Omega} \frac{\partial \check{j}}{\partial t}(x, t) \cdot \check{e}'(x) dx,$$

$$\int_{\Omega} \frac{\partial \check{h}}{\partial t}(x, t) \cdot \text{curl} \check{e}'(x) dx + \int_{\Omega} (\mu^{-1}(x) \text{curl} \check{e}(x, t)) \cdot \text{curl} \check{e}'(x) dx = 0$$

for all $\forall \check{e}' \in H_0(\text{curl}, \Omega)$.

Seek $e :]0, T[\rightarrow H_0(\text{curl}, \Omega)$ such that

$$\int_{\Omega} (\epsilon(x) \frac{d^2 \check{e}}{dt^2}(x, t)) \cdot \check{e}'(x) dx + \int_{\Omega} (\mu^{-1}(x) \text{curl} \check{e}(x, t)) \cdot \text{curl} \check{e}'(x) dx = - \int_{\Omega} \frac{\partial \check{j}}{\partial t}(x, t) \cdot \check{e}'(x) dx$$

(13.3.2.32)

for all $\check{e}' \in H_0(\text{curl}, \Omega)$.

Recall Sect 9.2 :

$$u(t) \in V_0: \quad m\left(\frac{d^2 u}{dt^2}, v\right) + a(u, v) = \ell(v) \quad \forall v \in V_0. \quad (9.3.1.8)$$

with

- function space $V_0 := H_0(\mathbf{curl}, \Omega)$,
- an s.p.d. " L^2 -type" bilinear form $m = m_\epsilon$, $m_\epsilon(\check{\mathbf{e}}, \check{\mathbf{e}}') := \int_{\Omega} (\epsilon(x) \check{\mathbf{e}}(x)) \cdot \check{\mathbf{e}}'(x) dx$,
- the bilinear form corresponding to a second-order PDE operator in space

$$a \quad \leftrightarrow \quad (\check{\mathbf{e}}, \check{\mathbf{e}}') \mapsto \int_{\Omega} (\mu^{-1}(x) \mathbf{curl} \check{\mathbf{e}}(x, t)) \cdot \mathbf{curl} \check{\mathbf{e}}'(x) dx,$$

- and a right-hand side linear form

$$\ell \quad \leftrightarrow \quad \mathbf{e}' \mapsto - \int_{\Omega} \check{\mathbf{j}}(x, t) \cdot \check{\mathbf{e}}'(x) dx.$$

EMWE share key features with scalar WE

→ finite speed of propagation $\leq s_{\max}$

$\text{supp } e_0, h_0 \subset \Omega_0$:

$\text{supp } e(t), \text{supp } h(t) \subset \{x \in \mathbb{R}^3 : \text{dist}(\Omega_0, x) \leq t \cdot s_{\max}\}$

→ domain of influence & dependence











