

We now switch gears entirely; it will be a while before we get back to spectral theory. This is because spectral theoretic tools (e.g. the functional calculus) can **in principle** be used to solve partial differential equations, the **verification of the assumptions** of the various theorems (self-adjointness? domains?) is **rather nontrivial**, and involves serious PDE machinery — which we will need to develop first!

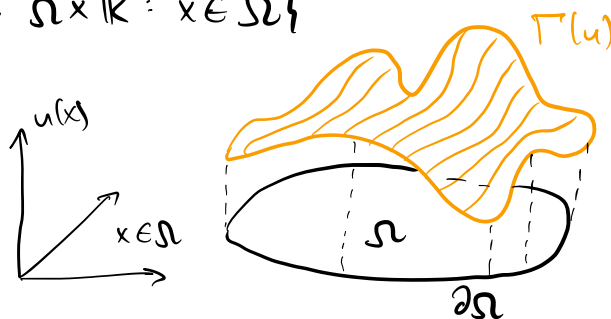
### Motivation: variational problems, PDE, and solution attempts.

Consider an **elastic membrane**: given a connected open set  $\Omega \subset \mathbb{R}^2$  with smooth boundary  $\partial\Omega$ , let  $u \in C^2(\bar{\Omega})$ , and

$$\Gamma(u) = \{ (x, u(x)) \in \bar{\Omega} \times \mathbb{R} : x \in \bar{\Omega} \}$$

is the **membrane**.

- We fix its boundary to be the graph of  $g \in C^2(\partial\Omega)$ , i.e.  $u(x) = g(x)$  for  $x \in \partial\Omega$ .



- The **energy** of the membrane is  $E(u) = \frac{1}{2} \int_{\Omega} |\nabla u|^2 dx$
- **Physical model**: given  $g \in C^2(\partial\Omega)$ ,  $u$  should have **least energy** among all elements of  $V(g) := \{ u \in C^2(\bar{\Omega}) : u|_{\partial\Omega} = g \}$

Questions: (i) Is  $e(g) := \inf_{u \in V(g)} E(u)$  **attained** for some  $u \in V(g)$ ?

(ii) If  $\exists$  minimizer  $u$  of  $E$  on  $V(g)$  is  $u$  **unique**?

(iii) How can one find/characterize  $u$ ? ( $\leadsto$  **PDE**.)

(iv) If  $g \in C^\infty(\partial\Omega)$ , is  $u \in C^\infty(\bar{\Omega})$ ? (**Higher regularity**.)

Let us try to answer some of these questions and see how far we get:

(ii) Uniqueness of minimizers is a consequence of the strict convexity of  $E$ . Namely, if  $u_1, u_2 \in V(g)$  with  $E(u_1) = E(u_2) = e(g)$ , then  $\frac{u_1 + u_2}{2} \in V(g)$  and

$$\begin{aligned} E\left(\frac{u_1 + u_2}{2}\right) &= \frac{1}{2} \int_{\Omega} \frac{1}{4} |\nabla u_1 + \nabla u_2|^2 dx \\ &= \frac{1}{8} \int_{\Omega} |\nabla u_1|^2 + 2 \nabla u_1 \cdot \nabla u_2 + |\nabla u_2|^2 dx \\ &\leq \frac{1}{8} \int_{\Omega} |\nabla u_1|^2 + 2 |\nabla u_1| |\nabla u_2| + |\nabla u_2|^2 dx \\ &\leq \frac{1}{8} \int_{\Omega} 2 |\nabla u_1|^2 + 2 |\nabla u_2|^2 dx \\ &= \frac{1}{2} (E(u_1) + E(u_2)) = e(g). \end{aligned}$$

$\Rightarrow \frac{u_1 + u_2}{2}$  is a minimizer too  $\Rightarrow$  equality holds everywhere, so

$\forall x \in \Omega, \nabla u_1(x) = c(x) \nabla u_2(x)$  for some  $c > 0$ , and  $|\nabla u_1(x)| = |\nabla u_2(x)|$

$\Rightarrow \nabla u_1 = \nabla u_2 \Rightarrow u_1 - u_2 = c \in \mathbb{R}$ ; but at  $\partial\Omega, u_1 - u_2 = 0$ ,

so  $u_1 = u_2$ .

(iii) PDE for the minimizer  $u \in V(g)$ . Let  $\varphi \in C_c^\infty(\Omega)$  (or just  $\varphi \in V(0)$ , i.e.  $\varphi \in C^2(\bar{\Omega}), \varphi|_{\partial\Omega} = 0$ ); then  $u + s\varphi \in V(g) \forall s \in \mathbb{R}$ ,

so  $E(u) \leq E(u + s\varphi) = \frac{1}{2} \int_{\Omega} |\nabla u|^2 + 2s \nabla u \cdot \nabla \varphi + s^2 |\nabla \varphi|^2 dx$

$$\xrightarrow[\text{clear}]{\frac{d}{ds} \Big|_{s=0}} \int_{\Omega} \nabla u \cdot \nabla \varphi dx = 0.$$

We can integrate by parts since  $\varphi|_{\partial\Omega} = 0 \Rightarrow \int_{\Omega} \Delta u \varphi dx = 0$ .

Since  $\varphi \in C_c^\infty(\Omega)$  is arbitrary:

$$\begin{cases} \Delta u = 0 & \text{in } \Omega \\ u = g & \text{on } \partial\Omega \end{cases} \quad (*)$$

(i) Existence of minimizers. Two options:

(a) try to solve the PDE  $(*)$ : see below.

(b) direct method of calculus of variations.  $C^2(\bar{\Omega})$  is not reflexive;  $E(u)$  has "little to do" with  $C^2(\bar{\Omega})$ ... Will need to extend the class of  $u$  we work with (to  $H_0^1(\Omega)$ ).

(iv) Higher regularity of  $u$ : via regularity theory for the PDE  $(*)$ .

We briefly discuss 2 natural approaches to solving the PDE  $(*)$ . Let  $u_0 \in C^2(\bar{\Omega})$  be any function with  $u_0|_{\partial\Omega} = g$ . Write  $u = u_0 + v$ , then we want

$$\begin{cases} \Delta v = f := -\Delta u_0 & \text{in } \Omega \\ v = 0 & \text{on } \partial\Omega. \end{cases}$$

Ignoring the precise nature of the function spaces in which  $f$  here lives, we call  $v \mapsto u$  and study now

$$\begin{cases} \Delta u = f & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega. \end{cases} \quad (\oplus)$$

APPROACH 1: solvability via functional analysis (domains, adjoints).

Idea: Regard  $(\oplus)$  as the equation  $Au = f$  where  $A: D(A) \subset L^2(\Omega) \rightarrow L^2(\Omega)$  is the Laplacian;  $D(A)$  encodes the Dirichlet boundary condition  $u|_{\partial\Omega} = 0$ .

Execution: Let  $D(A) := \{u \in C^2(\bar{\Omega}) : u|_{\partial\Omega} = 0\}$ ,  
 $Au := \Delta u \quad (u \in D(A)).$

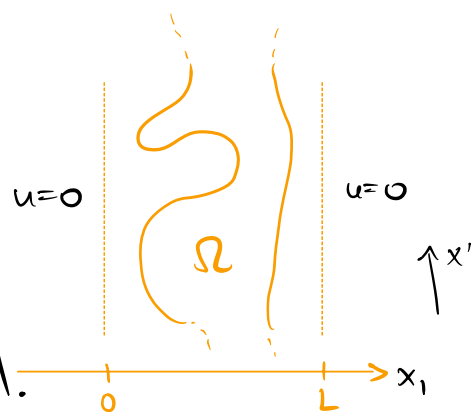
We already checked that  $A$  is symmetric (Example (E.7)),  
 so  $A \subset A^* \Rightarrow A$  is closable; the closure  $\bar{A} \subseteq A^*$  is  
 still symmetric (exercise).

Proposition (P.5)  $\text{ran } \bar{A} \subset L^2(\Omega)$  is closed, and  $\ker \bar{A} = \{0\}$ .

Lemma (L.8) (Poincaré inequality.) Let  $\Omega \subset [0, L] \times \mathbb{R}^{n-1}$  be  
 open. Then  $\forall u \in C_c^\infty(\Omega)$ ,

$$\int_{\Omega} |u|^2 dx \leq L^2 \int_{\Omega} |\nabla u|^2 dx.$$

Intuition: If  $u$  goes from 0 back to 0  
 over an interval of length  $L$ ,  
 then  $|u|$  cannot exceed  $L|\nabla u|$ .



Proof of Lemma (L.8) For  $x = (x_1, x') \in \Omega$ ,

$$\begin{aligned} |u(x_1, x')|^2 &= \left| \int_0^{x_1} \frac{\partial u}{\partial x_1}(s, x') ds \right|^2 \leq \left( \int_0^{x_1} \left| \frac{\partial u}{\partial x_1}(s, x') \right| ds \right)^2 \\ &\leq L \int_0^L \left| \frac{\partial u}{\partial x_1}(s, x') \right|^2 ds \end{aligned}$$

by Cauchy-Schwarz. Integrate over  $(x_1, x') \in \Omega$

$$\begin{aligned} \Rightarrow \|u\|_{L^2(\Omega)}^2 &\leq \int_0^L \int_{\mathbb{R}^{n-1}} L \int_0^L \left| \frac{\partial u}{\partial x_1}(s, x') \right|^2 ds dx' dx_1 \\ &= L^2 \left\| \frac{\partial u}{\partial x_1} \right\|_{L^2(\Omega)}^2 \end{aligned}$$

□

Proof of Proposition (P.5).

\* Injectivity: If  $u \in \ker \bar{A}$ , choose  $u_k \in D(A)$  s.t.  
 $u_k \rightarrow u, Au_k = \Delta u_k \rightarrow \bar{A}u = 0$ .

Then  $\|u_k\|_{L^2(\Omega)}^2 \stackrel{\text{Lemma (L.8)}}{\leq} C \|\nabla u_k\|_{L^2(\Omega)}^2 = C \int_{\Omega} \nabla u_k \cdot \nabla u_k dx$

$$\stackrel{\text{I.B.P.}}{=} C \int_{\Omega} u_k (-\Delta u_k) dx$$

$$\leq C \|u_k\|_{L^2(\Omega)} \|\Delta u_k\|_{L^2(\Omega)}.$$

$$\Rightarrow \|u_k\|_{L^2} \leq C \|\Delta u_k\|_{L^2} \xrightarrow{k \rightarrow \infty} 0$$

$$\Rightarrow u = \lim_{k \rightarrow \infty} u_k = 0.$$

\* **Closed range:** Let  $u_k \in \mathcal{D}(\bar{A})$ ,  $\bar{A}u_k = f_k \xrightarrow{k \rightarrow \infty} f \in L^2(\Omega)$ .

Replacing  $u_k$  by good approximations (in the graph norm) by elements of  $\mathcal{D}(A)$ , we may assume  $u_k \in \mathcal{D}(A)$ ; so

$$\begin{cases} u_k \in C^2(\bar{\Omega}), \\ u_k|_{\partial\Omega} = 0 \\ \Delta u_k = f_k \rightarrow f. \end{cases}$$

$$\Rightarrow \|u_k - u_\ell\|_{L^2(\Omega)}^2 \stackrel{\text{Lemma (L.8)}}{\leq} C \|\nabla(u_k - u_\ell)\|_{L^2(\Omega)}^2$$

$$= C \int_{\Omega} (u_k - u_\ell) (-\Delta(u_k - u_\ell)) dx$$

$$= C \left| \int_{\Omega} (u_k - u_\ell) (f_\ell - f_k) dx \right|$$

$$\leq C \|u_k - u_\ell\|_{L^2(\Omega)} \|f_k - f_\ell\|_{L^2(\Omega)}$$

$$\Rightarrow \|u_k - u_\ell\|_{L^2(\Omega)} \leq C \|f_k - f_\ell\|_{L^2(\Omega)} \xrightarrow{k, \ell \rightarrow \infty} 0.$$

$$\text{So } \exists \lim_{k \rightarrow \infty} u_k = u \in L^2(\Omega).$$

But  $\bar{A}u_k = \bar{A}u_k \rightarrow f$ ; so  $(u_k, \bar{A}u_k) \rightarrow (u, f)$  in  $\Gamma_{\bar{A}}$ ,  
and thus  $f = \bar{A}u$ . □

Finally, by Theorem (T.4),  $\text{ran } \bar{A} = (\ker \bar{A}^*)^\perp$ .

Theorem (T.15)  $\bar{A}$  is self-adjoint.

This is hard, and we will need to prepare well to prove it.

Granted Theorem (T.15), we get  $\text{ran } \bar{A} = (\ker \bar{A})^\perp = L^2(\Omega)$  from Proposition (P.5).

$\Rightarrow \bar{A}: D(\bar{A}) \rightarrow L^2(\Omega)$  is invertible.

Theorem (T.16)  $\forall f \in L^2(\Omega) \exists! u \in D(\bar{A})$  s.t.  $\bar{A}u = f$ .

Open questions: What is  $D(\bar{A})$ ? In what sense does  $u \in D(\bar{A})$  satisfy the Dirichlet boundary condition? How to prove Theorem (T.15)? ( $\rightarrow$  Sobolev spaces, boundary traces of Sobolev functions).

APPROACH 2: Riesz representation theorem.

The starting point is the "weak formulation" of the PDE  $\oplus$ :  
if  $u \in C^2(\bar{\Omega})$  is a solution and  $v \in C_c^\infty(\Omega)$ ,

$$\int_{\Omega} \nabla u \cdot \nabla v \, dx = - \int_{\Omega} \Delta u \cdot v \, dx = - \int_{\Omega} f v \, dx. \quad \oplus$$

Regard the L.H.S. as an inner product, with associated norm

$$\|u\|_{H_0^1(\Omega)}^2 := \int_{\Omega} |\nabla u|^2 \, dx.$$

By Lemma (L.8),  $\|u\|_{L^2(\Omega)}^2 \leq C^2 \|u\|_{H_0^1(\Omega)}^2$  for  $u \in C_c^\infty(\Omega)$ ,

so  $\|\cdot\|_{H_0^1(\Omega)}$  is a norm on  $C_c^\infty(\Omega)$ .

Moreover, the R.H.S. of  $\oplus$  is continuous in the  $H_0^1(\Omega)$ -norm:

$$\left| \int_{\Omega} f v \, dx \right| \leq \|f\|_{L^2(\Omega)} \|v\|_{L^2(\Omega)} \leq C \|f\|_{L^2(\Omega)} \|v\|_{H_0^1(\Omega)}.$$

To apply Riesz, need Hilbert spaces:

Definition (D.11)  $H_0^1(\Omega) :=$  closure of  $C_c^\infty(\Omega)$  w.r.t.  $\|\cdot\|_{H_0^1(\Omega)}$ .

This is a Hilbert space with  $H_0^1(\Omega) \subset L^2(\Omega)$  and inner product

$$(u, v)_{H_0^1} = \int_{\Omega} \nabla u \cdot \nabla v \, dx,$$

where  $\nabla u = \lim_{k \rightarrow \infty} \nabla u_k \in L^2(\Omega)$  if  $C_c^\infty(\Omega) \ni u_k \rightarrow u$  in  $H_0^1(\Omega)$ .

Theorem (T.16') Let  $f \in L^2(\Omega)$ . Then  $\exists!$   $u \in H_0^1(\Omega)$  s.t.

$$\int_{\Omega} \nabla u \cdot \nabla v \, dx = - \int_{\Omega} f v \, dx \quad \forall v \in C_c^\infty(\Omega).$$

We say that  $u$  is a **weak solution** of  $\textcircled{\#}$ .

Proof  $H_0^1(\Omega) \ni v \mapsto - \int_{\Omega} f v \, dx \in \mathbb{R}$  defines an element of  $H_0^1(\Omega)^*$ , which is equal to  $(u, v)_{H_0^1(\Omega)}$  for some unique  $u \in H_0^1(\Omega)$  by Riesz.  $\square$

Open questions: Is  $u$ , for  $f \in C^\infty(\bar{\Omega})$ , also a classical (i.e.,  $C^2(\bar{\Omega})$ , or even  $C^\infty(\bar{\Omega})$ ) solution of  $\textcircled{\#}$ ?

In what sense does  $u \in H_0^1(\Omega)$  satisfy the Dirichlet boundary condition?

Plan for the next  $N \gg 1$  lectures:

- define, analyze Sobolev spaces such as  $H^1_0(\Omega)$
- solvability and regularity for general elliptic PDEs

$$\begin{cases} \sum_{i,j=1}^n a_{ij}(x) \frac{\partial^2 u}{\partial x_i \partial x_j}(x) + \sum_{i=1}^n b_i(x) \frac{\partial u}{\partial x_i}(x) + c(x)u(x) = f(x) \\ \text{boundary conditions for } u, \end{cases} \quad (*)$$

where  $(a_{ij})_{i,j=1}^n$  is symmetric, and  $\sum_{i,j=1}^n a_{ij}(x) \xi_i \xi_j \geq c|\xi|^2$ ,  $x \in \Omega$ ,  
for all  $\xi \in \mathbb{R}^n$ , where  $c > 0$  ("ellipticity" of  $(*)$ ).

$$\left( \text{Laplace equation: } \begin{cases} (a_{ij}) = \text{identity matrix} \\ b_i = 0 \\ c = 0. \end{cases} \right)$$