

ETH Lecture 401-0674-00L Numerical Methods for Partial Differential Equations

Numerical Methods for Partial Differential Equations

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Q & A Session

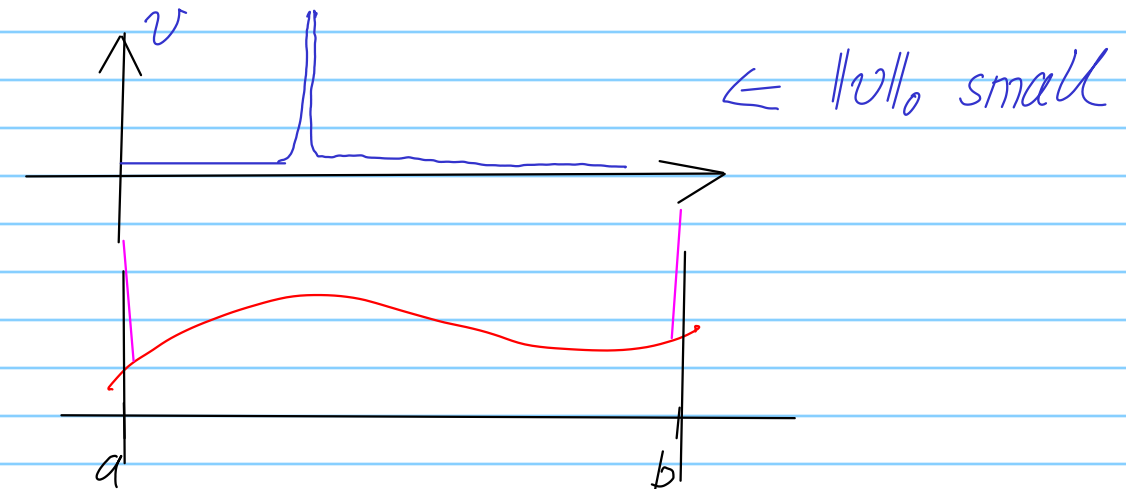
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- 1) Guidance to h.w. problems in tutorial videos
- 2) Links to video files in PDF
- 3) Sub-folders in polybox

Norms :

 $\|\cdot\| \triangleq$ Euclidean norm

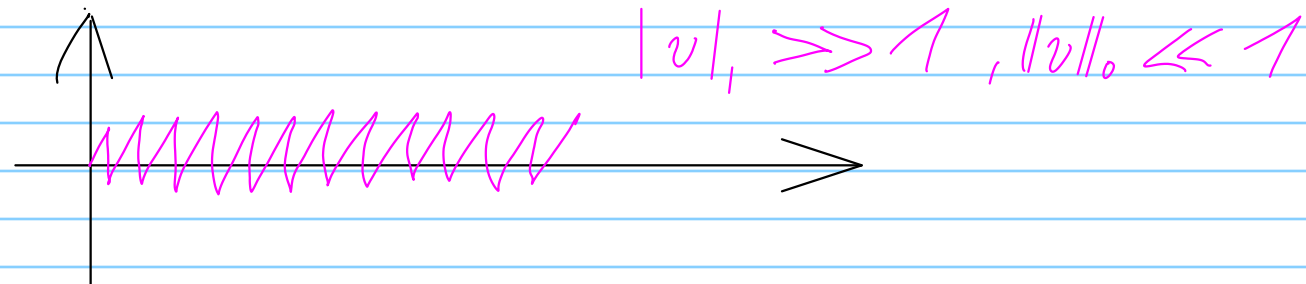
$$\|v\|_0 = \|v\|_{L^2(\Omega)} = \left(\int_{\Omega} |v|^2 dx \right)^{1/2} \triangleq \text{average size of } v$$

 $\hookrightarrow$ "blind to local effects"

②

$$|v|_1 = |v|_{H^1(\Omega)} = \left(\int_{\Omega} \|\text{grad } v\|^2 dx \right)^{1/2}$$

$\hat{=}$ measures strength of local variations



$\|\cdot\|_{\infty} \hat{=}$ maximum norm
"blind to global behavior"

• $|\cdot|_1$ vs $\|\cdot\|_1 := (|\cdot|_1^2 + \|\cdot\|_0^2)^{1/2}$
 $\hookrightarrow$ semi-norm: $= 0$ for constants $\Rightarrow$ no norm

Seek: $u \in H^1(\Omega)$, but $u \notin C_{pw}'(\overline{\Omega})$

$$\Omega = \{x: \|x\| < \epsilon\} : u(x) = \log|\log\|x\||$$

$$u(0) = \infty \quad \text{and} \quad \|u\|_1 < \infty$$

Connection:

$$u \in H_0^1(\Omega) : \underbrace{\int_{\Omega} \text{grad } u \cdot \text{grad } v \, dx}_{\downarrow \text{Energy space } H^1(\Omega)} = v(0) \quad \forall v \in H_0^1(\Omega)$$

test function
 $\downarrow$
 $\forall v \in H_0^1(\Omega)$

$\uparrow$
 $=: \ell(v)$

Energy space $H^1(\Omega)$

$$\text{LVP: } u \in V_0 : a(u, v) = \ell(v) \quad \forall v \in V_0$$

$$\text{QMP: } \frac{1}{2} a(u, u) - \ell(u) \rightarrow \min$$

Necessary for existence of a minimizer:

$$\exists C > 0 : |\ell(v)| \leq C a(v, v)^{1/2} = C \|v\|_a$$

(3)

Energy norm: $\leftrightarrow$ energy

LVP: $u \in V_0 \quad \underbrace{a(u, v)}_{\text{s.p.d.}} = l(v) \quad \forall v \in V_0$

$$\|v\|_a := a(v, v)^{1/2}$$

Membrane model: $\frac{1}{2} a(u, u) \stackrel{!}{=} \text{elastic energy of membrane with shape } u$

Ad p. 3/1.4 $\mapsto$ s.p.d. $\mapsto$ cont. w.r.t. $\|\cdot\|_a$

$$J(v) = \frac{1}{2} a(v, v) - l(v) + c, \quad v \in V_0$$

$$\Leftrightarrow \text{LVP: } u^* \in V_0 : a(u^*, v) = l(v) \quad \forall v \in V_0$$

$$\begin{aligned} J(v) &= \frac{1}{2} a(v, v) - a(u^*, v) + \frac{1}{2} a(u^*, u^*) - \frac{1}{2} a(u^*, u^*) + c \\ &= \frac{1}{2} a(u^* - v, u^* - v) - \frac{1}{2} a(u^*, u^*) + c \\ &= \frac{1}{2} \|u^* - v\|_a^2 - \underbrace{\frac{1}{2} a(u^*, u^*)}_{\text{minimal value}} + c \end{aligned}$$

Ch 1: on mathematical models centering around energy minimization on function spaces [Sect 1.2]

$$\text{QMP} \Leftrightarrow \text{LVP}$$

$$\dim < \infty : J(\vec{v}) = \frac{1}{2} \vec{v}^T A \vec{v} - \vec{b} \cdot \vec{v}$$

$$\text{grad } J(\vec{u}) = A\vec{u} - \vec{b} \stackrel{!}{=} 0 \stackrel{!}{=} \text{LSE}$$

