

**Convex Optimization
in Machine Learning and
Computational Finance**

**Lecture 5:
Subgradients,
Conjugate functions**

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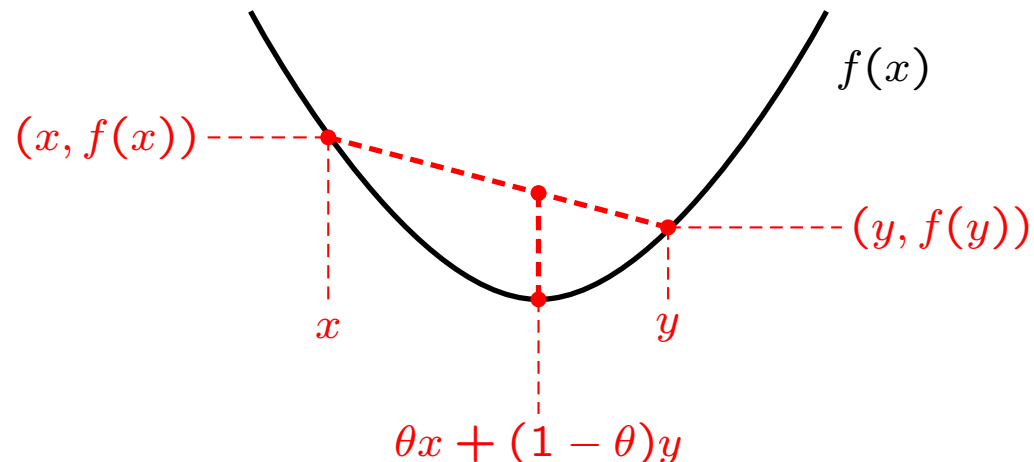
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Quick recall of last week's lecture

- ▶ Continuity and differentiability:
every convex function f is continuous on $\text{int dom } f$
- ▶ Necessary/sufficient condition for optimality
in **unconstrained** optimization.
- ▶ Lagrangian duality: strong duality works
with affine nondecreasing functions
(whenever **inf-sup = sup-inf** holds).
Examples: convex problems where:
 1. one of the two feasible sets is compact;
 2. or Slater condition holds.
- ▶ Conic duality

A summary of everything we know about convex functions 1/2

- ▶ A convex function f has a convex epigraph.
- ▶ Equivalently, $\forall x, y \in \text{dom } f, \lambda \in [0, 1]$:
$$f(\lambda x + (1 - \lambda)y) \leq \lambda f(x) + (1 - \lambda)f(y).$$
- ▶ Let $(f_\alpha)_{\alpha \in A}$ be convex functions $\mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$.
Then $f = \sup_{\alpha \in A} f_\alpha$ is convex.



Convexity and optimality

Let $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ be a convex function.

Let $Q \subseteq \mathbb{R}^n$ be a convex set. Let $X^* := \arg \min_{x \in Q} f(x)$.

► X^* is convex: if $x, y \in X^*$, $\lambda \in [0, 1]$, $f^* := \min_{x \in Q} f(x)$,
we have $f(\lambda x + (1 - \lambda)y) \leq \lambda f(x) + (1 - \lambda)f(y) = f^*$.

► More generally, *level sets* are convex.

If $\mathcal{L}_\alpha(f) := \{x \in Q : f(x) \leq \alpha\}$, $\mathcal{L}_\alpha(f)$ is convex.

Solving a convex optimization problem
approximately **is** finding a point
in a convex set – namely $\mathcal{L}_{f^* + \epsilon}(f)$.

A summary of everything we know about convex functions 2/2

- ▶ Every convex function f is continuous on $\text{int dom } f$.
- ▶ A closed convex set is the intersection of all the half-spaces containing it.

For epigraphs of convex LSC functions f , it means:

$$f(x) = \sup\{h(x) : f \geq h, h \text{ affine}\}.$$

Note 1: There are non-LSC convex functions:

$$f : \mathbb{R}_+ \rightarrow \mathbb{R}, \quad f(x) = 0 \text{ for } x > 0, \quad f(0) = 1.$$

Note 2: There are non-continuous LSC convex functions:

$$\begin{aligned} f : \mathbb{R}_+ \times \mathbb{R} \rightarrow \mathbb{R}, \quad f(x, y) &= y^2/x \text{ for } x \neq 0, \\ f(0, y) &= +\infty \text{ for } y \neq 0, \\ f(0, 0) &= 0 \end{aligned}$$

(cfr. Lecture 2: $\text{epi } f \equiv \mathbb{S}_+^2$)

Convex functions are almost differentiable

Theorem 1 Let $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ be convex, $x \in \text{relint}(\text{dom} f)$, and $d \in \text{aff}(\text{dom} f)$. Then

$$\nabla f(x)[d] := \lim_{t \downarrow 0} \frac{f(x + td) - f(x)}{t} \text{ exists.}$$

Warning: $\nabla f(x)[d]$ might not be linear in d .

e.g. if $f(x) = |x| \in \mathbb{R}$, $\nabla f(0)[d] = |d|$.

Proof: Let $\mu(t) := (f(x + td) - f(x))/t$ for all $t \in \mathbb{R}_{++}$.

The function μ is increasing, as it can be easily checked by using convexity of f . Therefore, $\mu(t)$ is bounded from below for $t > 0$.

Since $\mu(t)$ decreases when $t \downarrow 0$, the limit $\lim_{t \downarrow 0} \mu(t)$ exists.

Differentiable convex functions

Let $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ be a differentiable convex function. For all $x \in \text{relint}(\text{dom } f)$, $y \in \text{dom } f$:

$$\begin{aligned}\langle f'(x), y - x \rangle &= \lim_{t \rightarrow 0} \frac{f(x + t(y - x)) - f(x)}{t} \\ &\leq \lim_{t \rightarrow 0} \frac{(1 - t)f(x) + tf(y) - f(x)}{t} = f(y) - f(x).\end{aligned}$$

► $f(y) \geq f(x) + \langle f'(x), y - x \rangle$.

► **Increasing gradient property:**

$$\langle f'(y) - f'(x), y - x \rangle \geq 0.$$

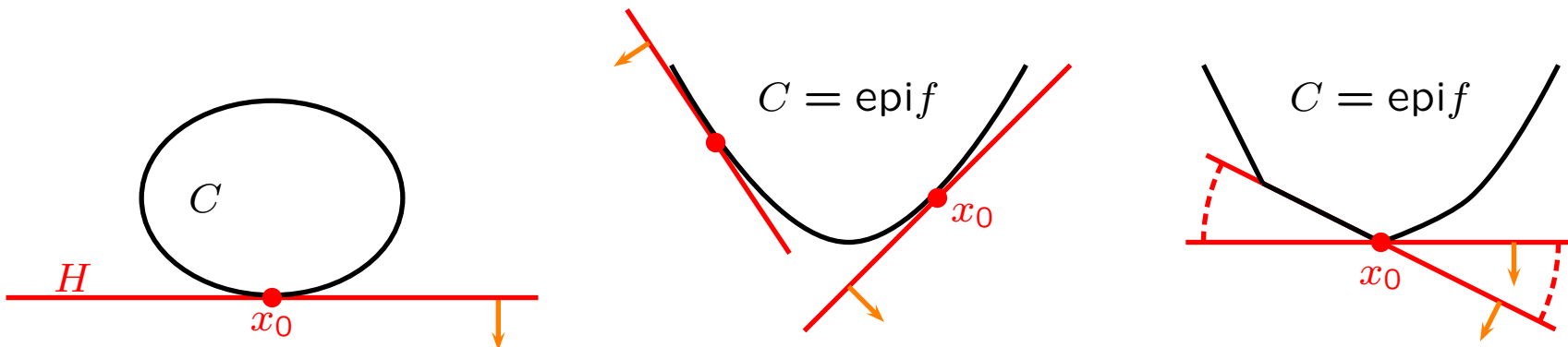
► If f twice differentiable, $f''(x) \succeq 0 \quad \forall x \in \text{int dom } f$.

$$\text{Indeed, } 0 \leq \frac{1}{t^2} \langle f'(x + th) - f'(x), th \rangle \rightarrow \langle f''(x)h, h \rangle \text{ as } t \rightarrow 0.$$

Thus $f'(x^*) = 0$ is **sufficient** to guarantee optimality!

Supporting hyperplanes

- ▶ A *supporting hyperplane* $H = \{x : l(x) = \beta\}$, l linear, of a convex set C at a point $x_0 \in \text{bd}C$, is such that $x_0 \in H$ and $C \subseteq \{x : l(x) \leq \beta\}$.
- ▶ We only consider here **non-trivial** supporting hyperplanes, that is $C \not\subseteq H$.



Supporting hyperplanes of convex epigraphs

Let $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ be an LSC convex function.
Let $x_0 \in \text{relint}(\text{dom } f)$. As $(x_0, f(x_0)) \in \text{bd}(\text{epi } f)$,
we can consider all the supporting hyperplanes of $\text{epi } f$.
They are not vertical. Let H be one of them:

$$\begin{aligned} H &= \left\{ (x, t) \in \mathbb{R}^n \times \mathbb{R} : \left\langle \begin{pmatrix} \hat{g} \\ -\mathbf{1} \end{pmatrix}, \begin{pmatrix} x \\ t \end{pmatrix} \right\rangle = \beta \right\} \\ &= \{(x, t) : g(x) - t = \beta\}, \text{ where } g \text{ linear.} \end{aligned}$$

As $(x_0, f(x_0)) \in H$, $\beta = g(x_0) - f(x_0)$.

As $(x, f(x)) \in \text{epi } f$ for all $x \in \text{dom } f$, we have:

$$g(x) - f(x) \leq \beta = g(x_0) - f(x_0) \Leftrightarrow f(x_0) + g(x - x_0) \leq f(x).$$

Note: If f is differentiable at x_0 , $g := \nabla f(x_0)$ works.

Subgradients of a convex function

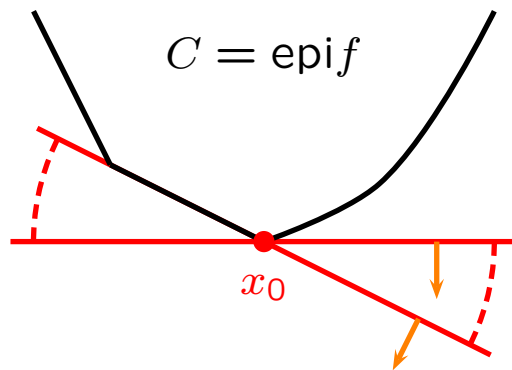
Let $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ be an LSC convex function.

Let $x_0 \in \text{relint}(\text{dom} f)$.

g completely describes a supp. hyperplane of $\text{epi} f$ at x_0 .

$$\partial f(x_0) := \{g \text{ linear} : f(x) \geq f(x_0) + g(x - x_0) \forall x \in \mathbb{R}^n\}$$

is the *subdifferential* (= set of *subgradients*) of f at x_0 .



Note: We can also see $\partial f(x_0)$ as a set of **points** $\in \mathbb{R}^n$, using a scalar product $\langle \cdot, \cdot \rangle$ of \mathbb{R}^n : By Riesz's Theorem, $\exists \hat{g} \in \mathbb{R}^n : \langle \hat{g}, x \rangle = g(x)$ for all linear $g : \mathbb{R}^n \rightarrow \mathbb{R}$:

$$\partial f(x_0) = \{\hat{g} \in \mathbb{R}^n : f(x) \geq f(x_0) + \langle \hat{g}, x - x_0 \rangle \forall x \in \mathbb{R}^n\}.$$

The subdifferential is rarely empty:

If f is convex, $x \in \text{relint}(\text{dom } f) \Rightarrow \partial f(x) \neq \emptyset$

Let $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ be an LSC convex function,
let $x \in \text{relint}(\text{dom } f)$.

Recall the **affine separation theorem**:

*Let $C \subseteq \mathbb{R}^N$ convex set with $\text{relint}(C) = C \neq \emptyset$
and D affine $C \cap D = \emptyset$. There exists a hyperplane H
of dimension $N - 1$ such that $D \subseteq H$, and $C \subseteq \text{int } H^+$.*

Here $C := \text{relint}(\text{epi } f)$, $D = \{(x, f(x))\}$.

Let $H := \{y \in \mathbb{R}^n \times \mathbb{R} : l(y) = c\}$.

As $C \subseteq \{y \in \mathbb{R}^n \times \mathbb{R} : l(y) < c\}$,

$\text{epi } f \subseteq \text{cl}(C) \subseteq \{y \in \mathbb{R}^n \times \mathbb{R} : l(y) \leq c\}$.

H is thus a supporting hyperplane of $\text{epi } f$ at x .

It is also not vertical, because $x \in \text{relint}(\text{dom } f)$.

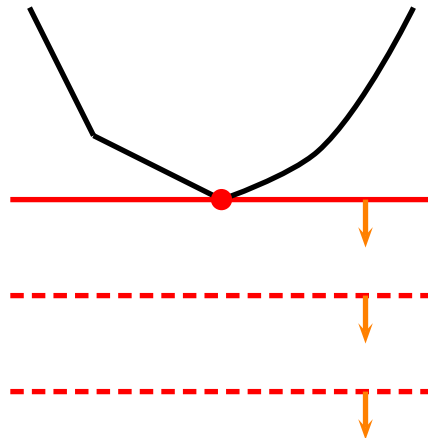
Subdifferential and optimality

Theorem 2 Let $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$
be an LSC convex function.
 $x^* \in \arg \min_{x \in \mathbb{R}^n} f(x)$ **iff** $0 \in \partial f(x^*)$.

Proof: We have:

$$f(y) \geq f(x^*) + \langle 0, y - x^* \rangle = f(x^*)$$

for every $y \in \mathbb{R}^n$ iff $0 \in \partial f(x^*)$.



**Duality and differentiability
are closely related concepts**

Conjugate functions

A very useful related concept: conjugate functions

$$\begin{array}{l} \inf f(x) \\ \text{s.t. } x \succeq_K b \\ x \in \text{dom}(f) \end{array} \geq \begin{array}{l} \sup F(b) \\ \text{s.t. } F(x) \leq f(x) \forall x \in X \\ F \in \mathcal{F} \end{array}$$

(Here $X = \text{dom}(f)$. And $g \equiv \text{Id}$)

Recall that $\mathcal{F} := \{x \mapsto \langle u, x \rangle - u_0 : u \in K^*\}$

almost ensures strong duality

(check convexity and Slater's conditions).

The dual becomes:

$$\begin{array}{l} \sup \langle u, b \rangle - u_0 \\ \text{s.t. } \langle u, x \rangle - u_0 \leq f(x) \forall x \in \text{dom}(f) \\ u \in K^*, u_0 \text{ free} \end{array}$$

A very useful related concept: conjugate functions

$$\begin{array}{ll} \sup & \langle u, b \rangle - u_0 \\ \text{s.t.} & \langle u, x \rangle - u_0 \leq f(x) \quad \forall x \in \text{dom}(f) \\ & u \in K^*, u_0 \text{ free} \end{array}$$

Looking at the constraints: $\langle u, x \rangle - u_0 \leq f(x) \quad \forall x \in \text{dom}(f)$
 $\Leftrightarrow \langle u, x \rangle - f(x) \leq u_0 \quad \forall x \in \text{dom}(f)$

The function $f_*(u) := \sup_{x \in \mathbb{R}^n} \langle u, x \rangle - f(x)$
is the *conjugate of f* . Note that f_* is **LSC and convex**.

$$d^* = \sup_{u \in K^*} \langle u, b \rangle - f_*(u) \leq \inf_{x \succeq_K b} f(x) \leq f(b)$$

Conjugate functions tell you how to package portfolios optimally

We are selling portfolios of d assets, priced p_1, \dots, p_d .
Any random profit/loss goes to the client, but
he must pay a commission for our portfolio management
Let $\xi \in \mathbb{R}^d$ be the portfolio composition
and $f(\xi)$ the commission for managing it.
To minimize our cost:

$$\min_{\xi} p^T \xi - f(\xi) = g(p),$$

where $-g(-p) = (-f)_*(p)$.

How do we determine the optimal ξ^* ?

Conjugates of conjugates

By definition, $f_*(u) = \sup_{x \in \mathbb{R}^n} \langle u, x \rangle - f(x)$

Let $f_{**}(b) := \sup_{u \in \mathbb{R}^m} \langle u, b \rangle - f_*(u)$

$$\boxed{\sup_{u \in \mathbb{R}^m} \langle u, b \rangle - f_*(u)} \leq \boxed{\inf_{x = b} f(x)} = f(b)$$

Theorem 3 *If f is LSC convex, then $f_{**} = f$.*

Proof: When $b \in \text{int dom}(f)$, Slater's condition holds, yielding strong duality: $f_{**}(b) = f(b)$.

Thus $\text{int epi}(f_{**}) = \text{int epi}(f)$. As f_{**} and f are LSC, we get $\text{epi} f_{**} = \text{cl}(\text{int epi}(f_{**})) = \text{cl}(\text{int epi}(f)) = \text{epi} f$, and $f_{**} = f$.

Support functions: the simplest example of conjugate functions

Let $X \subseteq \mathbb{R}^n$ be closed convex. Suppose you have to solve

$$\begin{array}{ll} \sup & \langle u, x \rangle \\ \text{s.t.} & x \in X \end{array}$$

for many u 's. The *support function* of X is

$$\begin{array}{ll} \sigma_X(u) = \sup & \langle u, x \rangle \\ & \text{s.t. } x \in X. \end{array}$$

It is the conjugate of the characteristic function of X :

$$\begin{cases} \chi_X(x) = 0, & x \in X \\ \chi_X(x) = +\infty, & x \notin X. \end{cases}$$

Massively used when easily computable.

Some support functions

- ▶ **Point:** $X = \{x\}$. Then $\sigma_X(u) = \langle u, x \rangle \forall u \in \mathbb{R}^n$.
- ▶ **Unit ball:** $X = \{x : \|x\| \leq 1\}$.
 $\sigma_X(u) = \sup_{\|x\| \leq 1} \langle u, x \rangle =: \|u\|_* \forall u \in \mathbb{R}^n$.
- ▶ **k -simplex:** $X = \text{conv}\{v_0, \dots, v_k\}$.
 $\sigma_X(u) = \sup\{\langle u, \sum_i t_i v_i \rangle : t_i \geq 0, \sum_i t_i = 1\} = \max_i \langle u, v_i \rangle$.
- ▶ **Convex cone:**
 $\sigma_K(u)$ is the characteristic function of $-K^*$.
- ▶ **Half-space:** $X = \{x : \langle a, x \rangle \leq b\}$.
 $\sigma_X(\gamma a) = \gamma b$ for $\gamma \geq 0$, and $\sigma_X(u) = +\infty$ elsewhere.

Support function of subdifferentials

Theorem 4 Let $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ be LSC convex. Let $x \in \text{relint}(\text{dom} f)$. The support function of $\partial f(x)$ is $h : \text{aff}(\text{dom} f) \rightarrow \mathbb{R}$, $d \mapsto \nabla f(x)[d]$.

Proof: We fix $x \in \text{relint}(\text{dom} f)$ and $d \in \text{aff}(\text{dom} f)$. We need to check $h(d) = \sup\{\langle g, d \rangle : g \in \partial f(x)\}$. First, $h(d) \geq \sup\{\langle g, d \rangle : g \in \partial f(x)\}$ as:

$$\forall g \in \partial f(x), \quad h(d) = \lim_{t \downarrow 0} \frac{f(x + td) - f(x)}{t} \geq \lim_{t \downarrow 0} \frac{\langle g, td \rangle}{t} = \langle g, d \rangle.$$

Second, the function h is convex on \mathbb{R}^n , by convexity of f . Thus $\partial h(d) \neq \emptyset$. Let $g_h \in \partial h(d)$ and $v \in \mathbb{R}^n$. Note that for all $\tau > 0$:

$$\tau h(v) = h(\tau v) \geq h(d) + \langle g_h, \tau v - d \rangle \Rightarrow h(v) \geq \langle g_h, v \rangle = h(0) + \langle g_h, v \rangle,$$

by dividing by τ and letting $\tau \rightarrow +\infty$. Hence $g_h \in \partial h(0)$. Also, $\langle g_h, d \rangle \geq h(d)$ by taking $\tau \rightarrow 0$. Since $\mu(t) := (f(x + td) - f(x))/t$ is decreasing on \mathbb{R}_{++} (easy to check from the convexity of f) and $g_h \in \partial h(0)$:

$$f(y) - f(x) \geq \lim_{t \downarrow 0} \frac{f(x + t(y - x)) - f(x)}{t} = h(y - x) \geq \langle g_h, y - x \rangle \quad \forall y \in \text{dom} f.$$

Therefore $g_h \in \partial f(x)$ and $\sup\{\langle g, d \rangle : g \in \partial f(x)\} \geq \langle g_h, d \rangle \geq h(d)$. ■

Subdifferential and differentiability

- ▶ f is differentiable at x iff $\partial f(x) = \{g\}$.

In that case, $g = \nabla f(x)$.

Proof: Assume that $\partial f(x) = \{g\}$.

The support function of $\partial f(x)$ is thus $\langle g, d \rangle = \nabla f(x)[d]$.

As it is a linear function, f is differentiable at x .

Moreover, $g = f'(x)$.

Conversely, if f is differentiable, $\nabla f(x)[d]$ is linear,

i.e. the support function of a single point.

Thus, $\partial f(x)$ is a singleton. ■

There is a deep link between conjugates and subdifferentials

Let $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ be an LSC convex function.
Let $x \in \text{relint}(\text{dom} f)$.

$$\partial f(x) = \{g : f(y) \geq f(x) + \langle g, y - x \rangle \forall y \in \mathbb{R}^n\}$$

$$g \in \partial f(x) \Leftrightarrow \langle g, x \rangle - f(x) \geq \sup_y \langle g, y \rangle - f(y) = f_*(g)$$

But $f_*(g) \geq \langle g, x \rangle - f(x)$; thus

$$g \in \partial f(x) \Leftrightarrow f_*(g) + f(x) = \langle g, x \rangle.$$

By $f_{**} = f$, you also get:

$$x \in \partial f_*(g) \Leftrightarrow f_*(g) + f(x) = \langle g, x \rangle.$$

$$g \in \partial f(x) \Leftrightarrow x \in \partial f_*(g)$$

For next week

- ▶ A crucial consequence of the subgradient theory:
Optimality conditions for constrained problems
(KKT conditions)
- ▶ Applications of duality theory and KKT conditions
in finance and engineering.